**3GPP TSG RAN WG1 Meeting #101-e R1-** **200xxxx**

**e-meeting, 8th June - 11th June 2020**

**Source: Moderator (CATT)**

**Title: Summary of Email Discussion [101-e-Post-NR-Pos-Enh]**

**Agenda item: 8.2**

**Document for: Discussion and Decision**

# Introduction

This document provides a summary of the following email discussion:

🖂[101-e-Post-NR-Pos-Enh] Email discussion/approval prioritizing remaining  evaluation assumptions till 6/17 – Ren Da (CATT)

* Focusing on high priority proposals first, target 6/11 for early approvals
* Followed by medium priority/low priority proposals

This summary covers the follow-up discussion of the following issues (R1-2005049):

* **Proposal 2.1-1: Rel-17 target positioning requirements**
* **Proposal 2.1-2: Metric of positioning accuracy requirements**
* **Proposal 4.1-3: (Optional) UE RX/TX timing error for antenna panel**
* **Proposal 4.1-4: (Optional) hand blockage model in evaluation**
* **Proposal 5.1-3: (Optional) UE mobility model**
* **Proposal 5.1-8: (Optional) Base station spacing**
* **Proposal 6.1-1: Evaluation scenario(s) for commercial use cases**
* **Proposal 8.1-3: Physical layer and higher layer positioning latency**
* **Proposal 8.1-5: Evaluation of UE power consumption**
* **TR 38.857 skeleton**

Please note of the following highlights will be used in this summary:

* The Pink highlights are proposals and issues for discussion with high priority in this email discussion
* The Yellow highlights are proposals and issues for discussion with medium priority in this email discussion
* The Dark Yellow highlights are proposals and issues for discussion with low priority in this email discussion
* The Turquoise highlights are offline consensus/conclusion based on offline discussion or comments

# Proposals for Discussion

Note: See R1-2005049 [1] for the discussions of previous proposals.

### Proposal 2.1-1

FL Comments

In previous discussion, most companies support the Proposal 2.1-1 (Revision #3)[1]. Two companies suggest removing the FFS bullets for Physical layer latency, one company suggest using the same target accuracy as shown in SID, one company suggest adding 1m of Horizontal position accuracy into IIoT use cases, and one company suggest removing 20ms delays as in SID. Given that all of the suggestions of the changes are for either the numbers in brackets or FFS, it might be better for us minimize the effort on the discussion of the proposals at this moment, since we may need to further investigation (e.g., marketing requirements, the evaluation results based on R16 positioning, the potential R17 enhancements, etc.) to decide the reasonable and realistic target positioning performance for Rel-17.

Note: It is worthy to point out that the target positioning performance for Rel-17 shows what we are targeting in R17. It is not defined nor bounded by the simulation results based on Rel-16 positioning technologies. The target positioning performance for Rel-17 will be used for us to identify the gap between the positioning performance based on Rel-16 positioning technologies and what we are targeting to achieve in Rel-17.

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| **Proposals** | **Description** | **Comments** |
| **Proposal 2.1-1** | Revision #4* + In Rel-17 target positioning requirements for **commercial use cases** are defined as follows:
		- * + Horizontal position accuracy (<1 m)
				+ Vertical position accuracy (< [2 or 3] m)
				+ End-to-end latency for position estimation of UE (<[100m]s)
				+ FFS: whether to define target hysical layer latency for position estimation of UE (<[10ms])
	+ In Rel-17 target positioning requirements for **IIoT use cases** are defined as follows:
		- * + Horizontal position accuracy (< X m)

X = [ 0.2 or 0.5]m* + - * + Vertical position accuracy (< Y m)

Y = [0.2 or 1]m* + - * + End-to-end latency for position estimation of UE (<[10ms, 20ms, or 100ms])
				+ FFS: whether to define target physical layer latency for position estimation of UE (<[10ms])
 | CATT: Support Revision #4 with the following values of target positioning requirements:* + In Rel-17 target positioning requirements for **commercial use cases** are defined as follows:
		- * + Horizontal position accuracy (<1 m)
				+ Vertical position accuracy (< 3 m)
				+ End-to-end latency for position estimation of UE (<100ms)
				+ FFS: whether to define target hysical layer latency for position estimation of UE (<[10ms])
	+ In Rel-17 target positioning requirements for **IIoT use cases** are defined as follows:
		- * + Horizontal position accuracy (< X m)

X = 0.2m* + - * + Vertical position accuracy (< Y m)

Y = 1m* + - * + End-to-end latency for position estimation of UE (<100ms)
				+ FFS: whether to define target physical layer latency for position estimation of UE (<[10ms])

OPPO:* Ok to keep the position accuracy open for IIOT use cases.
* We shall add the CDF percentile value for each position accuracy target, otherwise, [x]m accuracy alone does not make sense. Suggest to add 80% for commercial use cases and 90% for IIoT use cases.

Huawei/HiSilicon: OK.vivo：At least，we believe physical layer latency for IIoT is needed if RAN 1 wants to focus on phy latency. Otherwise, RAN1 will spend more time to evaluate the ratio of phy latency. So, we propose to delete “whether to define target”ZTE： From our perspective, different scenarios may have different target requirements. So it’s better to keep the note in the previous version, i.e.Note: Target positioning requirements may not necessarily be reached for all scenarios.Fraunhofer: Agree with ZTENokia/NSB: OK.Qualcomm: OK with Revision #4 as it is. Keep all the numbers in the brackets. There is no need to finalize the target values in this meeting. CATT-v2: As the compromise, we can accept the target requirements with all the numbers in the brackets. However, we prefer to take the scenario into account, i.e. there are different target requirements for InF-SH and InF-DH scenarios. Moreover, we propose the target for InF-DH scenario should aiming to the modified InF-DH scenario with baseline clutter parameters (40%, 2m, 2m) which we had agreed last weekRevision #5* + In Rel-17 target positioning requirements for **commercial use cases** are defined as follows:
		- * + Horizontal position accuracy (<1 m)
				+ Vertical position accuracy (< [2 or 3] m)
				+ End-to-end latency for position estimation of UE (<[100m]s)
				+ FFS: whether to define target hysical layer latency for position estimation of UE (<[10ms])
	+ In Rel-17 target positioning requirements for **IIoT use cases** are defined as follows:
		- * + Horizontal position accuracy (< X m)

X = [ 0.2 or 0.5]m for InF-SH scenarioX = [1]m for InF-DH scenario with baseline clutter parameters { 40%, 2m, 2m}* + - * + Vertical position accuracy (< Y m)

Y = [0.2 or 1]m for InF-SH scenarioY = [3]m for InF-DH scenario with baseline clutter parameters { 40%, 2m, 2m}* + - * + End-to-end latency for position estimation of UE (<[10ms, 20ms, or 100ms])
				+ FFS: whether to define target physical layer latency for position estimation of UE (<[10ms])

LG: We are generally supportive of the revision #4, but we prefer to remove “whether to define target” for physical layer latency.CMCC: So far we are fine with the layout of the proposals, and to leave the target accuracy open. A follow-up comment for CATT’s 2nd reply, no objections to define separate target performance for different IoT scenarios, but as per the last note in the agreement “Note: Target positioning requirements may not necessarily be reached for all scenarios”, does it imply that only one target performance is defined for all InF scenarios?Lenovo, Motorola Mobility: Support Revision #4 but also prefer to remove the “whether to define target” statement. Since physical layer latency is an important component in the overall end-to-end latency analysis/evaluation in Rel-17, we feel that it is not a question of “whether to define target physical layer latency” but rather to study the feasibility of achieving the physical layer latency targets in the context of the overall end-to-end latency requirements. CATT-v3: Agree with CMCC that maybe only one target performance is enough, as there is a note “Note: Target positioning requirements may not necessarily be reached for all scenarios” in the agreement. What we worried about is that the LOS probability of InF-DH scenario is much less than InF-SH scenario, so it will be better for InF-DH scenario to have relaxed target performance. In addition, there is another note “Note: Target performance and performance gap identification will be discussed separately” in the agreement, therefore, it may be better to set different target performances for InF-SH and InF-DH.Intel: OK with proposed revision. |

### Proposal 2.1-2

FL Comments

In previous discussion, most companies support the Proposal 2.1-2 (Revision #2) [1] in principle with the suggestion of changing “availability of [90%]” either to “[90%] of CDF values” or “[90%] of UEs”, which is used in TR 38.855 in Rel-16. Thus, it might be better to follow TR 38.855 to use “[90%] of UEs”.

One company asks what happens if the target positioning accuracy can only be achieved at a percentile lower than [90%]. To address the question, our understanding is that one of the main purposes of the simulation evaluation is to identify the gap between the positioning performance based on Rel-16 positioning technologies, which are currently used for simulation evaluation, and the target positioning performance defined for Rel-17. In another word, the target positioning performance requirements in R17, including the percentile of CDF values, are not bounded by the simulation results. We may expect reasonably a gap between the evaluation results based on Rel-16 positioning technologies and the target positioning accuracy for Rel-17.

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| **Proposals** | **Description** | **Comments** |
| **Proposal 2.1-2** | Revision #3* The target horizontal and vertical positioning accuracy requirements are defined based on [90%] of UEs.
 | CATT: Support.OPPO: 90% for IIoT use cases and 80% for common commercial use cases.Huawei/HiSilicon: OK.vivo: SupportZTE: OK.Fraunhofer: OkNokia/NSB: Support. Qualcomm: Thanks for the clarification by FL. Considering the main purpose is to identify the performance gap between Rel-16 technology and Rel-17 target, we are ok with Revision #3 as long as the target percentile is set without compromising the Rel-17 target accuracy stated in SI (i.e. do not relax the accuracy for (I)IOT use cases to 0.5m). Regarding the target percentile, we believe there is no need to conclude on the value in this meeting, meaning we can leave the brackets there in Revision #3. Also, we share similar view with OPPO on keeping different percentiles for IIOT and commercial use cases, which can be added to the proposal as FFS in a subbullet. LG: OKCMCC: Support.Lenovo, Motorola Mobility: Supportive of Revision#3.Intel: OK |

### Proposal 4.1-3

FL Comments

In previous discussion, it seems most companies are in favour of the option to model The UE/gNB RX-TX timing error. Near the end of the meeting, there was a discussion of the revision proposed by the proponents. Interested companies are welcome to present their views on the revision.

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| **Proposals** | **Description** | **Comments** |
| **Proposal 2.1-2** | Revision #1(Optional)The UE/gNB RX-TX timing error, in FR1/FR2, can be modelled as a truncated Gaussian distribution of (T1 ns) rms values, subject to a largest timing difference of T2 ns, where T2 = 2\*T1* That is, the range of timing errors is [-T2, T2]
* T1: [2] ns for gNB and [8] ns for UE (realistic Rx-Tx calibration)
* Note: RX-TX timing errors are generated per panel
 | CATT: Support. We are fine with including FR1 case for modelling of RX-TX timing error in the Revision #1.OPPO: supportHuawei/HiSilicon:* Just would like to clarify the following, when we agreeing with this, whether it means that DL-TDOA and UL-TDOA are going to suffer from additional [1.4]ns of Tx chain (DL-TDOA) or Rx chain (UL-TDOA) group delay error or not?

ZTE: Agree. Fraunhofer: OKNokia/NSB: Okay. Qualcomm: Support Revision #1. The proposed Rx-TX timing error modeling is applicable for DL+UL positioning (m-RTT). For TDOA, the performance is mainly affected by network synchronization error, where the group delay error can be omitted in the modeling. Huawei/HiSilicon: To our understanding, if there is unresolved random group delay (i.i.d. across gNB panel) for Rx – Tx time difference, it should also be reflected in DL-TDOA and UL-TDOA, even if those gNBs shares the same clock source. Basically it is our understanding that each gNB should calibrate the group delay with a very small residual error, which will affect both gNB Rx – Tx time difference and TDOA-based positioning methods. For UE side, we think the common residue group delay will be cancelled for TDOA measurements.So here is our suggestion:(Optional)The UE/gNB RX and TX timing error, in FR1/FR2, can be modelled as a truncated Gaussian distribution of (T1 ns) rms values, subject to a largest timing difference of T2 ns, where T2 = 2\*T1* That is, the range of timing errors is [-T2, T2]
* T1: [1.4] ns for gNB and [5.6] ns for UE (realistic Rx-Tx calibration)
* Note: RX-TX timing errors are generated per panel

Intel: Suppor the revision. |

### Proposal 4.1-4

FL Comments

In previous discussion, the number of companies (4) that are supportive to the Proposal 4.1-4 [1] is fewer than the number of companies (6) that do not support it. The proponents of the Proposal 4.1-4 suggested to explicitly state in the TR that 'Hand blockage aspects were not taken into account in the study item phase.' Given that TR 38.901 does not define hand blockage model, and it is obvious the SI may not be consider all practical issues, it may not be necessary to have the statement in TR. But, this issue can be discussed when we prepare the TR.

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| **Proposals** | **Description** | **Comments** |
| **Proposal 4.1-4** | • (Optional) In FR2, a loss of 10 dB can be applied for a randomly chosen blocked panel to model hand blockage  | FL suggestion: no further discussion on the proposal in this meeting. CATT: Support FL suggestion that no further discussion this proposal.OPPO: Agree with the FL suggestion. We do not see need for this proposal vivo: Agree with FL suggestionZTE: Support the FL suggestion.Fraunhofer: Agree with the FL suggestionNokia/NSB: Support FL suggestion.Qualcomm: Support the FT suggestion. LG: Support FL suggestionLenovo, Motorola Mobility: Agree with FL’s suggestion.Intel: Agree with FL suggestion. |

### Proposal 5.1-3

FL Comments

In previous discussion, it seems most companies are supportive to the Proposal 5.1-3 (Revision #2)[1]. Four companies prefer to have the common model, and one company suggests let each company to choose their own model. In the revision#3, we include the common model proposed in previous email discussion for further comments.

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| **Proposals** | **Description** | **Comments** |
| **Proposal 5.1-3** | Revision #3* (Optional) UE mobility can be considered in evaluation with the consideration of the spatial consistency procedure defined in TR 38.901.
* Individual companies are encouraged to consider using the following mobility model:
	+ Track mode: linear track
	+ Velocity & acceleration (velocity acceleration values decided by companies)
		- Option 1: constant speed [30km/h], zero acceleration.
		- Option 2: initial constant acceleration period + constant speed period
	+ Position update rate: describes the time when the position of a track is updates >1ms (values decided by companies)
	+ Direction: describes the travel direction along the track. The direction is a random value if either 0, pi/2 and -pi/2 in rad.
	+ Additional assumptions:
		- Spatial Consistency according to TR 38.901 (Section 7.6.3)
* Note1: UE dropping procedure in Table 5-1 applies
* Note 2: For InF UE positions not within the Hall are not considered for evaluation
 | CATT: We prefer to have the common model. We are generally fine with the proposed common model in the left column. And a fixed path trajectory maybe need to be agreed in order to facilite the convergence of simulation results. That is to say, interested companies use the same path trajectory to model the movement of UE.Our proposed change to the Revision #2 as follows,* + Track mode: linear track with fixed path trajectory.

OPPO: Wording change suggestion: * Individual companies ~~are encouraged to~~ may consider using the following mobility model as starting point:

Huawei/HiSilicon:* This is too much for a single meeting. Suggest to consider in the next meeting. For example, it is unclear
* how linear track can have this random bearing {0, pi/2, -pi/2}, and why there is no pi;
* how to model the displacement error between two positioning measurements;
* how to evaluate the positioning error (real time or long term);
* how LOS condition is changed throughout the track.
* what Table 5-1 is.
* what the usage of Note 2 especially considering when we have fixed trajectory.

vivo: we think the detailed model only can be a start point rather than agreement.Furthermore, for detailed mobility model, maybe also needs an error model of the velocity, acceleration, relative time, etc. And we also have a question about the position update rate, we want to know what information will be updated and how to update. In our platform, all of UE is fixed position and fixed velocity, So which one is your mean* Update the velocity & acceleration with time for one fixed UE
* there is a list UE with a fixed position and Velocity & acceleration，but Velocity & acceleration of different UE is different according to the  Position or position update rate

ZTE: Agree with OPPO since it’s an optional feature. Our suggestion is we only keep the first bullet, it’s up to interested companies to elaborate other details.Fraunhofer: we support to have an common model for mobility. Since the proposal changed to a fixed trajectory, I assume the direction [0, pi/2 pi, -pi/2] and Notes 1 (Table 5-1 in the last FL summary referred to the normal dropping procedure) and Note2 are no longer needed (as indicated by HW).One comparable example can be found in TR36.855 (A.1.2): for simplicity the current proposal did not include turn probabilities to keep things simple (go straight track). On the other comments:* The LOS condition changes according to LOS/NLOS probability and spatial consistency procedure in 38.901.
* A UE position on the track can correspond to an SRS transmission or an PRS reception and this determines the “UE-position update rate” or the UE fixes on the track. I think it should be fine as a starting point to apply constant speed (we are also fine with option2).
* The evaluation of the UE position on a track is a different discussion not directly related with the mobility model itself. We support to evaluate the number of occasions on a track per positioning estimate to have a direct comparison with the baseline approach.

 Nokia/NSB: Agree with Huawei. Too complex for a short post meeting email discussion. Companies wanting to do mobility modeling can do it over the summer and then bring detailed papers. No need to agree this now. Qualcomm: It does not seem we have time to agree on the details. However, we can try to reach an agreement to cover at least the following: Linear track Spatial consistency according to TR38.901 If the reduced list cannot be agreed upon, we are ok with keeping only the first bullet.LG: We understand this could be considered as a meaningful work, but we it is difficult to agree the details regarding mobility model, so we prefer to agree with only the first bullet and to leave it up to each company for evaluation.Lenovo, Motorola Mobility: We also agree that the mobility model parameters may be too detailed to converge at this stage of the Post RAN1#101-e meeting email discussion. However, a common mobility model with a fixed linear trajectory could be a reasonable and basic starting point for further discussions.Intel: For NR Positioning evaluations RAN1 hasn’t had sufficient time for analysis of mobility model details. Current proposal seems incomplete, as also commented by other companies we prefer to postpone the discussion and we do not support the revised proposal right now. |

### Proposal 5.1-8

FL Comments

In previous discussion, seven companies are supportive to the Proposal 5.1-8[1], but three companies don’t support. Suggest having a further discussion to have further understanding of the motivation as well as the concerns.

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| **Proposals** | **Description** | **Comments** |
| **Proposal 5.1-8** | * (Optional) Base station spacing of D=10m can be considered for BS layout in small hall (L=120m x W=60m).
 | CATT: Support this proposal and we are fine for it to be optional.OPPO: do not see need for this proposal. So not support it.Huawei/HiSilicon: Too many base stations (5x11=55). Suggest postponing.vivo: No needed, considering the costing and the LOS probability have been modified to ensure 95% UE has more than 4 LOS path.ZTE: Support. It may be useful to investigate DL PRS interference, NLOS identification and so on. Fraunhofer: Ok.Nokia/NSB: Support. As mentioned previously the additional base stations could be positioning only TP or RP which address the cost consideration. We think achieving the performance needed in Rel-17 should consider this type of deployment.Qualcomm: We don’t think it is necessary but can go with the majority if most companies want to include D=10m in small hall as optional. CMCC: We have no strong views to support or object this proposal. Just for notification, even by defining a smaller value of the BS spacing can provide a better performance, we may not be able to deploy such a dense base station spacing in reality due to the cost.Intel: Considering comment from CMCC, we don’t see strong motivation for this scenario. Ok as an optional scenario if majority wants to have it |

### Proposal 6.1-1

FL Comments

Five companies prefer Proposal 6.1-1 (Revision #3)[1], three companies do not see the need for the proposal, while one company prefer Revision #2. Even if we do not define the baseline scenario for the evaluation of the positioning enhancements for commercial use cases, it may still be useful to have a conclusion that no baseline scenario is defined. In addition, it might be better to exclude the scenarios that no company is interested in.

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| **Proposals** | **Description** | **Comments** |
| **Proposal 5.1-8** | Revision #4* In Rel-17 SI for the evaluation of the positioning enhancements for commercial use cases, no baseline scenario is defined. [UMi, UMa, IOO] scenario(s) defined in TR 38.855 can be considered as optional scenarios.
 | FL: Interested companies are encoraged propose the scenario(s) they may evaluate. We may exclude the scenario that no company is interested in. CATT: we prefer to adopt IOO scenario defined in TR38.855 as optional scenario for commercial use cases evaluations.OPPO: Ok to be optional and ok to not define baseline. Suggest to model absolute time of arrival in the evaluation, especially for IOO scenarios. Huawei/HiSilicon: IOO most likely.We would like to also clarify the understanding of evaluating general enhancement is to introduce NLOS propagation delay compared Rel-16 evaluation or not. If so, it is unclear how NLOS delay is modelled for IOO as it was not considered for IIoT channel model SI.vivo:Agree with Huawei and we worried UMa can reach the Target, whether we add the note for the proposal like before * + Note: Target positioning requirements may not necessarily be reached for all scenarios.

ZTE: We don’t see the intention of this proposal since we have evaluated the UMi, IOO and UMa during the Rel-16 study phase. Fraunhofer: Support.Nokia/NSB: Support. If we have no baseline scenario how are we supposed to know if we meet the target? Qualcomm: We should not spend time on debating which Rel-16 scenarios to be included/excluded considering they are already listed as optional. We are ok with VIVO’s proposal on the note that target positioning requirements may not necessarily be reached for all scenarios. Also, we agree with OPPO/Huawei that the applicability of absolute time of arrival model for non-InF channels must be clarified. Currently, the parameters for absolute time of arrival model are only specified for InF-SL/SH/DL/DH in TR38.901. The discussion on the parameters to use for UMi/UMa/IOO can take place in the next meeting. CATT-v2: For absolute time of arrival model for IOO model, as IOO layout has 12BSs per 120m x 50m, Inter-gNB distance= 20m, then IOO has similar hall size and ISD as InF scenarios and it could therefore be reasonable to reuse the same parameters of the absolute time of arrival model for the InF model in Table 7.6.9-1 in 38.901 as follows, as least the following values of parameters for InF can be start point of the modelling of NLOS excess delay for IOO scenario,

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| Scenarios | InF-SL, InF-DL | InF-SH, InF-DH |
| $$lgΔτ=log\_{10}\left({Δτ}/{1s}\right)$$ | $$μ\_{lgΔτ}$$ | -7.5 | -7.5 |
|  | $$σ\_{lgΔτ}$$ | 0.4 | 0.4 |
| Correlation distance in the horizontal plane [m] | 6 | 11 |

LG: Support and we are fine with leaving a note suggested from Vivo.Lenovo. Motorola Mobility: Support Revision #4, with Vivo’s noteCATT-v3: As suggested by vivo, I am fine to delete the last row in the table as we don’t need consider correlation distance when modeling absolute time of arrival model. Maybe we can reuse the same parameters of the absolute time of arrival model of InF scenario as that of IOO scenario, as shown in the table below:

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| Scenarios | InF-SL, InF-DLInF-SH, InF-DH | IOO |
| $$lgΔτ=log\_{10}\left({Δτ}/{1s}\right)$$ | $$μ\_{lgΔτ}$$ | -7.5 | -7.5 |
| $$σ\_{lgΔτ}$$ | 0.4 | 0.4 |

Intel: Support. Suggest to modify last sentence as follows: scenario(s) defined in TR 38.855 can be considered as optional scenarios without modifications. |

### Proposal 8.1-3

FL Comments

In previous discussion, all companies are supportive to the main bullet of the Proposal 8.1-3 (Revision #3) [1]. One company made a comment to reword of the note, saying RAN1’s discussion will only focus on physical layer latency. Given that the main bullet says “Both Physical layer and higher layer positioning latency can be evaluated”, it would not better to remove “only”, but “RAN1 discussions focus on physical layer latency”, which we assume is the common understanding anyway.

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| **Proposals** | **Description** | **Comments** |
| **Proposal 8.1.-3** | Revision #4* Both Physical layer and higher layer positioning latency can be evaluated through analysis and, optionally, numerical evaluation.
	+ Note: RAN1 discussions focus on physical layer latency.
	+ Note: RAN2 may need to be involved for higher layer latency analysis
 | CATT: Support.OPPO: OkHuawei/HiSilicon: OK.vivo:SupportZTE: OK.Fraunhofer: SupportNokia/NSB: Support. Qualcomm: With regards to the additional first Note: We don’t see the need to be so definite that RAN1 cannot have views on high layer signaling. This is a RAN1-led SI, and we need to think about the overall latency reduction. Even if RAN1 reduces the triggering/processing/reporting to a few msec, if the high layer latency is 100+ msec, then the targets would not be met. At this point, the discussion needs to stay generic and after the conclusions are written of the SI, during the WID discussions, delegation of topics to each WG can happen more effectively (e.g. RAN2 work on high layer enhancements to achieve low latency and RAN1 to work on physical layer enhancements to achieve low latency).LG: Support.Lenovo, Motorola Mobility: Generally supportive of Revision#4, but we also share Qualcomm’s view about the first Note, in not excluding RAN1’s understanding of the overall positioning impacts to latency and this can be achieved with close co-coordination with other WGs, e,g. RAN2.Intel: OK |

### Proposal 8.1-5

FL Comments

Most companies are supportive to the proposal 8.1-5 Revision #3 [1], while one company suggests emphasizing the evaluation of UE power consumption is optional, which is actually clearly covered in Revision #3. The comment also suggests using the model developed in TR 38.840 as baseline model for the evaluation. But, TR 38.840 actually does not define the UE power consumption model for DL PRS processing and UL SRS for positioning. Thus, it would be better to simply suggest interested companies to use the UE power consumption models in TR 38.840 as the starting points to define the UE power consumption model suitable for NR positioning, but not spend the time to discuss the common model in this SI.

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| **Proposals** | **Description** | **Comments** |
| **Proposal 8.1.-5** | Revision #4* UE power consumption for NR positioning can be evaluated in the SI.
* Note: It is up to each company on how to evaluate the power consumption for positioning. The UE power consumption models developed in TR38.840 can be used as the starting point for defining the UE power consumption model for the evaluation for NR positioning.
 | CATT: Support.OPPO: okHuawei/HiSilicon: OK.vivo:SupportZTE: OK.Fraunhofer: SupportNokia/NSB: Support but the last sentence of the note seems not needed. If it is up to individual companies then they can do what they like.Qualcomm: OK. LG: Support, but we have not discussed if the UE power consumption models in TR 38.840 is applicable to PRS measurement and PRS processing, so we suggest to remove the last sentence, or we have a modified suggestion for this sentence. “The UE power consumption models developed in TR38.840 can be ~~used~~considered as the starting point for defining the UE power consumption model for the evaluation for NR positioning.”Lenovo, Motorola Mobility: Support.Intel: OK |

# TR skeleton for TR 38.857

The skeleton for TR 38.857 [2] was discussed in the meeting [1]. Based on the comments, an update version is provided in the draft folder “[R1-20NNNN skeleton for TR38857 v001.docx](https://www.3gpp.org/ftp/tsg_ran/WG1_RL1/TSGR1_101-e/Inbox/drafts/8.2%20Study%20on%20NR%20Positioning%20Enhancements/R1-20NNNN%20skeleton%20for%20TR38857%20v001_ericsson.docx)” by TR Rapporteur. Interested companies are encouraged to provide further comments to the revised TR skeleton.

Comments

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| **Company** | **Comments**  |
| Huawei/HiSilicon | According to SID1b. Evaluate the achievable positioning accuracy and latency with the Rel-16 positioning solutions in (I)IoT scenarios and identify any performance gaps. [RAN1] The section 8.1 should be limited to IIoT cases. Suggest to change it to “Performance analysis of Rel-16 positioning solutions for IIoT use case” |
| vivo | For the 1b Evaluate the achievable positioning accuracy and latency with the Rel-16 positioning solutions in (I)IoT scenarios and identify any performance gaps. [RAN1] We think may include IoT, it better for (I)IoT scenarios. |
| Nokia/NSB | To Huawei and vivo: From SID 1a. Define additional scenarios (e.g. (I)IoT) based on TR 38.901 to evaluate the performance for the use cases (e.g. (I)IoT).We don’t think it is right to limit Section 8.1 to IIoT at this stage. (I)IoT is given as one example but the justification section of the SID and the main bullet of objective one are clear that general commercial use cases are included. We can discuss later in the SI what is included in section 8.1 or not.  |
| Huawei/HiSilicon | From the reading, objective 1b was cited under section 8.1, which means that section 8.1 serves for objective 1b. If general commercial requirement is important, we suggest Nokia to propose another section in the TR.To us, a dedicated section for the explicit objective 1b is important, which should be one of the main target of the SI. |

# Summary of Proposals

TBD

References

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