

## ***TSGR1#14 R1-00-0959***

Meeting #14, Oulu, Finland, 03-07 July 2000

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<b>Source:</b>	<b>Editor</b>
<b>Title:</b>	<b>TR 25.928, 1.28Mcps functionality for UTRA TDD Physical Layer</b>
<b>Document for:</b>	<b>Approval</b>
<b>Agenda Item:</b>	<b>WG1 Plenary</b>

# 3G TR 25.928 V1.0.1 (2000-07)

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*Technical Report*

**3<sup>rd</sup> Generation Partnership Project (3GPP);  
Technical Specification Group (TSG);  
Radio Access Network (RAN);  
1.28Mcps functionality for UTRA TDD Physical Layer**

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Reference

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DTS/TSGR-0125223 (25223-300.PDF)

Keywords

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<keyword[, keyword]>

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## Foreword

This Technical Report has been produced by the 3GPP.

The contents of the present document are subject to continuing work within the TSG and may change following formal TSG approval. Should the TSG modify the contents of this TS, it will be re-released by the TSG with an identifying change of release date and an increase in version number as follows:

Version 3.y.z

where:

- x the first digit:
  - 1 presented to TSG for information;
  - 2 presented to TSG for approval;
  - 3 Indicates TSG approved document under change control.
- y the second digit is incremented for all changes of substance, i.e. technical enhancements, corrections, updates, etc.
- z the third digit is incremented when editorial only changes have been incorporated in the specification.

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## 1 Scope

This Technical Report describes the 1.28Mcps functionality for UTRA TDD physical layer, identifies commonalities and explains the differences to the 3.84Mcps chip rate. Suggestions for alignment will be provided too.

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## 2 References

The following documents contain provisions which, through reference in this text, constitute provisions of the present document.

- References are either specific (identified by date of publication, edition number, version number, etc.) or non-specific.
- For a specific reference, subsequent revisions do not apply.
- For a non-specific reference, the latest version applies.

- [1] TS 25.201: "Physical Layer - General Description"
- [2] TS 25.221: "Physical channels and mapping of transport channels onto physical channels (TDD)"
- [3] TS 25.222: "Multiplexing and channel coding (TDD)"
- [4] TS 25.223: "Spreading and modulation (TDD)"
- [5] TS 25.224: "Physical layer procedures (TDD)"
- [6] TS 25.225: "Physical layer – Measurements (TDD)"

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## 3 Abbreviations

For the purposes of the present document, the following abbreviations apply:

CDMA	Code Division Multiple Access
PN	Pseudo Noise
QPSK	Quadrature Phase Shift Keying
RACH	Random Access Channel

## 4 Radio Requirements

### 4.1 Radio environments

The radio environment recommended by ITU like indoor environment, pedestrian environment, vehicular environment (120km/h) should be well supported by the low chip rate TDD option.

### 4.2 Services

As one option of TDD mode, the low chip rate option should provide the basic service (bearer service). For a IMT-2000 compliant system corresponding to ITU requirement, for the indoor environment, up to 2Mbps data service should be provided. And for outdoor pedestrian environment, the data service should be up to 384kbps and more. For the UE in moving environment (vehicular speed less than 120km/h), the data rate supported should be 384 and more kbps.

### 4.3 Operational requirements

The low chip rate TDD option should provide the flexibility to be used for high spot or high density area to provide high speed data service or to provide enhanced coverage or be used alone as macro cell to provide the service coverage. It should allow deployment together with FDD system, with high chip rate TDD system, and be similar as high chip rate TDD deploying with GSM.

#### 4.1.14.3.1 Deployment scenarios

For the low chip rate TDD option, the deployment should be flexible for all the scenarios like macro cell, micro cell and pico cell, etc. and also should provide the fixed wireless access.

[Description:]

For the low chip rate TDD option, the deployment should be flexible for all the scenarios like macro cell, micro cell and pico cell, etc. and also should provide the fixed wireless access.

Dependent on the kind of interference accepted by the operator, the operator can vary the max. cell radius in a trade-off with UL - DL interference with the following limitations:

*Table: Interference scenarios and the corresponding max. cell radius*

Case	Max. cell radius
no UpPTS – DwPTS interference allowed	11.25 km
UpPTS – DwPTS interference allowed, but no interference to TS0 allowed	22.5 km
no TS1 – DwPTS interference allowed, other interference allowed	30 km
TS1 – DwPTS interference allowed, but no interference to TS0 allowed	41.25 km

[Rational:]

The guard period of 75 s between the DwPTS and the UpPTS is designed to avoid interference between the UpPTS (UL) and the DwPTS (DL). Therefore the cell size ensuring the interference free reception of the DwPTS is guaranteed to a size of approximately 10 km in radius (exact value 11.25 km, assuming no delay spread).

Consequently, for bigger cell radii there is a conflict that the advanced UpPTS interfering the DwPTS reception of another UE being close by.

Even though the UpPTS – DwPTS interference is possible for bigger cell radii then 11.25 km, the impact on the quality of service can be low and acceptable for an operator willing to operate bigger cells.

There are three reasons for that:

The probability that the a UE is close to another UE is low - especially for big cells

The DwPTS needs not to be received by every mobile in every frame. A few DwPTSs being not received during initial cell search mean no big degradation.

The UpPTS is not transmitted every frame it is only needed for random access or handover. So the probability of disturbance is rather low.

It is recommended that the operator avoids interference of TS1 to TS0 by means of the choice of the cell radius. This interference would mean permanent interference for TS0.

The operators can judge the trade-off between quality of service and range and select the range accordingly.

The maximum cell radius  $d_{max}$  is dependent on the time  $t_{gap}$  between the potentially interfering UL signal and the potentially interfered DL signal by to following equation:

$$d_{max} = \frac{c t_{gap}}{2}; c \text{ is velocity of light.}$$

The following table shows the possible trade-offs between cell radius and interference:

*Allowed cell radius for the occurrence of the special UL - DL interference*

Potentially interfering UL signal	Potentially interfered DL signal	$t_{gap}$ in s	$d_{max}$ in km
UpPTS	DwPTS	75	11.25
UpPTS	TS0	150	22.5
TS1	DwPTS	200	30
TS1	TS0	275	41.25

[Explanation difference:]

For the high chip rate option there is no DwPTS – guard – UpPTS structure. Here, the UL time slots are following the DL time slots immediately. Thus, there is only one step in degree and quality of interference between DL and UL signals.

For the low chip rate option, it makes a difference in quality and degree whether the DwPTS or TS is interfered by the UpPTS or TS1. Hence the trade-off between cell range and interference is more manifold for the low chip rate option.

## 4.4 Handover and Cell selection/reselection

The low chip rate TDD option should support the handover between UTRA modes (e.g, low chip rate TDD to high chip rate TDD, low chip rate TDD to FDD), and between systems (e.g. low chip rate TDD to GSM, etc.).

## 4.5 Particular characteristics of the low chip rate TDD

The features of uplink synchronization, smart antenna (beam forming) etc. have been discussed. These features were agreed to be included in this technical report as they may provide potential performance improvement.

## 5 High level characteristics

Parameter/Feature	Value/Expression	Note
Chip rate	1.28 Mcps	
Modulation	QPSK (8PSK)	
Spreading Factor	1/2/4/8/16	
Nominal Channel Spacing	1.6MHz / Carrier	
Burst Format	1 burst type	
Radio Frame Length	10ms (divided into 2 sub-frames)	
Sub-frame length	5ms	
Time slot number (traffic)	7	
Time slot length (us)	675	
Downlink pilot slot (us)	75	DwPTS
Uplink pilot slot (us)	125	UpPTS
Guard Period (us)	75	GP After DwPTS
Range of uplink slot	1 – 6	
Range of downlink slot	1 – 6	
Receiver type	Multi-user Detection (option), Rake	
Pilot aided detection	DwPTS, UpPTS, Midamble	
Synchronization aspect	Downlink and uplink synchronization	
Precision for UL sync.	1/8 chip	
Antenna processing	Smart antenna with beam forming	Option
Switching point	Two switching points / sub-frame	
Power control / rate	Open loop power control Closed loop power control / 200Hz (max rate)	
Variable bit rate service	Supported (using TFCl)	
Basic resource unit	One code, one slot with Spreading factor =16 (use of same resource in both consecutive sub-frames)	
Service mapping	Multi-code, multi-slot combination (variable spreading factor)	
Interleaving period	10/20/40/80ms	
HO capability	Low chip rate TDD to High chip rate TDD, FDD, GSM, etc.	



Tx Diversity	same capability as high chip rate TDD for DwPTS,DPCH, but not for P-CCPCH; the TxDiversity scheme used for the DPCH is used for the FPACH, as well.	Refer to sub clause 10.5 of TR
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## 6 Physical layer - General description

### 6.1 General description of Layer 1

Common with the high chip rate TDD mode

#### 6.1.2 Service provided to higher layers

The physical layer offers data transport services to higher layers. The access to these services is through the use of transport channels via the MAC sub-layer. In addition to the functions listed in TS25.201, the physical layer for the low chip rate TDD option is expected to perform the following functions in order to provide the data transport service:

- beamforming
- synchronisation shift control

### 4.26.2 Document structure of the physical layer specification

#### 6.2.1 Multiple Access

In contrast to the high chip rate TDD option, the access scheme is Direct-Sequence Code Division Multiple Access (DS-SS) with information spread over approximately 1.6 MHz bandwidth only, thus also often denoted as low chip rate TDD option due that nature.

The frame structure of the low chip rate options differs from the high chip rate option in the following way: A 10 ms radio frame is divided into 2 sub-frames of 5ms. The frame structure (e.g. switching points) for each sub-frame in the 10ms frame length is the same. The sub-frame is divided into 7 traffic slots (864 chip/slot at the chip rate 1.28 Mcps) as described in subclause 7.2.1 'Frame Structure' and 3 timeslots with special functionality.

The information rate of the channel is different from the high chip rate option and varies with the symbol rate being derived from the 1.28 Mcps chip rate, the spreading factor and the modulation mode.

#### 6.2.2 Channel coding and interleaving

Common with the high chip rate TDD mode

#### 6.2.3 Modulation and spreading

The ordinary modulation scheme is QPSK, as for the the high chip rate option. In addition to that 8PSK is also possible.

For separating different cells the following solutions are additionally supported in the low chip rate option:

- SYNC sequences, SYNC1 sequences.

For separating different UEs the following code families are additionally defined:

- SYNC1 sequences

## 6.2.4 Physical layer procedures

There are several physical layer procedures involved with low chip rate TDD operation that are different and in addition to the high chip rate option. Such procedures covered by physical layer description are:

- 1) The power control, for low chip rate TDD mode close loop control in both uplink and downlink.
- 2) Cell search operation.
- 3) Uplink synchronisation for low chip rate TDD mode.
- 4) Random access
- 5) Beamforming (optional)

## 6.2.5 Physical layer measurements

Common with the high chip rate TDD mode

[Explanation difference to section 6]

Most of the physical characters of the low chip rate TDD option are same as the high chip rate TDD option. But due to the different operation frequency band width and some other different implementation consideration such as power control method, uplink synchronization, there still exist some difference and all these differences will be discussed in the main part of TR25.928.

## 7 Physical channels and mapping of transport channels onto physical channels

### 7.1 Transport channels

#### 7.1.1 Transport channels

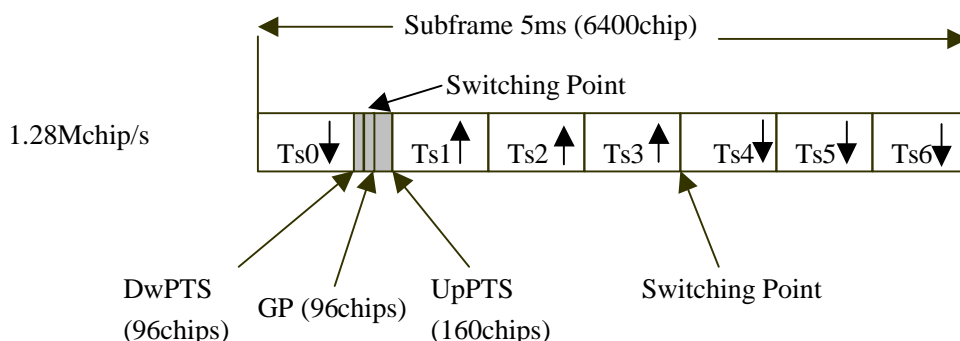
'Common with the high chip rate TDD mode'

### 7.2 Physical channels

#### 7.2.1 Frame structure

[Description:]

For low chip rate option, the frame length is 10ms and the 10ms frame is divided into 2 sub-frames of 5ms. The frame structure for each sub-frame in the 10ms frame length is the same.



The frame structure for each sub-frame is shown in Figure above.

*Figure Structure of the sub-frame for low chip rate option*

Tsn (n from 0 to 6): the nth normal time slot, 864 chips duration;

DwPTS: downlink pilot time slot, 96 chips duration;

UpPTS: uplink pilot time slot, 160 chips duration;

GP: main guard period for TDD operation, 96 chips duration;

[Rationale:]

In the figure above, the total number of normal traffic time slot for uplink and downlink is 7, and the length for each normal time slot is 864 chips duration. Among the 7 normal traffic time slot, Ts0 is always allocated as downlink while Ts1 is always allocated as uplink. The time slots for the uplink and the downlink

are separated by a switching point. Between the downlink time slots and uplink time slots, the special period is the switching point to separate the uplink and downlink. In each sub-frame of 5ms for low chip rate option, there are two switching points (uplink to downlink and vice versa). The proposed frame structure has taken some new technologies into consideration, either the smart antenna (beam forming) technology or the uplink synchronisation will be well supported.

Using the above frame structure, the low chip rate TDD option can operate on both symmetric and asymmetric mode by properly configuring the number of downlink and uplink time slots; (note that whatever the time slot configuration will be, the GP and DwPTS position within the frame should not change in order not to desynchronise the UEs and in order to allow Node B on air synchronisation procedures which make use of the DwPTS channel!) . It should be noted that in asymmetric operation mode, at least one normal uplink time slot and one downlink time slot will be allocated for traffic (Ts0 for downlink and Ts1 for uplink). The guard period GP of 96 chips can support the cell radius of up to about 11 km for uplink synchronization operation where the uplink transmission is advanced in macro-, micro- and pico- cell of small cells in cities or large cells in rural areas. Here the GP insures that an UE transmitting the UpPTS does not disturb the reception of the DwPTS for other UEs being close by. If this distortion is accepted in the network the cell radius can be bigger. (Note that the UpPTS is not continuously transmitted and the DwPTS is not continuously received.)

The only difference to the last version of the frame structure proposal for low chip rate is the improving of the numbering of the time slots. The physical layer behaviour does not change.

[Explanation of difference:]

For both high chip rate option and low chip rate option, the frame length is 10 ms , But for low chip rate option the 10 ms length is divided into 2 sub-frame of 5 ms to allow the fast update of power control, uplink synchronization, and smart antenna beamforming.

For high chip rate option , each 10 ms frame consists of 15 time slots, each allocated to either the uplink or the downlink . So it has both single and multiple-switching point configuration both for symmetric and asymmetric allocation. While in the low chip rate option, the position of the big Guard Period GP and of the DwPTS and UpPTS physical channels, is always between Ts0 and Ts1 whatever the level of asymmetry be.

## 7.2.2 Dedicated physical channel (DPCH)

### 7.2.2.1 Spreading

'Common with the high chip rate TDD mode'

### 7.2.2.2 Burst Types

[Description:]

In correspondence to the frame structure described above, the burst structures for Tsn, DwPTS and UpPTS are proposed. The burst structure for normal time slot (Tsn) is described in Figure below.

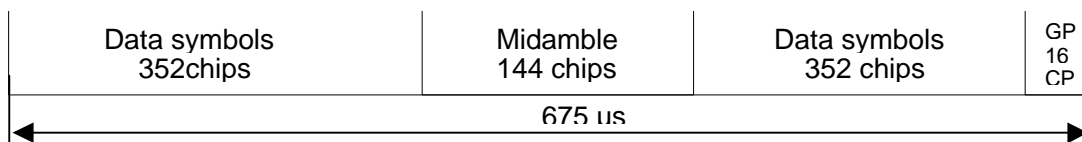
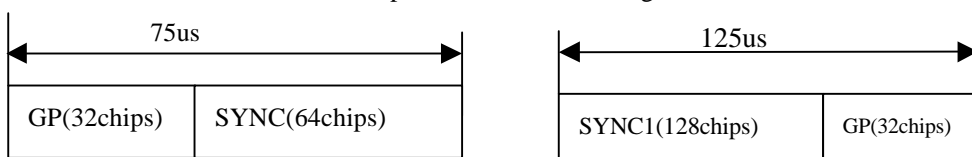


Figure Burst structure for normal traffic time slot

The structure for DwPTS and UpPTS is described in Figures below.



*Figure Structure for DwPTS**Figure Structure for UpPTS*

[Rationale:]

In the burst structure figure, the data symbols in each side of the midamble are 352 chips. The TPC bits for power control, the TFCI bits and the additional uplink synchronization bits (synchronization shift) are included in the Data symbols fields of the burst if they are needed. The amount of TFCI bits used is depending on the service and the details for TFCI, synchronization shift and TPC bits should be provided later with service mapping. For the power control symbols, the uplink synchronization control symbols and the TFCI the symbols around the midamble are used.

The GP field in the same figure for each time slot is used for protection between time slots to avoid the long delay multi-path interference. It should be noted that the GP of the TS0 together with the guard period in DwPTS is 48 chips long which is different with other normal guard period of 16 chips between time slots. This 'super long' guard period can be used to avoid the interference between the last normal downlink time slot and the downlink synchronization pilot burst. Otherwise, the interference to the last downlink time slot from the strong powered pilot will be serious to the traffic; and vice versa, the interference to the downlink pilot burst from the last downlink time slot will decrease the performance on downlink synchronization and cell search. Note that if the UEs serving Node B is far away and the UE makes handover measurements it will receive the beginning of the DwPTS of a close by Node B inside these 48 chip. 48 chip corresponds to 11 km difference in distance to the Node B. If the other Node B is more distant to the serving Node B, big guard period can be used for receiving the DwPTS of the handover candidate Node B.

In DwPTS and UpPTS, the content of SYNC and SYNC1 field are used for downlink and uplink pilot. The GP fields are used to separate the downlink (uplink) pilot from the normal downlink (uplink) time slot.

It should be pointed out that the uplink synchronization burst (SYNC1) is not followed by a RACH immediately. First the UL synchronization burst UpPTS is sent by the UE. This UpPTS is used for Node B to determine the received power level and the received timing. Second, the Node B transmits timing and power control information to the UE using the FPACH (one burst message) within the next 4 frames. Then the P-RACH is transmitted. Both FPACH and P-RACH are carrying single burst messages transmitted on a normal traffic time slot (see Burst structure figure). This two phase procedure which is different with the GSM of one phase procedure has better performance than the classical approach as used in GSM. In this case, the normal traffic burst and access burst can be active in the same time slot and the interference is reduced for each other if they are time-aligned.

Note that the UpPTS has to be transmitted by the UE in advance (starting in the big GP) to arrive at the Node B at the position indicated in the burst structure figure. The UpPTS can also be received at a different position if the UE cannot or does not aim at the RX position indicated in the burst structure figure. Thus, the UpPTS can also start within the guard interval (RX, TX), depending on the situation in the system. This means relaxation to estimate timing in UE, e.g. from pathloss on P-CCPCH.

And the proposed frame structure can support all the environments of macro-, micro- and pico- cells. In vehicular environment, the speed can be more than 120km/h. Also in the proposed frame structure, some specific properties for low chip rate option such as smart antenna technology, uplink synchronisation, beamforming, etc can be well supported.

[Explanation difference:]

In high chip rate option, there are 2 burst types of DPCH. They have different midamble lengths. And there is only one burst type of DPCH in the low chip rate option. The use of the same burst structure for RACH and for traffic will guarantee that the RACH can be handled with conventional traffic on the same UL time slots since the RACH is already UL synchronised.

#### 7.2.2.2.1 Transmission of TFCI

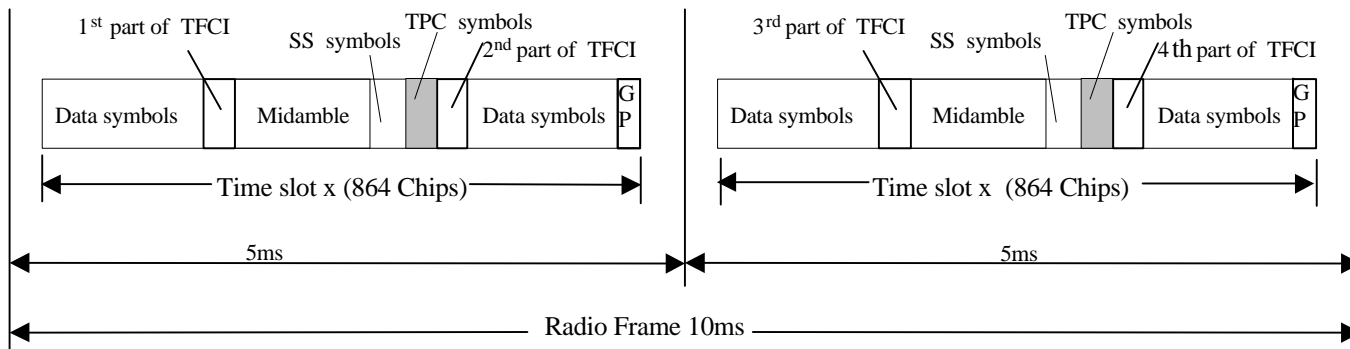
[Description:]

There is only one burst type for normal time slot in the low chip rate option. It provides the possibility for transmission of TFCI both in up- and downlink. For every user the TFCI information is to be transmitted

once per 10ms radioframe. If no TPC and SS are applied, the TFCI information is to be transmitted directly adjacent to the midamble of the 5ms subframe of the assigned frame. The position in case of TPC and/or SS application is shown in the figures below.

[Rationale:]

There is only one burst type for normal time slot in the low chip rate option. It provides the possibility for transmission of TFCI both in up- and downlink. For every user the TFCI information is to be transmitted once per 10ms radioframe. The transmission of TFCI is negotiated at call setup and can be re-negotiated during the call. For each CCTrCH it is indicated by higher layer signalling, which TFCI format is applied. Additionally for each allocated timeslot it is signalled individually whether that timeslot carries the TFCI or not. If a time slot contains the TFCI, then it is always transmitted using the first allocated channelisation



**Position of TFCI information in the traffic burst in case of L1 control signals**

code in the timeslot, according to the order in the higher

layer allocation message. The transmission of TFCI is done in the data parts of the respective physical channel, this means TFCI and data bits are subject to the same spreading procedure. The encoded TFCI symbols are both equally distributed between the subframes and between the data blocks. Hence the midamble structure and length is not changed. If no TPC and SS are applied, the TFCI information is to be transmitted directly adjacent to the midamble of the 5ms subframe of the assigned frame. The position in case of TPC and/or SS application is shown in the figures above. Figure above shows the position of the TFCI in a traffic burst, if L1 control signals, SS (synchronization shift) and TPC (Transmit Power Control), is transmitted.

[Explanation difference:]

In high chip rate option, both burst types 1 and 2 provide the possibility for transmission of TFCI both in up- and downlink. The TFCI information is to be transmitted directly adjacent to the midamble if no TPC is transmitted. In the low chip rate option, there is only one burst type for normal time slot. It provides the possibility for transmission of TFCI both in up- and downlink. For every user the TFCI information is to be transmitted once per 10ms radioframe. The TFCI information is to be transmitted directly adjacent to the midamble of the 5ms subframe of the assigned frame if no TPC and SS is applied. The position of the TFCI in case of TPC and/or SS transmission is analogous to the high chiprate option and depicted in figure above.

7.2.2.2.2 Transmission of TPC

[Description:]

There is only one burst type for normal time slot in the low chip rate option. It provides the possibility for transmission of L1 control signal "TPC" both in up- and downlink. For every user the TPC information is to be transmitted once per 5ms subframe.

[Rational:]

Hence the midamble structure and length is not changed. The TPC information is to be transmitted directly after SS. Figure below shows the position of the TPC in a traffic burst.

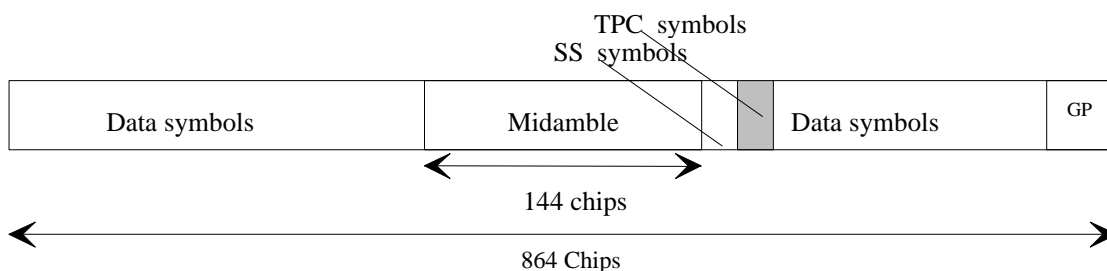


Figure : Position of TPC information in the traffic burst

For the number of layer 1 symbols there are 3 possibilities configurable for each channelisation code during the call setup:

- one SS and TPC symbol
- no SS and TPC symbols
- 16/SF SS and 16/SF TPC symbols (note: there is a need to study this further)

[Explanation difference:]

In high chip rate option, both burst types 1 and 2 provide the possibility for transmission of TPC only in uplink.

While in the low chip rate option, there is only one burst type for normal time slot. For the number of layer 1 symbols there are 3 possibilities configurable for each channelisation code during the call setup. It provides the possibility for transmission of TPC both in up- and downlink. For every user the TPC information is to be transmitted once per 5ms subframe. So it gives faster power control functionality in the low chip rate option than it does in high chip rate option. This is advantageous, because the lower chip rate has less frequency diversity which can be compensated with faster control algorithms. The smart antenna feature increases the demand on the speed of the control algorithms, because the smart antenna algorithms tend to focus on one DOA which has more Rayleigh fading than all DOAs received at a single antenna.

Note: This is to be verified by performance analysis



## 7.2.2.2.3 Timeslot formats

[Description:]

The timeslot format depends on the spreading factor, midamble length, the TPC and SS signals presence and on the number of the TFCI bits. In the case that L1 signals is used, different amount of bits are mapped to the two data fields. For the transmission of the TPC/SS, there are three possible configurations for the number of TPC/SS symbols:

1. 1 symbol TPC and 1 symbol SS
2. No TPC and No SS.
3. 16/SF symbol TPC and 16/SF symbol SS.

So, in case 3 , when  $SF=1$  , the number of TPC/SS is 16 symbol corresponding 32 bits (for QPSK) and 48 bits (for 8PSK).

16/SF TPC/SS symbols is for the case that the number of L1 signalling bits of one given RU after spreading are same although different SFs are used. Thus, the mapping of user data on the payload can stay the same regardless what the spreading factor is.

The timeslot formats are depicted in the following subclause.

## 7.2.2.2.3.1 Timeslot formats for Downlink

Table : Time slot formats for the Downlink

Slot Format #	Spreading Factor	Midamble length (chips)	$N_{\text{TFCI}}$ (bits)	$N_{\text{SS}} \& N_{\text{TPC}}$ (bits)	Bits/slot	$N_{\text{Data/Slot}}$ (bits)	$N_{\text{data/data field(1)}}$ (bits)	$N_{\text{data/data field(2)}}$ (bits)
0	16	144	0	<b>0 &amp; 0</b>	88	88	44	44
1	16	144	4	0 & 0	88	84	42	42
2	16	144	8	0 & 0	88	80	40	40
3	16	144	16	0 & 0	88	72	36	36
4	16	144	32	0 & 0	88	56	28	28
5	16	144	0	2 & 2	88	84	44	40
6	16	144	4	2 & 2	88	80	42	38
7	16	144	8	2 & 2	88	76	40	36
8	16	144	16	2 & 2	88	68	36	32
9	16	144	32	2 & 2	88	52	28	24
10	1	144	0	0 & 0	1408	1408	704	704
11	1	144	4	0 & 0	1408	1404	702	702
12	1	144	8	0 & 0	1408	1400	700	700

Slot Format #	Spreading Factor	Midamble length (chips)	N <sub>TF</sub> CI (bits)	N <sub>SS</sub> & N <sub>TPC</sub> (bits)	Bits/slot	N <sub>Data/Slot</sub> (bits)	N <sub>data/data field(1)</sub> (bits)	N <sub>data/data field(2)</sub> (bits)
13	1	144	16	0 & 0	1408	1392	696	696
14	1	144	32	0 & 0	1408	1376	688	688
15	1	144	0	2 & 2	1408	1404	704	700
16	1	144	4	2 & 2	1408	1400	702	698
17	1	144	8	2 & 2	1408	1396	700	696
18	1	144	16	2 & 2	1408	1388	696	692
19	1	144	32	2 & 2	1408	1372	688	684
20	1	144	0	32 & 32	1408	1344	704	640
21	1	144	4	32 & 32	1408	1340	702	638
22	1	144	8	32 & 32	1408	1336	700	636
23	1	144	16	32 & 32	1408	1328	696	632
24	1	144	32	32 & 32	1408	1312	688	624

7.2.2.2.3.2 Timeslot formats for Uplink

Table : Time slot formats for the Uplink

Slot Format #	Spreading Factor	Midamble length (chips)	N <sub>TF</sub> CI (bits)	N <sub>SS</sub> & N <sub>TPC</sub> (bits)	Bits/slot	N <sub>Data/Slot</sub> (bits)	N <sub>data/data field(1)</sub> (bits)	N <sub>data/data field(2)</sub> (bits)
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Slot Format #	Spreading Factor	Midamble length (chips)	N <sub>TFCI</sub> (bits)	N <sub>SS</sub> & N <sub>TPC</sub> (bits)	Bits/slot	N <sub>Data/Slot</sub> (bits)	N <sub>data/data field(1)</sub> (bits)	N <sub>data/data field(2)</sub> (bits)
0	16	144	0	0 & 0	88	88	44	44
1	16	144	4	0 & 0	88	84	42	42
2	16	144	8	0 & 0	88	80	40	40
3	16	144	16	0 & 0	88	72	36	36
4	16	144	32	0 & 0	88	56	28	28
5	16	144	0	2 & 2	88	84	44	40
6	16	144	4	2 & 2	88	80	42	38
7	16	144	8	2 & 2	88	76	40	36
8	16	144	16	2 & 2	88	68	36	32
9	16	144	32	2 & 2	88	52	28	24
10	8	144	0	0 & 0	176	176	88	88
11	8	144	4	0 & 0	176	172	86	86
12	8	144	8	0 & 0	176	168	84	84
13	8	144	16	0 & 0	176	160	80	80
14	8	144	32	0 & 0	176	144	72	72
15	8	144	0	2 & 2	176	172	88	84

Slot Format #	Spreading Factor	Midamble length (chips)	N <sub>TFCI</sub> (bits)	N <sub>SS</sub> & N <sub>TPC</sub> (bits)	Bits/slot	N <sub>Data/Slot</sub> (bits)	N <sub>data/data field(1)</sub> (bits)	N <sub>data/data field(2)</sub> (bits)
16	8	144	4	2 & 2	176	168	86	82
17	8	144	8	2 & 2	176	164	84	80
18	8	144	16	2 & 2	176	156	80	76
19	8	144	32	2 & 2	176	140	72	68
20	8	144	0	4 & 4	176	168	88	80
21	8	144	4	4 & 4	176	164	86	78
22	8	144	8	4 & 4	176	160	84	76
23	8	144	16	4 & 4	176	152	80	72
24	8	144	32	4 & 4	176	136	72	64
25	4	144	0	0 & 0	352	352	176	176
26	4	144	4	0 & 0	352	348	174	174
27	4	144	8	0 & 0	352	344	172	172
28	4	144	16	0 & 0	352	336	168	168
29	4	144	32	0 & 0	352	320	160	160
30	4	144	0	2 & 2	352	348	176	172
31	4	144	4	2 & 2	352	344	174	170
32	4	144	8	2 & 2	352	340	172	168

Slot Format #	Spreading Factor	Midamble length (chips)	N <sub>TFCI</sub> (bits)	N <sub>SS</sub> & N <sub>TPC</sub> (bits)	Bits/slot	N <sub>Data/Slot</sub> (bits)	N <sub>data/data field(1)</sub> (bits)	N <sub>data/data field(2)</sub> (bits)
33	4	144	16	2 & 2	352	332	168	164
34	4	144	32	2 & 2	352	316	160	156
35	4	144	0	8 & 8	352	336	176	160
36	4	144	4	8 & 8	352	332	174	158
37	4	144	8	8 & 8	352	328	172	156
38	4	144	16	8 & 8	352	320	168	152
39	4	144	32	8 & 8	352	304	160	144
40	2	144	0	0 & 0	704	704	352	352
41	2	144	4	0 & 0	704	700	350	350
42	2	144	8	0 & 0	704	696	348	348
43	2	144	16	0 & 0	704	688	344	344
44	2	144	32	0 & 0	704	672	336	336
45	2	144	0	2 & 2	704	700	352	348
46	2	144	4	2 & 2	704	696	350	346
47	2	144	8	2 & 2	704	692	348	344
48	2	144	16	2 & 2	704	684	344	340
49	2	144	32	2 & 2	704	668	336	332

Slot Format #	Spreading Factor	Midamble length (chips)	N <sub>TFCI</sub> (bits)	N <sub>SS</sub> & N <sub>TPC</sub> (bits)	Bits/slot	N <sub>Data/Slot</sub> (bits)	N <sub>data/data field(1)</sub> (bits)	N <sub>data/data field(2)</sub> (bits)
50	2	144	0	16 & 16	704	672	352	320
51	2	144	4	16 & 16	704	668	350	318
52	2	144	8	16 & 16	704	664	348	316
53	2	144	16	16 & 16	704	656	344	312
54	2	144	32	16 & 16	704	640	336	304
55	1	144	0	0 & 0	1408	1408	704	704
56	1	144	4	0 & 0	1408	1404	702	702
57	1	144	8	0 & 0	1408	1400	700	700
58	1	144	16	0 & 0	1408	1392	696	696
59	1	144	32	0 & 0	1408	1376	688	688
60	1	144	0	2 & 2	1408	1404	704	700
61	1	144	4	2 & 2	1408	1400	702	698
62	1	144	8	2 & 2	1408	1396	700	696
63	1	144	16	2 & 2	1408	1388	696	692
64	1	144	32	2 & 2	1408	1372	688	684
65	1	144	0	32 & 32	1408	1344	704	640
66	1	144	4	32 & 32	1408	1340	702	638

Slot Format #	Spreading Factor	Midamble length (chips)	N <sub>TFCI</sub> (bits)	N <sub>SS</sub> & N <sub>TPC</sub> (bits)	Bits/slot	N <sub>Data/Slot</sub> (bits)	N <sub>data/data field(1)</sub> (bits)	N <sub>data/data field(2)</sub> (bits)
67	1	144	8	32 & 32	1408	1336	700	636
68	1	144	16	32 & 32	1408	1328	696	632
69	1	144	32	32 & 32	1408	1312	688	624

## 7.2.2.2.3.3 Timeslot formats for 8PSK modulation ( both for Uplink and Downlink )

Table: Timeslot formats for 8PSK modulation

Slot Format #	Spreading Factor	Midamble length (chips)	N <sub>TFCI</sub> (bits)	N <sub>SS</sub> & N <sub>TPC</sub> (bits)	Bits/slot	N <sub>Data/Slot</sub> (bits)	N <sub>data/data field(1)</sub> (bits)	N <sub>data/data field(2)</sub> (bits)
0	1	144	0	<b>0 &amp; 0</b>	2112	2112	1056	1056
1	1	144	6	0 & 0	2112	2106	1053	1053
2	1	144	12	0 & 0	2112	2100	1050	1050
3	1	144	24	0 & 0	2112	2088	1044	1044
4	1	144	48	0 & 0	2112	2064	1032	1032
5	1	144	0	3 & 3	2112	2106	1056	1050
6	1	144	6	3 & 3	2112	2100	1053	1047
7	1	144	12	3 & 3	2112	2094	1050	1044



Slot Format #	Spreading Factor	Midamble length (chips)	N <sub>TFCI</sub> (bits)	N <sub>SS</sub> & N <sub>TPC</sub> (bits)	Bits/slot	N <sub>Data/Slot</sub> (bits)	N <sub>data/data field(1)</sub> (bits)	N <sub>data/data field(2)</sub> (bits)
8	1	144	24	3 & 3	2112	2082	1044	1038
9	1	144	48	3 & 3	2112	2058	1032	1026
10	1	144	0	48 & 48	2112	2016	1056	960
11	1	144	6	48 & 48	2112	2010	1053	957
12	1	144	12	48 & 48	2112	2004	1050	954
13	1	144	24	48 & 48	2112	1992	1044	948
14	1	144	48	48 & 48	2112	1968	1032	936
15	16	144	0	0 & 0	132	132	66	66
16	16	144	6	0 & 0	132	126	63	63
17	16	144	12	0 & 0	132	120	60	60
18	16	144	24	0 & 0	132	108	54	54
19	16	144	48	0 & 0	132	84	42	42
20	16	144	0	3 & 3	132	126	66	60
21	16	144	6	3 & 3	132	120	63	57
22	16	144	12	3 & 3	132	114	60	54
23	16	144	24	3 & 3	132	102	54	48
24	16	144	48	3 & 3	132	78	42	36

[Explanation difference:]

Based on the burst structure and the TFCI,SS and TPC control signals, the low chip rate TDD option has a different burst type from that of high chip rate TDD option. When 2M service is transmitted, the timeslot formats are based on 8PSK modulation, but the timeslot formats in table 3 are not restricted to the use for 2Mbps only..

### 7.2.2.2.3 Transmission of SS

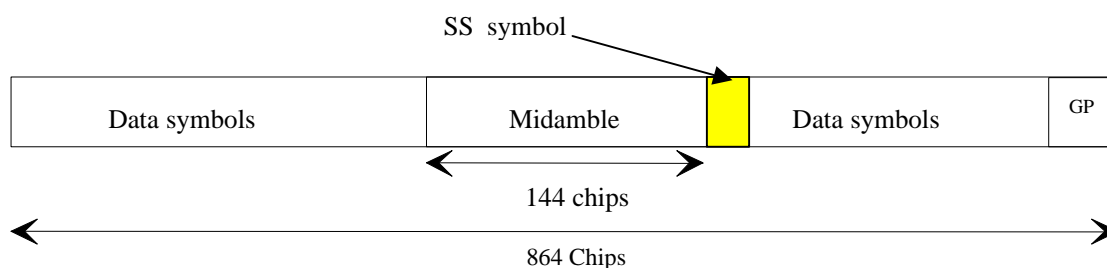
[Description:]

The SS is utilized to command a timing adjustment each M frame. The SS, as one of L1 signals, is to be transmitted once per 5ms subframe in downlink.

[Rationale:]

The SS is utilized to command a timing adjustment  $(k/8)T_c$  each M frames, where  $T_c$  is the chip period. The default k and M values are signaled by the network by means of system information that is broadcast in the cell. The SS information is to be transmitted directly after the midamble in downlink. Figure 1 shows the position of the SS in a burst. The SS, as one of L1 signals, is to be transmitted once per 5ms subframe.

M (1-8) and k (1-8) can be adjusted during call setup or readjusted during the call.



*Position of SS information in a burst in downlink and uplink*

Note that for the uplink where there's no SS symbol used, the SS symbol space is reserved for future use. This can keep the UL and DL slot same structure.

For the number of layer 1 symbols there are 3 possibilities configurable for each channelisation code during the call setup:

- one SS and TPC symbol
- no SS and TPC symbols
- 16/SF SS and 16/SF TPC symbols

[Explanation difference:]

In high chip rate TDD option, SS information is not transmitted as L1 signal on each frame. Because of uplink synchronization in the low chip rate TDD option, SS information is transmitted in downlink, as one of L1 signals, once per 5ms subframe.

### 7.2.2.3 Training sequences for spread bursts

[Description:]

The training sequences, i.e. midambles, of different users active in the same time slot are time shifted versions of a single periodic basic code. Different cells use different periodic basic midamble codes, i.e. different midamble sets. In this way joint channel estimation for the channel impulse responses of all active users within one time slot can be done by one single cyclic correlation. The different user specific channel impulse response estimations are obtained sequentially in time at the output of the correlator.

Up to 16 midambles are possible within the low chip rate TDD option.

The generation of midamble is different from high chip rate TDD option. The difference of training sequences for spread bursts for low chip rate is described here.

[Rationale:]

The burst structure for low chip rate TDD option is different with high chip rate TDD option. These bursts contain  $L_m$  midamble chips, which are also termed midamble elements. The  $L_m$  elements  $\underline{m}_i^{(k)}$ ;  $i=1\dots L_m$ ;  $k=1,\dots,K$ ; of the midamble codes  $\underline{\mathbf{m}}^{(k)}$ ;  $k=1,\dots,K$ ; of the  $K$  users are taken from the complex set

$$\underline{V}_m = \{1, j, -1, -j\}. \quad (1)$$

The elements  $\underline{m}_i^{(k)}$  of the complex midamble codes  $\underline{\mathbf{m}}^{(k)}$  fulfil the relation

$$\underline{m}_i^{(k)} = (j)^i \cdot m_i^{(k)} \quad m_i^{(k)} \in \{1, -1\}; i = 1, \dots, L_m; k = 1, \dots, K. \quad (2)$$

Hence, the elements  $\underline{m}_i^{(k)}$  of the complex midamble codes  $\underline{\mathbf{m}}^{(k)}$  of the  $K$  users are alternating real and imaginary.

With  $W$  being the number of taps of the impulse response of the UE radio channels, the  $L_m$  binary elements  $m_i^{(k)}$ ;  $i = 1, \dots, L_m$ ;  $k = 1, \dots, K$ ; of (2) for the complex midamble  $\underline{\mathbf{m}}^{(k)}$ ;  $k=1,\dots,K$ ; of the  $K$  users are generated according to Steiner's method [1] from a single periodic basic code

$$\mathbf{m} = (m_1, m_2, \dots, m_{L_m+(K-1)W})^T \quad m_i \in \{1, -1\}; i = 1, \dots, (L_m + (K-1)W). \quad (3)$$

The elements  $m_i$ ;  $i = 1, \dots, (L_m + (K-1)W)$ , of (3) fulfil the relation

$$m_i = m_{i-P} \quad \text{for the subset } i = (P+1), \dots, (L_m + (K-1)W). \quad (4)$$

The  $P$  elements  $m_i$ ;  $i = 1, \dots, P$ , of one period of  $m$  according to (3) are contained in the vector

$$\mathbf{m}_P = (m_1, m_2, \dots, m_P)^T. \quad (5)$$

With  $\mathbf{m}$  according to (3) the  $L_m$  binary elements  $m_i^{(k)}$ ;  $i = 1, \dots, L_m$ ;  $k = 1, \dots, K$ ; of (2) for the midamble of the  $K$  users are generated based on Steiner's formula

$$m_i^{(k)} = m_{i+(K-k)W} \quad i = 1, \dots, L_m; k = 1, \dots, K. \quad (6)$$

In the following the term 'a midamble code set' or 'a midamble code family' denotes  $K$  specific midamble codes  $\underline{\mathbf{m}}^{(k)}$ ;  $k=1,\dots,K$ . Different midamble code sets  $\underline{\mathbf{m}}^{(k)}$ ;  $k=1,\dots,K$ ; are in the following specified based on different periods  $\mathbf{m}_P$  according (5).

In adjacent cells of the cellular UE radio system, different midamble codes sets  $\underline{\mathbf{m}}^{(k)}$ ;  $k=1,\dots,K$ ; should be used to guarantee a proper channel estimation.

As mentioned above a single midamble code set  $\underline{\mathbf{m}}^{(k)}$ ;  $k=1,\dots,K$ ; consisting of  $K$  midamble codes is based on a single period  $\mathbf{m}_P$  according to (5).

In the following several exemplary periods  $\mathbf{m}_P$  according (5) which can be used to generate different midamble code sets  $\underline{\mathbf{m}}^{(k)}$ ;  $k=1,\dots,K$ ; will be listed in tables in a hexadecimal representation. As shown in the table below always 4 binary elements  $m_i$  are mapped on a single hexadecimal digit.

The mean degradation's which serve as a quality information of the periods  $\mathbf{m}_p$  according to (5) and hence of the specified midamble code sets  $\underline{\mathbf{m}}^{(k)}$ ;  $k=1,\dots,K$ ; will be also given.

*Table : Mapping of 4 binary elements on a single hexadecimal digit*

4 binary elements $m_i$	Mapped on hexadecimal digit
-1 -1 -1 -1	0
-1 -1 -1 1	1
-1 -1 1 -1	2
-1 -1 1 1	3
-1 1 -1 -1	4
-1 1 -1 1	5
-1 1 1 -1	6
-1 1 1 1	7
1 -1 -1 -1	8
1 -1 -1 1	9
1 -1 1 -1	A
1 -1 1 1	B
1 1 -1 -1	C
1 1 -1 1	D
1 1 1 -1	E
1 1 1 1	F

Table: Basic Midamble Codes

Code ID	Basic Midamble Codes of length 128
0	B2AC420F7C8DEBFA69505981BCD028C3
1	0C2E988E0DBA046643F57B0EA6A435E2
2	D5CEC680C36A4454135F86DD37043962
3	E150D08CAC2A00FF9B32592A631CF85B
4	E0A9C3A8F6E40329B2F2943246003D44
5	FE22658100A3A683EA759018739BD690
6	B46062F89BB2A1139D76A1EF32450DA0
7	EE63D75CC099092579400D956A90C3E0
8	D9C0E040756D427A2611DAA35E6CD614
9	EB56D03A498EC4FEC98AE220EC390450
10	F598703DB0838112ED0BABB98642B665
11	A0BC26A992D4558B9918986C14861EFF
12	541350D109F1DD68099796637B824F88
13	892D344A962314662F01F9455F7BC302
14	49F270E29CCD742A40480DD4215E1632
15	6A5C0410C6C39AA04E77423C355926DE
16	7976615538203103D4DBCC219B16A9E1
17	A6C3C3175845400BD2B738C43EE2645F
18	A0FD56258D228642C6F641851C3751ED
19	EFA48C3FC84AC625783C6C9510A2269A
20	62A8EB1A420334B23396E8D76BC19740
21	9E96235699D5D41C9816C921023BC741
22	4362AE4CAE0DCC32D60A3FED1341A848
23	454C068E6C4F190942E0904B95D61DFB
24	607FEEA6E2E99206718A49C0D6A25034
25	E1D1BCDA39A09095B5C81645103A077C
26	994B445E558344DE211C8286DDD3D1A3
27	C15233273581417638906ADB61FDCA3C
28	8B79A274D542F096FB1388098230F8A1
29	DF58AC1C5F44B2A40266385CE1DA5640

30	B5949A1CC69962C464401D05FF5C1A7A
31	85AC489841ED3EAA2D83BBB0039CC707
32	AE371CC144BC95923CA8108D8B49FE82
33	7F188484A649D1C22BDA1F09D49B5117
34	ADAA3C657089DEF7C0284903A491C9B0
35	C3F96893C7504DC3B51488604AF64F4C
36	B4002F5AE0CE8623AC979D368E9148C1
37	0EEBCC0C795C02A106C24ABB36D08C6E
38	4B0F537E384A893F58971580D9894433
39	08E0035AB29B7ECC53C15DAA0687CC8F
40	8611ACBC4C82781D77654EE862506D60
41	63315261A8F1CB02549802DBFD197C07
42	9A2609A434F43E7DCADC0E22B2EF4012
43	F4C9F0A127A88461209ABF8C69CE4D00
44	C79124EE3FFC28C5C4524D2B01670D42
45	C91985C4FED53D09361914354BA80E79
46	82AA517260779ECFF26212C1A10BDC29
47	561DE2040ACB458E0DBD354E43E111D9
48	2E58C7202D17392BC1235782CEFABB09
49	C4FAA121C698047650F6503126A577C1
50	E7B75206A9B410E44346E0DAE842A23C
51	3F8B1C32682B28D098D3805ED130EA7F
52	8D5FC2C1C6715F824B401434C8D4BB82
53	0B2A43453ACC028FE6EB6E1CB0740B59
54	BC56948FC700BA4883262EE73E12D82A
55	558D136710272912FA4F183D1189A7FD
56	5709E7F82DC6500B7B12A3072D182645
57	86D4F161C844AE5E20EE39FD5493B044
58	8729B6EDC382B152185885F013DAE222
59	154C45B50720F4C362C14C77FE8335A1
60	C6A0962890351F4EB802DE43A7662C9E
61	D19D69D6B380B4B22457CB80033519F0

62	C7D89509FB0DAE9255998E0A00C2B262
63	DFD481C652C0C905D61D66F1732C4AA2
64	06C848619AF1D6C910A8EAC4B622FC06
65	0635E29D4E7AC8ABC189890241F45ECA
66	B272B020586AAD7B093AC2F459076638
67	B608ACE46E1A6BC96181EEDD88B54140
68	0A516092B3ED7849B168AFE223B8670E
69	D1A658C5009E04D0D7D5E9205EE663E8
70	AC316DC39B91EB60B1AABD8280740432
71	E3F06825476A026CD287625E514519FC
72	A56D092080DDE8994F387C175CC56833
73	15EA799DE587C506D0CD99A408217B05
74	A59C020BAB9AF6D3F813C391CA244CD2
75	74B0101EB9F3167434B94BABC8378882
76	CE752975C8DA9B0100386DB82A8C3D20
77	BBB38DCDB1E9118570AC147DC05241A4
78	944ABBF0866098101F6971731AB2E986
79	2BB147B2A30C68B4853F90481A166EB6
80	444840ACCF3F23C45B56D7704BF18283
81	87604F7450D1AD188C452981A5C7FC9B
82	8C3842EBC948A65BC4C8B387F11B7090
83	10B4767D071CF5DB2288E4029576135A
84	6F07AAB697CD0089572C6B062E2018E4
85	D3D65B442057E613A8655060C8D29E27
86	5EDA330514C604BF4E0894E09EC57A74
87	B0899CD094060724DED82AE85F18A43A
88	B2D999B86DF902BC25015CAE3A0823C4
89	C23CD40F04242B92D46EED82CD9A9A18
90	D22DDCC5CB82960125DD24655F3C8788
91	54987218FBD99AE4340FD4C9458E9850
92	BE4341822997A7B11EA1E8A1A2767005
93	255200FBA6EE48E6DE0A82B0461B8D0F



94	6FBD58A663932423503690CF9C171701
95	D215033A4AA87EC1C232BAC7EDA09370
96	CA0959B01AE48E80204F1E4A3F29CE55
97	582043413B9B825903E3A3545ED59463
98	5016541922971C703D16E284CBDF633B
99	7347EF160A1733CA98D43608A83A920B
100	908B22AD433CCA00B3FD47C691F1A290
101	BB22A272FC6923DF1B43BA4118806570
102	0FA75C87474836B47DC7624D61193802
103	A22EBA0658A4D0FF1E9CA5030A65CC06
104	6C9C51CA15F1F4981F4C46180A6A6697
105	4C847ACF8BC15359C405322851C9BDE2
106	C1D29499C0082C9DE473ED15B14D63E0
107	7E85ECC98AC761005076C5572869A431
108	D8F11121595B8F49F78A7039E44126A0
109	1A0BC814445FD71C8E5B1A9163ED2059
110	A7591F27F8B0C00C68CC41697954FA04
111	6CA2CE595E7406D79C4840183D41B9D0
112	C093D3CC701FC20E66F5AB22516C5460
113	D0E0CDE9B595546B96C4F8066B469020
114	E99F743A451431C8B427054A4E6F2007
115	C0D21A344A2C07DF2A6EBE6250C7B91E
116	F031223E282CF7A4D8EF174A908668AE
117	E4BD244AC16C55C7137FB068FD44280C
118	C44920DE2028F19FC2AAB36A0DCFDAD0
119	3FA7054E77135250699E6C8A11600742
120	D5740B4D8870C1C5B5A214C4266FC537
121	F0B7942D43BB6F38446442EB8126AB80
122	83DB9534EAD6238FA8968798CDF04848
123	EB9663CDDC2B291690703125BABCB800
124	84D547225D4BBD20DEF1A583240C6E0F
125	B51F6A771838BE934724AEA6A2669802

126	D92AC05E10496794BBDC115233B1C068
127	D3ACF0078EDA9856BBB0AF8651132103

[Explanation difference:]

The midamble used in the burst for low chip rate TDD is different from high chip rate TDD. And this is mainly coming from different chip rate and burst format. Different chip rate lead to different length of channel impulse response and the different length of training sequence (midamble).

The maximum channel impulse response is scalable. This evokes a different midamble generation scheme as used for high chip rate TDD.

#### 7.2.2.3.1 Selection of length of channel impulse response

[Description:]

The training sequences, i.e. Midambles, of different users active in the same slot are time shifted versions of one single periodic basic code. Different cells use different periodic basic codes, i.e. different midamble sets. In this way a joint channel estimation for the channel impulse responses of all active users within one time slot can be done by one single cyclic correlation. The different user specific channel impulse response estimates are obtained sequentially in time at the output of the correlator. Up to 16 midambles in one time slot are possible within the low chip rate TDD option.

In both low and high chip rate systems,  $W$ , the length of the impulse response of the mobile radio channels, is an important parameter. There is only one burst type for normal time slot in the low chip rate TDD option, and the length of midambles is different from the high chip rate option, so the selection of  $W$  needs to be defined separately.

[Rational:]

The midamble has a length of  $L_m=144$ , which is corresponding to:

$$K=2, 4, 6, 8, 10, 12, 14, 16, W=\left\lfloor \frac{P}{K} \right\rfloor, P=128.$$

Note: that  $\lfloor x \rfloor$  denotes the largest integer number less or equal to  $x$ .

Depending on the possible delay spread cells are configured to use midambles which are generated from the Basic Midamble Codes.

The cell configuration is broadcast on BCH.

#### 7.2.2.4 Beamforming and Transmit Diversity

[Description:]

A smart antenna system is composed of an array of multiple antenna elements and coherent transceivers with advanced digital signal processing algorithms. Instead of a single fixed beam pattern from a traditional antenna, the smart antenna can dynamically generate multiple beam patterns, each of them is pointed to a particular UE, and such beam patterns can adapt to follow any UE intelligently. On the Rx side of Node B, such a feature, i.e., spatial selective reception at the Node B can greatly minimize co-channel interference

from the co-channel UEs at different locations, thus increase the Rx sensitivity and lead to higher capacity. It can also effectively incorporate multipath components to combat multipath fading. On the Tx side of Node B, intelligent spatially selective Tx (downlink) beamforming can also greatly reduce the interference to other co-channel UEs, then dramatically save the output power requirement and lead to higher capacity. It should be noted that this section only describes a preferred approach to beamforming, other high performance techniques may also be applicable.

The low chip rate option is mainly based on the smart antenna technology. Some main technical features of the low chip rate TDD option such as 5 ms sub-frame structure are based on the smart antenna request.

When DL beamforming or TX Diversity is used, at least for the resource units beamforming/Tx Diversity is applied to and which are allocated to dedicated channels, the resource units shall get one individual midamble per user or per resource unit according to midamble generation, even in DL.

[Rationale:]

The smart antenna array is composed of  $N$  antenna elements,  $N$  related feed cables and  $N$  coherent RF transceivers in RF part. By use of the A/D converters or D/A converters in analog baseband (ABB), the Rx and Tx analog signals are interfaced to the digital baseband (DBB) part over the high-speed data bus. In this model, all antenna elements related feed cables and coherent RF transceivers will be calibrated before operating.

#### Beamforming

For the Node B is equipped with smart antenna array and DBB DSP, when a signal comes from one UE within the coverage of the Node B, each antenna element and coherent RF receiver will get it. Because of the different location of the different antenna element, the phase of the Rx signal will be different. In case of multipath propagation, each path will come from different directions with different amplitude and delay. Then the Rx signal at each antenna element will show different phase and amplitude. After the front-end processing in RF part and A/D converters processing in ABB, digitized Rx signal with the phase and amplitude information will be sent to DSP in DBB part. After despreading in the DBB processor, the Rx data of each code channel may be obtained. The purpose of smart antenna in uplink is to find the best  $E_b/I_0$  after the combination. Theoretically, spatial reception at Node B can add up all useful signals while canceling all multipath interference. The next step is to realise downlink beamforming. The Tx signal of the each code channel is got by some algorithms that enable the UE to obtain the best  $E_b/I_0$ . In TDD system, because of the symmetrical performance in wave propagation, it is possible to directly use the spatial reception at Node B results to downlink beamforming.

#### Fast beamforming

It is always very important to reach fast beamforming to catch the time variation in mobile network. The Node B should have a in-time reaction to the fast changing beam patterns. And this is the reason that the TDD interval in low chip rate option is 5ms while 10ms in high chip rate option. This value is a compromise in considering both the number of time slots and the switching speed of RF components.

In smart antenna system, the BTS need receive the UpLink data first, then decide the UE's position, and then beamform to UE in Downlink, but the UE does not need to transmit regularly for the Node B to determine the antenna weights when it is in idle mode.

[Explanation difference:]

For high chip rate option, the chapter about beamforming already exists.

Like the high chip rate option is that not only each user can get one midamble but also each resource allocated to that user can (but need not to) get an individual midamble. The benefit of this is that the signalling overhead is reduced.

## 7.2.3 Primary common control physical channel (P-CCPCH)

### 7.2.3.1 Primary common control physical channel (P-CCPCH)

The BCH as described in subclause 7.3.2 'Common Transport Channels' is mapped onto the Primary Common Control Physical Channels (P-CCPCH1 and P-CCPCH2). The position (time slot / code) of the P-CCPCHs is fixed in low chip rate TDD option, see subclause 7.3.2 'Common Transport Channels'. An encoded bit identifies whether the interleaving frame in the P-CCPCH contains a BCH (1) or not (0).

#### 7.2.3.1.1 P-CCPCH Spreading

The P-CCPCHs use fixed spreading with a spreading factor  $SF = 16$ . The P-CCPCH1 and P-CCPCH2 always use channelisation code 0 and 1 respectively.

#### 7.2.3.1.2 P-CCPCH Burst Types

Only one burst type in low chip rate option

#### 7.2.3.1.3 P-CCPCH Training sequences

The training sequences, i.e. midambles, as described in the MA-generation chapter are used for the P-CCPCHs. The basic midamble code  $m^{(1)}$  is used for P-CCPCHs as training sequence.

As mentioned in sub clause of P-CCPCH in 25.928, P-CCPCHs are mapped onto first two code channels of Ts0 with spreading factor of 16. Other code channel in Ts0 should also use spreading factor of 16.

Each transport channel assigned in TS0 has channel impulse response estimation window of maximum length  $W=16$  such that there are 8 midamble codes used for TS0.

Ts0 is configured in the following way: Each of the 8 midamble codes is assigned to 2 code channels of spreading factor 16. The first midamble code is assigned to the first 2 code channels of spreading factor 16. The next midamble code to the next 2 code channels of spreading factor 16 and so forth. The P-CCPCHs are assigned to the first midamble code. In order to provide flexibility, it is possible that the Node B uses – for channels other than P-CCPCHs - a certain midamble code assigned to only 1 code channel of spreading factor 16. In that case, the second code that is assigned to the same midambles is not used by another UE.

[Explanation difference:]

In high chip rate option, the P-CCPCH always contains only the BCH . The position (time slot / code) of the P-CCPCH is known from the Synchronisation Channel (SCH).

In low chip rate option, the P-CCPCH can also contain the PCH and FACH as well as the BCH. The P-CCPCHs are mapped onto two code channels of the DL time slot (time slot 0) which is followed by the DwPTS

Other methods for BCH indication and their compatibility with models in TSG RAN WG2 are to be considered.

There are two kinds of burst types in high chip option and the burst type 1 is used for the P-CCPCH.

There is only one burst type in the low chip rate option.

If both the uplink and downlink physical channels are work under the synchronization mode and if "smart antenna" method is used, the interference on P-CCPCH is thought to be very little in low chip rate TDD option. As a result, "Tx diversity" has not been considered currently to be applied in low chip rate TDD. As this may not hold in all cases, the Block STTD applied for P-CCPCH is to be studied.

### 7.2.3.2 Secondary common control physical channel (S-CCPCH)

PCH and FACH can be mapped onto one or more secondary common control physical channels (S-CCPCH). In this way the capacity of PCH and FACH can be adapted to the different requirements. The time slot and codes used for the S-CCPCH are broadcast via cell information. An encoded bit identifies that the interleaving frame in the S-CCPCH contains no BCH. This bit is always 0.

#### 7.2.3.2.1 S-CCPCH Spreading

There are two S-CCPCHs ( S-CCPCH 1 and S-CCPCH 2 ) mapped onto two codes of spreading factor 16. There can be also more than a single pair in use.

#### 7.2.3.2.2 S-CCPCH Burst Types

Same as for the P-CCPCH

#### 7.2.3.2.3 S-CCPCH Training sequences

The training sequences, i.e. midambles as described in the MA-generation chapter, are used for the S-CCPCH.

### 7.2.3.3 The physical random access channel (PRACH)

The RACH is mapped onto one or more uplink physical random access channels (PRACH). In such a way the capacity of the RACH can be flexibly scaled depending on the operators need.

#### 7.2.3.3.1 PRACH Spreading

The uplink PRACH uses either spreading factor SF=16 or SF=8 as described in subclause 7.3.2.3 'The Random Access Channel (RACH)'. The PRACH configuration (time slot number and assigned spreading codes) is broadcast through the BCH information

#### 7.2.3.3.2 PRACH Burst Types

The burst type used on the PRACH is the same as for a traffic channel.

#### 7.2.3.3.3 PRACH Training sequences

The training sequences, i.e. midambles as described in the MA-generation chapter, are used for the PRACH.

#### 7.2.3.3.4 Association between Training Sequences and Channelisation Codes

In the low chip rate TDD option there is a different concept for the RACH. Resource units on the traffic time slots are used for the random access channels. For this reason the PRACH is described and allocated as e.g. the DPCH. Thus, there is no additional association between training sequences and channelisation codes like in the high chip rate TDD option.

[Explanation difference:]

In subclause 10.6.2 "random access procedure", it has been mentioned that the random access procedure of low chip rate option has two-step approach. The SYNC1 word is used to carry out uplink synchronisation and to resolve the access collision. This two-step procedure enables the PRACH to be transmitted with high synchronisation precision as DPCH. So in low chip rate TDD option, the PRACH is uplink synchronized with other uplink traffic, the burst type used on the PRACH is the same as for DPCH while in high chip rate TDD option the burst type of the PRACH is a little different from that of DPCH.

7.2.3.4 The synchronisation channel (SCH)

[Description:]

There are two dedicated physical synchronisation channels —DwPTS and UpPTS in each subframe of the low chip rate option as described in subclause 7.2.1 ‘Frame Structure’ and 7.2.2.2 ‘Burst Types’.

[Rationale:]

The burst structures used for DwPTS and UpPTS are different from that used for other physical channels. The detailed description of the burst structure of DwPTS and UpPTS can be found in subclause 7.2.2.2 ‘Burst Types’.

As described in subclause 7.2.2.2 ‘Burst Types’, there are no training sequences in DwPTS and UpPTS. The SYNC code in DwPTS and the SYNC1 code in UpPTS are not spread.

[Explanation difference:]

In low chip rate option, there are two dedicated Physical Synchronisation Channels, DwPTS for the down link synchronisation and UpPTS for the uplink synchronisation.

In high chip rate option, there is only one dedicated Physical Synchronisation Channel for down link synchronisation

7.2.3.5 Physical Uplink Shared Channel (PUSCH)

‘Common with the high chip rate TDD mode’

7.2.3.6 Physical Downlink Shared Channel (PDSCH)

‘Common with the high chip rate TDD mode’

7.2.3.7 The Page Indicator Channel (PICH)

[Description:]

The Page Indicator Channel (PICH) is a physical channel used, as in 3.84 MCPS TDD option, to carry the Page Indicators (PI).

The PICH is transmitted time multiplexed with a P/S-CCPCH and it is sent at the same reference power level and with the same antenna pattern configuration as the P-CCPCH.

As in the 1.28 MCPS TDD option one burst type only is defined having a different structure with respect to the ones foreseen in the 3.84 MCPS TDD, the PICH structure will be different as well. The structure is chosen so that without defining reserved bits and for all possible PI lengths the bits corresponding to one PI can be symmetrically located in the time slot with respect to the midamble, as in 3.84 MCPS TDD. Moreover, the usage of two codes allows an easy time multiplexing with the P/S-CCPCH and about the same number of PIs per slot as in the 3.84 MCPS TDD mode. Figure below depicts the PICH structure and the numbering order of the transported bits,  $N_{PIB}$ , where  $N_{PIB}$  is equal to 176 bits.



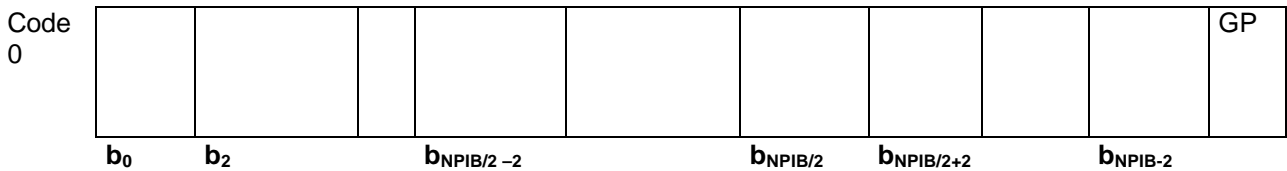


Figure: Transmission and numbering of PI carrying bits on the PICH

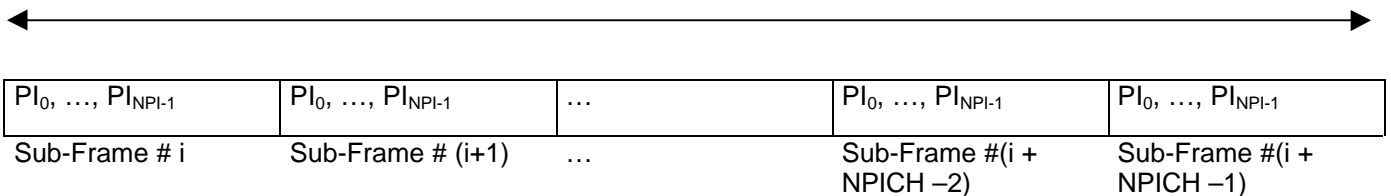
As in high chip rate TDD, Page Indicators can have different length ( $L_{PI}$ ), where  $L_{PI} = 2$  or 4 or 8 symbols respectively, as configured by the network. Therefore, the number of page indicators in a PICH burst are the ones reported in Table below.

Table : Number of Page Indicators (PI) in a PICH burst for the different PI length ( $P_{IL}$ )

	$L_{PI} = 2$	$L_{PI} = 4$	$L_{PI} = 8$
Number of PI per burst	44	22	11

Similar to the 3.84 MCPS TDD option, Page Indicators can be transmitted for  $N_{PICH}$  consecutive sub-frames, which form a PICH block as described in figure.  $N_{PICH}$  is configurable by the higher layers so that  $N = N_{PICH} * N_{PI}$  Page Indicators are transmitted in each PICH block.

1 PICH block



The structure of a paging block, consisting of a PICH and a PCH block is the same as in the high chip rate TDD option. As for the high chip rate TDD option, Page Indicator and Paging Group (PG) for a given user are computed by the higher layers in the network, where PI and PG are assigned independently one to the other.

A given PI corresponds to a  $PI_p$  in the PICH burst of a PICH block at sub-frame number “n”, according to the following rule:

$$p = PI \bmod N_{PI};$$

$$n = PI \text{ div } N_{PI}.$$

As in the high chip rate TDD, the Page Indicator  $PI_P$  is mapped to two bit strings, where the first bit string consists of the bits  $(b_{LPI^*P}; \dots; b_{LPI^*P+LPI-1})$  and the second bit string consists of the bits  $(b_{NPIB/2+LPI^*P}; \dots; b_{NPIB/2+LPI^*P+LPI-1})$  within that burst. This mapping scheme allows for an equal distribution of all PIs within the PICH burst.

[Rationale:]

PICH physical channel allows to improve the DRX mode at the UE, saving power consumption. The benefit of this channel have already been evaluated for the high chip rate TDD and FDD mode where it is now included; therefore it is recommended for its inclusion in the low chip rate TDD option as well.

[Differences:]

While no difference exists in principle between high chip rate TDD and low chip rate TDD PICH physical channel, there are differences in the burst structure coming from the different burst formats and the different number of supporting resource units in the respective TDD options.

## 7.2.4 Beacon function of physical channels

[Description:]

For the purpose of measurements, a beacon function shall be provided by particular physical channels. Considering about the physical character requirement of the beacon function, DwPTS and P-CCPCH in low chip rate TDD satisfy this requirement.

[Rationale:]

For the purpose of measurements, a beacon function is provided by the P-CCPCH and the DwPTS.

### 7.2.4.1 Location of physical channels with beacon function

The DwPTS and the P-CCPCH provides the beacon function in low chip rate TDD.

### 7.2.4.2 Physical characteristics of the beacon function

The physical channels providing the beacon function:

- are transmitted with reference power;
- are transmitted without beamforming
- use midamble  $m^{(1)}$  exclusively in this time slot when P-CCPCH provide the beacon function

[Explanation difference:]

In high chip rate TDD, a beacon function has to be defined for channels other than the P-CCPCH, because there are two cases of synchronisation and the possibility of multiframes for the P-CCPCH.

In the low chip rate option, only the P-CCPCH and the DwPTS provide the beacon function.

## 7.2.5 Midamble Allocation for Physical Channels

'Common with the high chip rate TDD mode'



## 7.3 Mapping of transport channels to physical channels

[Description:]

This clause describes the way in which transport channels are mapped onto physical resources.

[Rational:]

Transport channels	Physical channels
DCH	Dedicated Physical Channel (DPCH)
BCH	Primary Common Control Physical Channels (P-CCPCH)
PCH	Primary Common Control Physical Channels (P-CCPCH) Secondary Common Control Physical Channels(S-CCPCH)
FACH	Primary Common Control Physical Channels (P-CCPCH) Secondary Common Control Physical Channels(S-CCPCH)
RACH	Physical Random Access Channel (PRACH)
USCH	Physical Uplink Shared Channel (PUSCH)
DSCH	Physical Downlink Shared Channel (PDSCH)
	Down link Pilot Time Slot (DwPTS)
	Up link Pilot Time Slot (UpPTS)
	FPACH

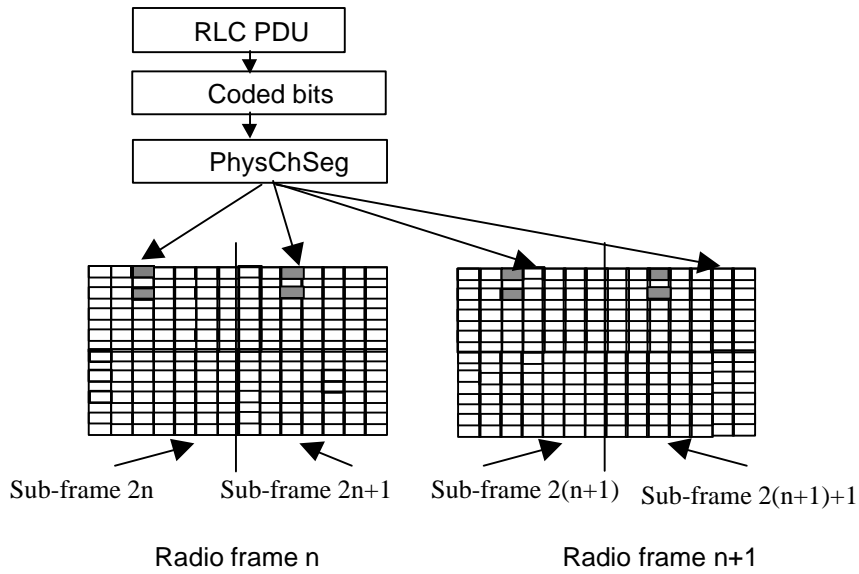
*Transport channel to physical channel mapping*

[Explanation difference:]

The PCH and FACH can be mapped on P-CCPCHs and S-CCPCHs in low chip rate TDD option and the BCH will only mapped into P-CCPCHs. The dedicated physical channel of DwPTS and UpPTS are used for downlink and uplink pilot. The physical channel FPACH is used to answer the UE and to adjust the timing and synchronization shift of the UE. These three channels are used for synchronization operation. For a detailed description, see subclause 7.3.2 of 25.928.

### 7.3.1 Dedicated Transport Channels

*Figure : Mapping of PDU onto the physical bearer( TTI= 20ms )*



[Description:]

The figure shows the mapping of PDU onto physical bearer.

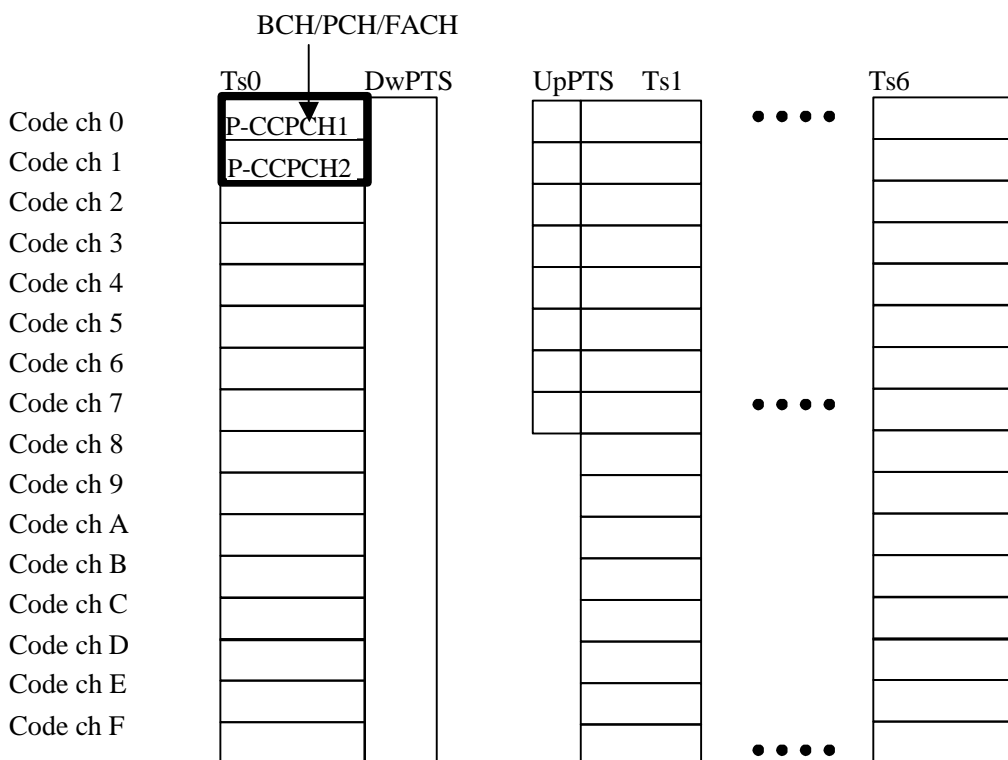
[Explanation difference:]

The mapping of PDU into dedicated channel is different from that of high chip rate TDD option according to the different frame structure. See separate sections (clause 8.1.11) for further explanation of the segmentation into sub-frames.

### 7.3.2 Common Transport Channels

[Description:]

The following figure shows the mapping of BCH, FACH and PCH transport channels onto the P-



CCPCHs :

Figure Transport channels mapping onto the physical channels

In low chip rate option, There are two P-CCPCH, P-CCPCH 1 and P-CCPCH 2 which are mapped onto i channelisation codes 0 and 1 (spreading factor 16) A cell should always contain P-CCPCH 1 and P-CCPCH 2 The transport channels mapped onto the P-CCPCH shall effectively be mapped onto P-CCPCH 1 and P-CCPCH 2 using the multi-code function in the channel coding and multiplexing (See physical channel segmentation in 25.222). As far as the SCCPCH is concerned, two cases can be considered. Either there are as well two SCCPCH, S-CCPCH 1 and SCCPCH 2 mapped onto two codes of spreading factor 16 or there is a single SCCPCH corresponding to a single code of spreading factor 8. The SCCPCHs may be mapped on any DL time slot. (as show in the figure above). More details are giving as following:

The BCH is mapped on a pre-defined number of RUs/physical channels, so that the UE can unambiguously decode it. As it is for the TDD high chip rate option and for FDD mode, the low chip rate option as well foresees for one P-CCPCH only. On the combined P-CCPCH1+P-CCPCH2, different logical channels can be mapped according to the multi-frame structure.

[Rational:]

### 7.3.2.1 The Broadcast Channel (BCH)

The BCH is always mapped on the P-CCPCH1+P-CCPCH2. Due to the adoption of smart antenna, in order to provide the coverage of the whole cell, the P-CCPCHs must have in general higher transmission power level with omni-directional or sectorial pattern (without adaptive beamforming) compared with the other physical channels which can be adaptively beamformed. The BCH is time multiplexed with other channels in the multi-frame.

The UE can find the beginning of each block which is delivered on the P-CCPCHs; that is the beginning of the interleaving period, through the DwPTS sequence and its relative phase with respect to the P-CCPCHs midamble sequences. Each DwPTS can have 4 different phases and can be independently assigned by the

Node B. Several continues different phase DwPTSs's combination can indicate the BCH's position in the multi-frame and the start position of the interleaving period. Also the beginning of the control multiframe can be detected from phase relations. To ensure correct decisions, an additional bit coded together with a BCH block, allows the UE to know the BCH interleaving block in P-CCPCHs.

### 7.3.2.2 The Paging Channel (PCH)

The PCH is a special broadcast channel used to page UEs from RNC. As mentioned above, it can also be mapped onto the P-CCPCHs time multiplexed with the BCH, FACH( see figure above) , and, therefore, transmitted with the same power level and antenna pattern as those of the BCH. PCH, FACH and BCH will occupy their own blocks in the multi-frame structure. And this is the preferred way, in some condition, the PCH can be mapped onto a different physical channel (S-CCPCH or SCCPCH1+SCCPCH2, on any DL time slot but not on the codes used for the P-CCPCHs.) , the location of PCH is indicated on the BCH.( This gives more flexibility to the system.)

### 7.3.2.2 The Forward Channel (FACH)

The FACH is used to carry control information to a mobile station when the system knows the location cell of the mobile station. The FACH may also carry short user packets. The FACH can be mapped onto the P-CCPCHs time multiplexed with the BCH and PCH, and, therefore, transmitted with the same power level and antenna pattern as those of the BCH. PCH, FACH and BCH will occupy their own blocks in the multi-frame structure. And this is the preferred way, in some condition, the FACH can be mapped onto a different physical channel (S-CCPCH or SCCPCH1+SCCPCH2 , on any DL time slot but not on the codes used for the P-CCPCHs.) , the location of FACH is indicated on the BCH.( This gives more flexibility to the system.)

[Explanation difference:]

In high chip rate option, the BCH is always mapped onto P-CCPCH and the PCH/FACH onto the S-CCPCH. The P-CCPCH always contains only the BCH . The secondary SCH indicates in which timeslot a mobile can find the PCCPCH containing BCH. And the location of PCH is indicated on the BCH.

In low chip rate option, the BCH is mapped only onto the P-CCPCHs (Primary Common Control Physical CHannel). The P-CCPCHs can also contain the PCH and FACH as well as the BCH. The P-CCPCHs are mapped onto the DL time slot preceding the DwPTS using two codes of that time slot (as shown in the figure 1) as described above. According the frame structure, P-CCPCHs carrying the BCH is followed by DwPTS, so when the UE detects the SYNC word, it can immediately find the BCH.

### 7.3.2.3 The Random Access Channel (RACH)

[Description:]

The RACH is mapped onto the P-RACH physical channel. The P-RACH configuration (time slot number and assigned spreading codes) is broadcast through the BCH information.

[Rationale:]

The RACH is mapped onto the P-RACH physical channel. The P-RACH can be configured by the network operator.

The P-RACHs can use either any spreading factor 16 RU or any spreading factor 8 RU in any UL time slot of the sub-frame. The spreading codes and time slots assigned to the P-RACHs are broadcast by the cell from the BCH. The capability of mapping RACH onto any UL time slot offers more flexibility to the system. The interference handling is then configurable. As the RACH is different from the other traffic it may be advantageous to distribute the RACH resources on several time slots.

The uplink sync codes (SYNC1 sequences) used by the UEs for UL synchronisation have a well known association to the P-RACHs, as broadcast by the BCH.

On the P-RACH, both power control and uplink synchronisation control is used.

The burst type used on the P-RACH is the same as for a traffic channel.

[Explanation difference:]

In low chip rate TDD option the random access procedure has two-step approach. The PRACH uses the close loop power control algorithm which is similar with the traffic channel..

In high chip rate TDD option the PRACH uses open loop power control. The details of the employed open loop power control algorithm may be different from the corresponding algorithm on other channels.

In low chip rate TDD option the burst type used on the P-RACH is the same as for a traffic channel while in high chip rate TDD option the burst type of the PRACH is a little different from the traffic channel.

### 7.3.2.4 The Uplink Shared Channel (USCH)

'Common with the high chip rate TDD mode'

### 7.3.2.5 The Downlink Shared Channel (DSCH)

'Common with the high chip rate TDD mode'

## Annex A (Normative): Basic Midamble Codes

### A.1 Basic Midamble Codes for Burst Type 1 and PRACH Burst Type

### A.2 Basic Midamble Codes for Burst Type 2

### A.3 Association between Midambles and Channelisation Codes

The following mapping schemes apply for the association between midambles and channelisation codes if no midamble is allocated by higher layers. These associations apply both for UL and DL.

#### A.3.1 Association for K=16 Midambles

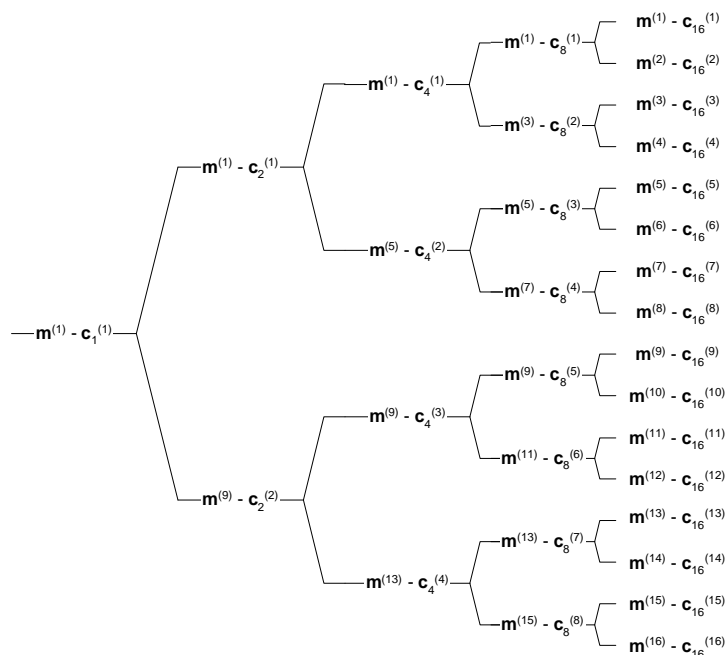


Figure A-1: Association of Midambles to Spreading Codes for K=16

A.3.2 Association for K=8 Midambles

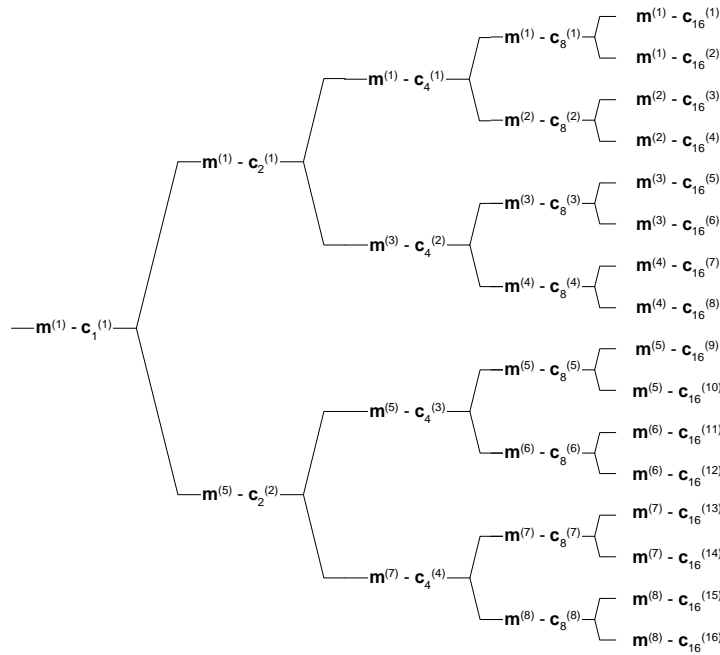


Figure A-2: Association of Midambles to Spreading Codes for K=8

A.3.3 Association for K=4 Midambles

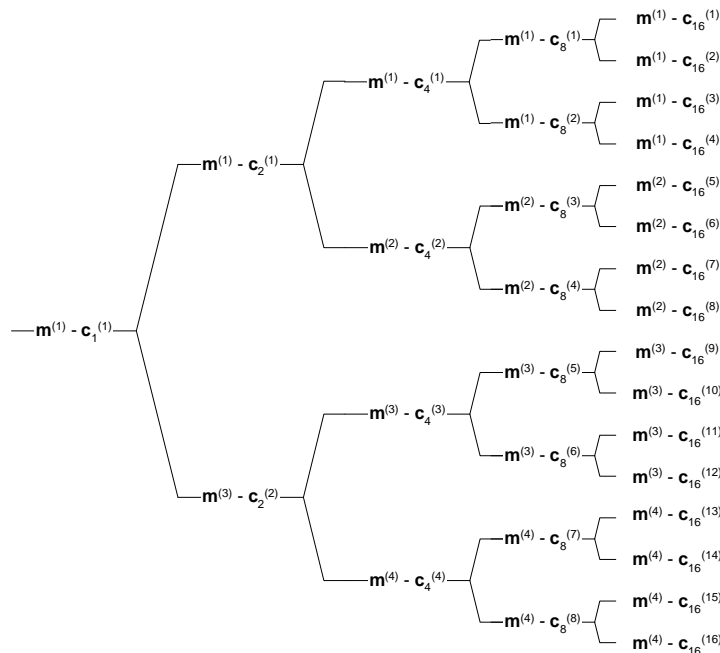


Figure A-3: Association of Midambles to Spreading Codes for K=4

A.3.4 Association for K=2 Midambles

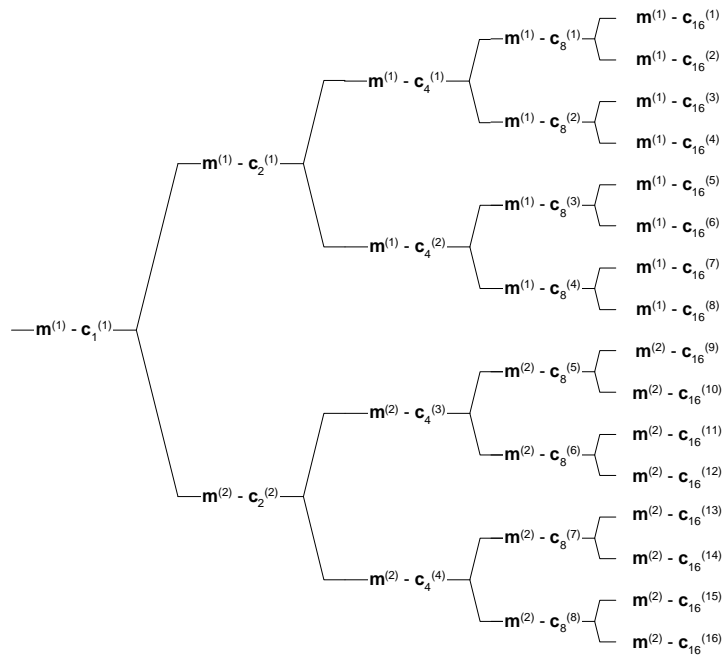


Figure A-4: Association of Midambles to Spreading Codes for K=2

A.3.5 Association for K=14 Midambles

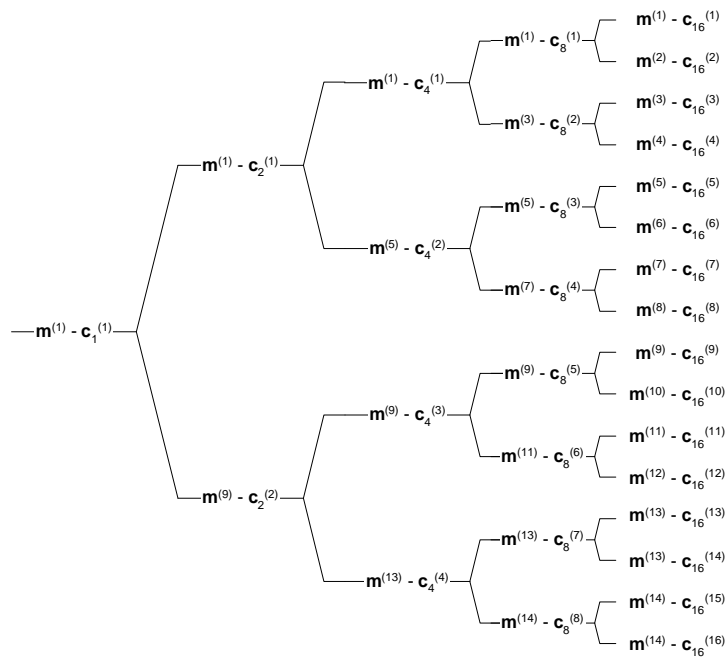


Figure A-5: Association of Midambles to Spreading Codes for K=14

A.3.6 Association for K=12 Midambles

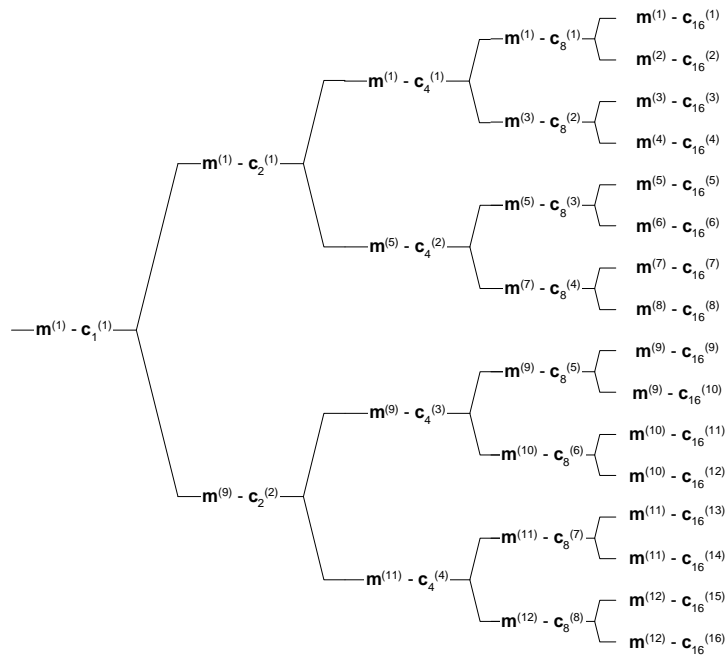


Figure A-6: Association of Midambles to Spreading Codes for K=12

A.3.7 Association for K=10 Midambles

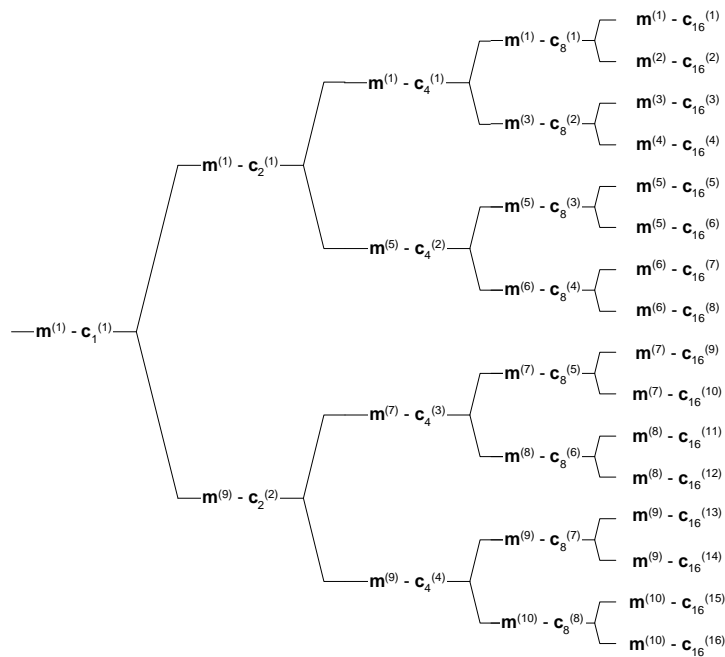


Figure A-7: Association of Midambles to Spreading Codes for K=10

A.3.8 Association for K=6 Midambles



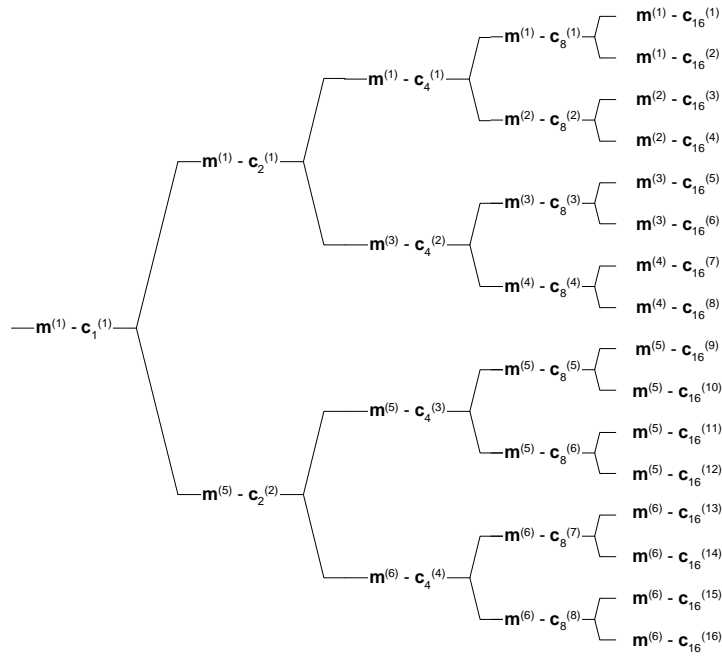


Figure A-8: Association of Midambles to Spreading Codes for K=6

## Annex B (Informative): CCPCH Multiframe Structure

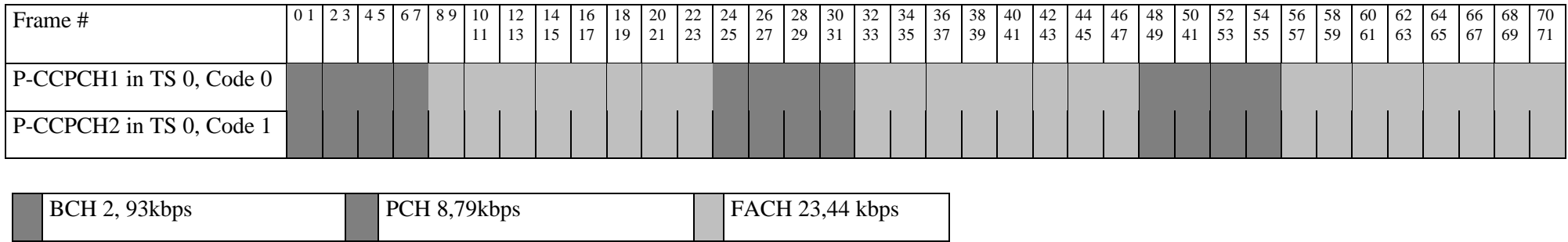


Figure B.1: Example for a multiframe structure for P-CCPCHs that is repeated every 72th frame (144 sub-frame)

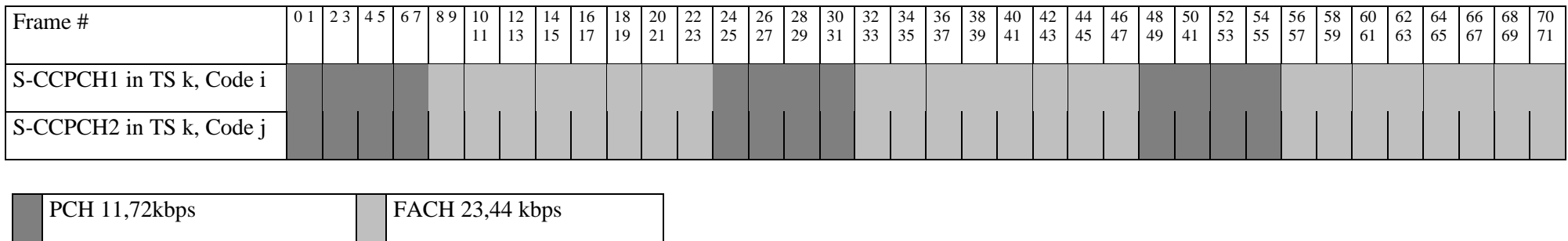


Figure B.2: Example for a multiframe structure for S-CCPCHs that is repeated every 72th frame, I,j=1...16 (144 sub-frame)

The two codes at SF 16 which define the two P-(S)CCPCHs, are jointly used to deliver the same higher layer message! this means that it not possible to send contemporarily two different messages (e.g. BCH and PCH) onto the two different codes of the P-(S)CCPCH

## 8 Multiplexing and channel coding

### 8.1 Transport channel coding/multiplexing

#### 8.1.1 Error detection

'Common with the high chip rate TDD mode'

#### 8.1.2 Transport block concatenation and code block segmentation

'Common with the high chip rate TDD mode'

#### 8.1.3 Channel coding

[Description:]

Usage of coding scheme and coding rate for the different types of TrCH is shown in table 1. In low chip rate TDD option, the coding scheme and coding rate of most type of TrCH are common with the high chip rate TDD.. Only BCH/PCH is a little different , it is mapped onto two code channels of the DL time slot. Rate 1/3 Convolutional coding is used for BCH and PCH.

[Rational:]

Usage of coding scheme and coding rate for the different types of TrCH is shown in table below. In low chip rate TDD option, BCH/PCH is mapped onto two physical channels of the DL time slot. If the usage of coding scheme and coding rate is 1/2 Convolutional coding, repeating as rate matching would be needed. So, it is used 1/3 Conv. coding as the coding scheme, this will lead to a better performance.

*Table: Usage of channel coding scheme and coding rate*

Type of TrCH	Coding scheme	Coding rate
BCH, PCH	Convolutional coding	1/3
RACH	Convolutional coding	1/2
DCH, DSCH, FACH, USCH		
	Turbo coding	1/3
	No coding	

The coding scheme and coding rate of other TrCH are common with high chip rate TDD and the following subclauses can be mentioned as "common with high rate TDD":

##### 8.1.3.1 Convolutional Coding

##### 8.1.3.2 Turbo coding

##### 8.1.3.2.1 Turbo coder

##### 8.1.3.2.2 Trellis termination in turbo code

##### 8.1.3.2.3 Turbo code internal interleaver

[Explanation difference:]

In high chip rate option, the coding scheme and coding rate of BCH/PCH is 1/2 Conv. coding. While in the low chip rate option, it is used 1/3 Conv. coding as the coding scheme and coding rate of BCH and PCH in low chip rate TDD option.

#### 8.1.4 Radio frame size equalisation

'Common with the high chip rate TDD mode'

#### 8.1.5 1st interleaving

'Common with the high chip rate TDD mode'

#### 8.1.6 Radio frame segmentation

'Common with the high chip rate TDD mode'

#### 8.1.7 Sub-frame segmentation

[Description:]

In the low chip rate option the radio frame which has a duration of 10 ms is subdivided into 2 subframes of 5ms each. The basic operated unit is a subframe. The bit streams in CCTrCH are mapped onto code channels of time slots in subframes. So, in low chip rate TDD option, it is needed to add the subframe segmentation unit between 2<sup>nd</sup> interleaving unit and physical channel mapping unit.

[Rational:]

In low chip rate option the radio frame which has a duration of 10 ms is subdivided into 2 subframes of 5ms each. The basic operated unit is a subframe. The bit streams in CCTrCH are mapped onto code channels of time slots in subframes. So, in low chip rate TDD option, it is needed to add subframe segmentation unit between 2<sup>nd</sup> interleaving unit and physical channel mapping unit. The operation of rate-matching guarantees that the bit streams is a even number and can be subdivided into 2 subframes. The transport channel multiplexing structure for uplink and downlink is shown in figure below.

The input bit sequence is denoted by  $x_{i1}, x_{i2}, x_{i3}, \dots, x_{iX_i}$  where  $i$  is the TrCH number and  $X_i$  is the number bits. The two output bit sequences per radio frame are denoted by  $y_{i,n_1}, y_{i,n_2}, y_{i,n_3}, \dots, y_{i,n_{Y_i}}$  where  $n_i$  is the subframe number in current radio frame and  $Y_i$  is the number of bits per radio frame for TrCH  $i$ . The output sequences are defined as follows:

$$y_{i,n,k} = x_{i,((n_i-1)Y_i)+k}, \quad n_i = 1 \text{ or } 2, \quad k = 1 \dots Y_i$$

where

$Y_i = (X_i / 2)$  is the number of bits per subframe,

$x_{ik}$  is the  $k^{\text{th}}$  bit of the input bit sequence and

$y_{i,n,k}$  is the  $k^{\text{th}}$  bit of the output bit sequence corresponding to the  $n^{\text{th}}$  subframe

The input bit sequence to the radio frame segmentation is denoted by  $v_{(t)1}, v_{(t)2}, \dots, v_{(t)U_{(t)}}$ ,  $x_{ik} = v_{(t)k}$  and  $X_i = U_{(t)}$ .

The output bit sequence corresponding subframe  $n_i$  is denoted by  $g_{p1}, g_{p2}, \dots, g_{pU_p}$ , where  $p$  is the PhCH number and  $U_p$  is the number of bits in one subframe for the respective PhCH. Hence,  $g_{pk} = y_{i,n,k}$  and  $U_p = Y_i$ .

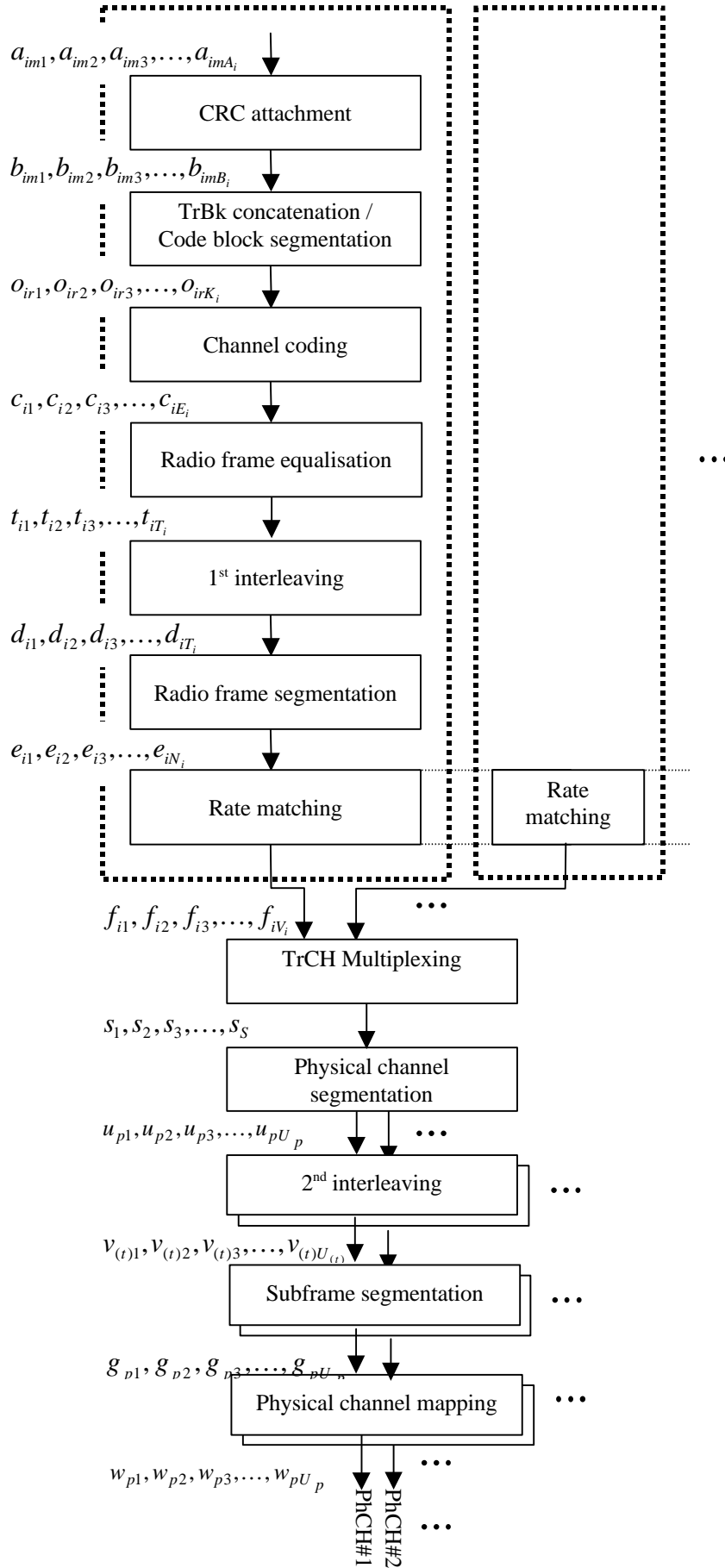


Figure : Transport channel multiplexing structure for uplink and downlink

[Explanation difference:]

In low chip rate option the radio frame which has a duration of 10 ms is subdivided into 2 subframes of 5ms each. The bit streams in CCTrCH are mapped onto code channels of time slots in subframes. So, in low chip rate TDD option, it is needed to add subframe segmentation unit between 2<sup>nd</sup> interleaving unit and physical channel mapping unit. While in high chip rate TDD option it is not included.

### 8.1.8 Rate matching

'Common with the high chip rate TDD mode'

### 8.1.9 TrCH multiplexing

'Common with the high chip rate TDD mode'

### 8.1.10 Physical channel segmentation

'Common with the high chip rate TDD mode'

### 8.1.11 2nd interleaving

'Common with the high chip rate TDD mode'

#### 8.1.11.1 Frame related 2nd interleaving

#### 8.1.11.2 Timeslot related 2<sup>nd</sup> interleaving

### 8.1.12 Physical channel mapping

[Description:]

In the low chip rate option the radio frame which has a duration of 10 ms is subdivided into 2 subframes of 5ms each. The basic operated unit is a subframe. So the bit streams from the subframe segmentation unit are mapped onto code channels of time slots in subframes in the low chip rate option.

[Rational:]

In the low chip rate option the radio frame which has a duration of 10 ms is subdivided into 2 subframes of 5ms each. The basic operated unit is a subframe. So the bit streams from the subframe segmentation unit are mapped onto code channels of time slots in subframes in the low chip rate option.

The PhCH for both uplink and downlink is defined in subclause 7.2. The bits after physical channel mapping are denoted by  $w_{p1}, w_{p2}, \dots, w_{pU_p}$ , where  $p$  is the PhCH number and  $U_p$  is the number of bits in one subframe for the respective PhCH. The bits  $w_{pk}$  are mapped to the PhCHs so that the bits for each PhCH are transmitted over the air in ascending order with respect to  $k$ .

The mapping of the bits  $g_{p1}, g_{p2}, \dots, g_{pU_p}$  is performed like block interleaving, writing the bits into columns, but a PhCH with an odd number is filled in forward order, were as a PhCH with an even number is filled in reverse order.

The mapping scheme, as described in the following subclause, shall be applied individually for each timeslot  $t$  used in the current subframe. Therefore, the bits  $g_{p1}, g_{p2}, \dots, g_{pU_p}$  are assigned to the bits of the physical channels  $w_{t1,1..U_{t1}}, w_{t2,1..U_{t2}}, \dots, w_{tP,1..U_{tP}}$  in each timeslot.

In uplink there are at most two codes allocated ( $P \leq 2$ ). If there is only one code, the same mapping as for downlink is applied. Denote SF1 and SF2 the spreading factors used for code 1 and 2, respectively. For the number of consecutive bits to assign per code  $bs_k$  the following rule is applied:

```

if
SF1 >= SF2 then  $bs_1 = 1$  ;  $bs_2 = SF1/SF2$  ;
else
SF2 > SF1 then  $bs_1 = SF2/SF1$ ;  $bs_2 = 1$  ;
end if

```

In the downlink case  $bs_p$  is 1 for all physical channels.

#### 8.1.12.1 Mapping scheme

Notation used in this subclause:

$P_t$ : number of physical channels for timeslot t ,  $P_t = 1..2$  for uplink ;  $P_t = 1...16$  for downlink

$U_{tp}$ : capacity in bits for the physical channel p in timeslot t

$U_t$ : total number of bits to be assigned for timeslot t

$bs_p$ : number of consecutive bits to assign per code

for downlink all  $bs_p = 1$

for uplink if SF1 >= SF2 then  $bs_1 = 1$  ;  $bs_2 = SF1/SF2$  ;

if SF2 > SF1 then  $bs_1 = SF2/SF1$ ;  $bs_2 = 1$  ;

$fb_p$ : number of already written bits for each code

pos: intermediate calculation variable

for p=1 to  $P_t$  -- reset number of already written bits for every physical channel

$fb_p = 0$

end for

p = 1 -- start with PhCH #1

for k=1 to  $U_t$

do while ( $fb_p == U_{tp}$ ) -- physical channel filled up already ?

p = ((p + 1) mod ( $P_t + 1$ )) + 1 ;

end do

if (p mod 2) == 0

pos =  $U_{tp} - fb_p$  -- reverse order

else

pos =  $fb_p + 1$  -- forward order

endif

$W_{tp,pos} = g_{t,k}$  -- assignment

$fb_p = fb_p + 1$  -- Increment number of already written bits

if  $(fb_p \bmod bs_p) == 0$  -- Conditional change to the next physical channel

$p = ((p + 1) \bmod (P_t + 1)) + 1;$

end if

end for

[Explanation difference:]

In the high chip rate TDD option, the bit streams from the 2<sup>nd</sup> interleaving unit are mapped onto code channels of timeslots in radio frames. While in the low chip rate option the radio frame which has a duration of 10 ms is subdivided into 2 subframes of 5ms each. The basic operated unit is a subframe. So the bit streams from the subframe segmentation unit are mapped onto code channels of time slots in subframes in the low chip rate option.

### 8.1.13 Multiplexing of different transport channels onto one CCTrCH, and mapping of one CCTrCH onto physical channels

'Common with the high chip rate TDD mode'

#### 8.1.13.1 Allowed CCTrCH combinations for one UE

8.1.13.1.1 Allowed CCTrCH combinations on the uplink

8.1.13.1.2 Allowed CCTrCH combinations on the downlink

### 8.1.14 Transport format detection

'Common with the high chip rate TDD mode'

## 8.2 Coding for layer 1 control

### 8.2.1 Coding of transport format combination indicator (TFCI)

[Description:]

Encoding of the TFCI bits depends on the number of them and the mode of modulation applied. When the modulation of QPSK is deployed, encoding of the TFCI bits is the same as it in the high chip rate option. When the modulation of 8PSK is applied, the encoding of the TFCI bits is a little different from it in high chip rate option.

[Rationale:]

Encoding of the TFCI bits depends on the number of them and the mode of modulation applied. When the modulation of QPSK is deployed, encoding of the TFCI bits is the same as it in the high chip rate option. That is to say, if there are 6-10 bits of TFCI, the TFCI bits are encoded using a (32,10) sub-code of the second order Reed-Muller code. If the number of TFCI bits is in the range 3 to 5, the TFCI bits are encoded using a (16, 5) bi-orthogonal (or first order Reed-Muller) code. If the number of TFCI bits is 1 or 2, then repetition will be used for coding. In this case each bit is repeated to a total of 4 times giving 4-bit transmission ( $N_{TFCI}=4$ ) for a single TFCI bit and 8-bit transmission ( $N_{TFCI}=8$ ) for 2 TFCI bits. When 8PSK service is transmitted, the modulation of 8PSK is applied in low chip rate option. In this case of 8PSK service, the odd bits of the encoded TFCI bits from the TFCI coder are repeated (e.g. the input is b0, b1, b2, b3, b4... the output will be b0, b1, b1, b2, b3, b3, b4...). Thus the amount of encoded bits of TFCI in this case will be 48, 24, 12, 6 respectively for the 6-10, 3-5, 2, 1 TFCI bits. The same TFCI lengths like in WB-TDD are supported (0, 4, 8, 16, 32).

Other TFCI coding scheme for 8PSK is also considered.



[Explanation difference:]

In high chip rate option, encoding of the TFCI bits depends on the number of them. 1-10 bits of TFCI are supported. Thus, the amount of encoded bits of TFCI is 32, 16, 8, 4 respectively for the 6-10, 3-5, 2, 1 TFCI bits.

In the low chip rate option, encoding of the TFCI bits depends on the number of them and the mode of modulation applied. When the modulation of QPSK is deployed, encoding of the TFCI bits is the same as it in the high chip rate option. In this case of 8PSK service, the odd bits of the encoded TFCI bits from the TFCI coder are repeated, thus the amount of encoded bits of TFCI in this case will be 48, 24, 12, 6 respectively for the 6-10, 3-5, 2, 1 of TFCI bits. The repetition of TFCI odd bits is necessary to guarantee the same number of symbols.

Note: Details of the TFCI coding with 8PSK are for further study and proposals are under consideration.

## 8.2.2 Coding of Synchronisation Shift

[Description:]

The SS command, one kind of L1 control signals, is an identifier sent in downlink, to instruct a timing adjustment each M frames. The length of the SS command is 1 symbol.

[Rational:]

The SS command is sent in every sub-frame (in case allocated). The command may be updated only after every M sub-frames. I. The coding of the SS command is shown in table below. M (1-8) and k (1-8) can be adjusted during call setup or readjusted during the call by higher layer.

*Table: Coding of the SS*

SS Bits	Meaning
11	Increase timing advance by $k/8 T_c$
00	Decrease timing advance by $k/8 T_c$

\* Note: other methods like e.g. definition of 'do nothing' are under consideration

In case of 8PSK service, the numbers of the SS bits is 3. The specific coding of SS for the case of 8PSK service is shown in table below.

*Table : Coding of the SS (special for in case of 8PSK)*

SS Bits	Meaning
111	Increase timing advance $k/8 T_c$
001	Decrease timing advance $k/8 T_c$

\* Note: other methods like e.g. definition of 'do nothing' are under consideration

[Explanation difference:]

In high chip rate TDD option, SS information is not transmitted as L1 signal on each frame. Because of uplink synchronisation in the low chip rate TDD option, SS information is transmitted, as one of L1 signals, once per 5ms subframe.

The SS command is an identifier sent in downlink, to instruct a timing adjustment each M frames. The length of the SS command is 1 symbol. The SS bits "11" mean increasing timing advance  $k/8 T_c$  and "00" mean decreasing the timing advance by  $k/8 T_c$ . The modulation of 8PSK is applied, e.g. in case of 2Mbps service. In this case, the numbers of the SS bits is 3. The specific coding of SS for the case of 8PSK service is shown in table above.

### 8.2.3 Coding of Transmit Power Control (TPC)

[Description:]

The TPC command, one kind of L1 control signals, is an identifier sent both in up- and downlink, to instruct a power level adjustment which is increase or decrease. The coding of the TPC command is shown.

[Rationale:]

The TPC command is an identifier sent both in up- and downlink, to instruct a power level adjustment which is increase or decrease. The length of the TPC command is one symbol. The coding of the TPC command is shown in table 1.

*Table: Coding of the TPC*

TPC	TPC Bits	Meaning
'Up'	11	Increase Tx Power
'Down'	00	Decrease Tx Power

\* Note: other methods like e.g. definition of 'do nothing' are under consideration

When 8PSK modulation is applied, the length of the coded TPC command remains one symbol and therefore the number of TPC Bits is 3. The specific coding of TPC for the case of 2Mbps service is shown in table 2.

*Table: Coding of the TPC (Special for 8PSK)*

TPC	TPC Bits	Meaning
'Up'	111	Increase TX power
'Down'	001	Decrease TX power

\* Note1: other methods like e.g. definition of 'do nothing' is under consideration

\* Note2: the TPC coding for 8PSK refer to 9.1.2

[Explanation difference:]

In high chip rate option, the TPC command is sent in uplink transmission only, to instruct the NodeB whether Tx power has to be increased or decreased. The length of the TPC command is one symbol.

In the low chip rate option, the TPC command is an identifier sent both in up- and downlink, to instruct a power level adjustment which is increase or decrease. When 8PSK modulation is applied the length of the coded TPC command remains one symbol and therefore the number of TPC Bits is 3. The specific coding of TPC for the case of 8PSK is shown in table above. Other methods like e.g. to define the command of 'do nothing' is under consideration.

### 8.2.4 Coding of the Paging Indicator

Common with the high chip rate TDD option

## 9 Spreading and Modulation

### 9.1 Data modulation

[Description:]

This document is described the difference of modulation and spreading in low chip rate TDD. The main difference is the mapping of bits onto signal point constellation, synchronization codes and code Allocation.

[Rational:]

#### 9.1.2 Mapping of bits onto signal point constellation

##### 9.1.2.1 QPSK modulation

'Common with high chip rate TDD'

##### 9.1.2.2 8PSK modulation

The data modulation is performed to the bits from the output of the physical channel mapping procedure for 8PSK service 3 consecutive binary bits to a complex valued data symbol. Each user burst has two data carrying parts, termed data blocks:

$$\underline{d}^{(k,i)} = (\underline{d}_1^{(k,i)}, \underline{d}_2^{(k,i)}, \dots, \underline{d}_{N_k}^{(k,i)})^T \quad i = 1, 2; k = 1, \dots, K. \quad (1)$$

$N_k$  is the number of symbols per data field for the user  $k$ . This number is linked to the spreading factor  $Q_k$ .

Data block  $\underline{d}^{(k,1)}$  is transmitted before the midamble and data block  $\underline{d}^{(k,2)}$  after the midamble. Each of the  $N_k$  data symbols  $\underline{d}_n^{(k,i)}$ ;  $i=1, 2$ ;  $k=1, \dots, K$ ;  $n=1, \dots, N_k$ ; of equation 1 has the symbol duration  $T_s^{(k)} = Q_k \cdot T_c$  as already given.

The data modulation is 8PSK, thus the data symbols  $\underline{d}_n^{(k,i)}$  are generated from 3 consecutive data bits from the output of the physical channel mapping procedure:

using the following mapping to complex symbols:

Consecutive binary bit pattern	complex symbol
$b_{1n}^{(k,i)} b_{2n}^{(k,i)} b_{3n}^{(k,i)}$	$\underline{d}_n^{(k,i)}$
000	$\text{Cos}(11\pi/8) + \text{sin}(11\pi/8)$
001	$\text{Cos}(9\pi/8) + \text{sin}(9\pi/8)$
010	$\text{Cos}(5\pi/8) + \text{sin}(5\pi/8)$
011	$\text{Cos}(7\pi/8) + \text{sin}(7\pi/8)j$
100	$\text{Cos}(13\pi/8) + \text{sin}(13\pi/8)$
101	$\text{Cos}(15\pi/8) + \text{sin}(15\pi/8)$

110	$\text{Cos}(3\pi/8)+\sin(3\pi/8)1$
111	$\text{Cos}(\pi/8)+\sin(\pi/8)$

The mapping corresponds to a 8PSK modulation of the interleaved and encoded data bits  $b_{l,n}^{(k,i)}$  of the table above and  $d_n^{(k,i)}$  of equation 1.

The use of shifted 8PSK is under consideration.

### 9.1.3 Symbol rate

'Common with the high chip rate TDD mode'

## 9.2 Spreading modulation

### 9.2.1 Basic spreading parameters

'Common with the high chip rate TDD mode'

### 9.2.2 Spreading codes

'Common with the high chip rate TDD mode'

### 9.2.3 Scrambling codes

'Common with the high chip rate TDD mode'

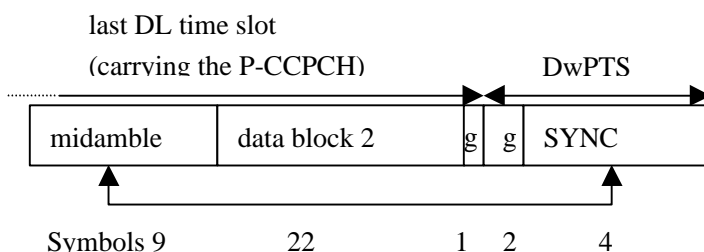
### 9.2.4 Spread and scrambled signal of data symbols and data blocks

'Common with the high chip rate TDD mode'

## 9.3 Synchronisation codes

*DwPTS code*

The DwPTS is composed of 64 chips (4 symbols) of SYNC and 32 chips (2 symbols) of guard period as



**31.5 symbols (393.75 μs)**

shown in Figure below. SYNC code is not scrambled.

Figure : The frame structure around DwPTS

The phase of the whole DwPTS is used to signal the P-CCPCH multi-frame. As QPSK is used for the modulation of the DwPTS, the phases 45, 135, 225, 315° is used to signal. Indication of starting point of the phase quadruple and the position of the BCH is realised by means of direct signalling. In this method the phase of 45 ° is reserved for the beginning of each phase quadruple. For the other sub-frames of the phase quadruple, the phase 135 °, 225 ° and 315 ° are used only to detect the position of the BCH as shown Table 1.

The sequence of the phases is chosen, that the position of the BCH can also be detected by using differential demodulation of the consecutive phases of the DwPTS.

Table Sequence for the phase modulation for the DwPTS

Phase quadruple	# 225	(SFN/2) mod 8
45, 225, 225, 225	3	0 (the BCH should be here)
45, 135, 135, 225	1	1
45, 135, 225, 135	1	2
45, 315, 225, 315	1	3
45, 225, 135, 315	1	4
45, 225, 315, 315	1	5
45, 225, 225, 135	2	6
45, 225, 225, 315	2	7
Others	-	Error

There should be 32 different SYNC codes (see Table A) for the whole system. That the (SFN/2) mod 8= 0 is always used for BCH. Other position can also be configured to transmit the BCH.

*UpPTS code*

Synchronisation sequences for the UpPTS (SYNC1)

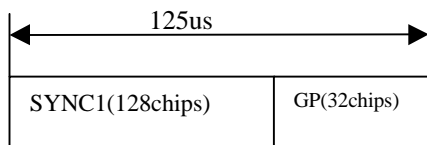
SYNC1 code is not scrambled.

The time slot is composed of 128chips of SYNC1 and 32chips of GP as shown in Figure 2.

There should be 256 different SYNC1 codes (see Table B) for the whole system.

Figure Burst structure of UpPTS

The possible restriction to the network planning from parameter grouping is to be verified.



Code Allocation

Relationship between the SYNC and SYNC1 sequences, the scrambling codes and the midamble codes

Code Group	Associated Codes			
	SYNC ID	SYNC1 ID (coding criteria)	Scrambling Code ID (coding criteria)	Basic Midamble Code ID (coding criteria)
Group 1	0	0~7 (000~111)	0 (00)	0 (00)
			1 (01)	1 (01)
			2 (10)	2 (10)
			3 (11)	3 (11)
Group 2	1	8~15 (000~111)	4 (00)	4 (00)
			5 (01)	5 (01)
			6 (10)	6 (10)
			7 (11)	7 (11)
.				
.				
.				
Group 32	31	248~255 (000~111)	124 (00)	124 (00)
			125 (01)	125 (01)
			126 (10)	126 (10)
			127 (11)	127 (11)

Table A

SYNC Codes

Code ID	SYNC Codes of length 64
0	B3A7CC05A98688E4
1	9D559BD290606791
2	2CE7BA12A017C3A2
3	34511D20672F4712

4	9A772841474603F2
5	9109B1A5CE01F228
6	8FD429B3594501C0
7	25251354AA3F8C19
8	C9A3B8E0C043EA56
9	BA04B888E5BC1802
10	A735354299370207
11	74C3C8DA4415AE51
12	F4FD0458A0124663
13	A011D4E16C3D6064
14	BDA0661B0CAA8C68
15	8E31123F28928698
16	F095C1632E2906AB
17	B60B4A8A664071CF
18	AA094DCCE91E041A
19	C0C31CDA8A256807
20	D516964FB18C1890
21	30DE01834F4AACCE
22	8F700323BA5CAD34
23	1B50F4DEE0C1380C
24	443382164F56F2D1
25	E1E4005D49B846B4
26	040A97165330BFAA
27	C48E26881693AD78
28	D4354B2FE02361CC
29	5383AB6C8A10CE84
30	D417A730F2F12244
31	ABF0A0D905A939C4

Table B

SYNC1 Codes

Code ID	SYNC1 Codes of length 128
0	C11C20F0D1807DB8859175B798EC094A
1	91278068081EC8E74543DBC1C9AD4235
2	38F5AEE2E513DB12A663BA04160103E5
3	7AA8A0A210F12A1E4332F2EDD33011FC
4	C180EA3B9BA1774EB9611BD249C4A508
5	B072A2C839489D496B98CE9D0132FBC9
6	B2723EAC6EB01667F2B33961C8074234
7	C4144AD060F0EC095E227B92CF7C8280
8	653036A10D3054146FCF815986C63A14
9	F899CA61435D64DC07FDF04C4A0C053A
10	B56F2D6893A8051407F4C341D88DC7DC
11	DC0BE838242142EDE6413A72C88D74AA
12	22A2FD86E4086C70A4860B13C76E579F
13	A3CBC21322C97D2A02728E7875F39588
14	D4EC4F694A082CB38E3B1558A0FCC89F
15	CC891141C4E216D235C15CF5D3F9B002
16	A1993114C50B77CB0C0725D1E22FD016
17	24F73A979DE52F82E8800CCB93842A59
18	8F878FA04659842E294D8DEAB20BA2FD
19	AC90B0442D70662B028CF76A6BECDF09
20	D94A284DF64D7B0102F0E084C29C88C8
21	8603200C7596F24E865FD3815693358D
22	B466B12CF433642BD8B08F1F452E0550
23	86A3A1772C1C99FCA7DBBA0C312E34A0
24	622A1889F72A9A2C042D46F08EFEE1AC
25	BF220A362BC0D3B0D7CE400954C6CFAE
26	D28D73C52E89CF57905C502244F63616
27	AD4E1C2103697D64D8B9D4C035D90548
28	8F081A9BA12B6C6BD024531AA984D21C
29	E4092429BE82988E1E3585BF6A6AE550
30	08BD36E0A9C061782CB38B35B335CA56



31	1CDFF3CC2685D1C44F4A1059AB03F40A
32	506ED4E88FB1CECE3243F2A27A0221A4
33	846CF58A7AB613C83A24130B5778C0E2
34	A2711A99E26A0C75AC026F4CFAECE893
35	D846EEEBA2432AC05A01043C62579DCF
36	6B16B4E851CAF2121FC4CF88820C89E7
37	AA4889A78207674A74E10C6F2BE11D48
38	8534CF8145BC991052814ED5C72709EE
39	01AEF15D2290A84A607425746D9963C7
40	999188F758245D5164FE16D852942C71
41	CF71C008599287E446E30745BD56E2D2
42	248414BA0DF8CDC4711FE7C8707ED0AD
43	EB2E263EC016191C81AB714BFE4D2B30
44	862082A7482FAC1C499793A0D8CED670
45	DE2C22B2783AB75A7342608DE413840A
46	E31AA60B727F2CA2A78DAAC10665011D
47	CEF6CD06509870AC9E0177ACD550921D
48	E52C84D499FFCDC287581691471540F2
49	B33BF6551A4322504BEE0930BCA1EC68
50	555BE6886D0FC43D72315E6C6D384148
51	8444F67451EE23CE1240C90F0B52A492
52	5C290D28E84060E69D09788A261B10FF
53	337E0C35E83CD38CCC5D45804241F952
54	A7879F0D31A8982A01EE6AC4952984DC
55	A37F506508928C70A83D69A2373781B9
56	42F55208EE12909803A7CBEB19B5419E
57	57E5E268A328FCC9ED04B9E5420AC702
58	EB033AD1222F84D8642C4E3FAAD28206
59	98EE1415F026AC0E862C520451697DD0
60	6A0528AEA4B7CD6702660D81F8821E19
61	763D626A87C603BCB09E1A4C800A378F
62	EEA61897879289340C23F669D6A03762
63	A6571B3CC2D0E04F017ACC808B92DCE7

64	DDF88B52EA1831D293A803CF23C8C471
65	6CA4D333A2684140475DAB491F61C17A
66	A7D2AD23043989A13289F7C3E135580A
67	B1C752FA66B41C81904EDE27EA000E2E
68	8694BE3CC1CB36BE2A095F89CC619080
69	9C20334E1BBC596B25E151180BF99940
70	484256214F81070DD9C49A2B05A43DCE
71	401A20BCBE29B7438A7AEE44635A9E23
72	8858585C3239CBF628033FA0DF189378
73	EFA36404C1BA5118CC5F9052FD28D9C3
74	155609873D8A042D496E6477B747C4F8
75	8446077883A6D7D2549CC9742E3FD023
76	E630142B189AA209371A6F0FFDBC30A7
77	C46060535AC6DBB2095F1D7826D0CD5C
78	E00D19E48797148B28DEDA9D429362E2
79	645DE447E938485489416CAFCC1C571F
80	DA10AFBF2AE61C593A1D88584DE30598
81	BB248AEA5FD3FE210CD48FC401E1A686
82	A89F146BD9191F445301C081CB6F5625
83	15BBF04F247C59150208949EB6B9CC58
84	08F48BFA7804B5B2CC2E96510232E062
85	9AA2BE74005A3679C626B209580B8D03
86	9D40664A2C808F2F293E255398B37E6A
87	6869C98A8AAD81CAE41A23C83FF9EEA0
88	576E8948E61BD0927C4140C3C04C4CF3
89	0F942C67A1137B6EAA058C2A74872C73
90	9D058E27ED546C10632684BBC84E5BC1
91	79D4B840E20148B134F90B51164BCBD0
92	0E35E1D8D1214C05FAC790B69B239150
93	FFA1BB0232CD71480BE5CA1C2A269F89
94	B2956F5F4E270446F9211584792628DB
95	F56CCA23421C8EC8F8A41F7DA4A41EA2
96	0B5ECA04F1789A7148C80C39D57D05F6

97	A10B538E8A8CFC8F8925C485F2A88660
98	9925C2C715001D9FC78ACCC51DA1AF34
99	0DAC9CFDEA40429A8B12C7D320D60F70
100	377FC9A097017958440914E83118E39D
101	8421096FA8B47E4E943B6473671955CC
102	574086183477C4F68540CB7E858263B1
103	895B6A8980C6703C779F49F40C5CFC19
104	D0D253E157BC19262150CEA668679E71
105	B8889C60EBA812BD7F0B6498823296D2
106	A13FB9F3A08528E44B13C12CF0D461AA
107	8D4DCFB E43D6E2024B1F8470224AA330
108	536D159E119E0893838657B12A074E64
109	DCFD49C504AD3A2F049A0CB70238EC8A
110	D363DB4C46C11757FA8FB18139789102
111	424A1E8A1D4DA256E4CA3BC8C2201BE3
112	417B619ED30FEB0A847CC3A191A20398
113	843FBBC95453C61786D1332612B45B4D
114	F26CACC0732CF8ED0C5BC1462B1620B4
115	88E0FE440C70E9249A92A7AF94638880
116	99A52B7D8C950308057E0661D7459960
117	A5C28218BF5D16E63E42698A0A6B0896
118	B2763BEEC784A12E8C50778536921806
119	987B2B6A3A77A059B30A082457AB84E0
120	820DB500F1B206358D7A7F210AB85AA8
121	97760A5CFC5E03EB439C914590045938
122	896A720E8857C8708A59F8C94DE0841E
123	2D101F0CF95263843412577340DEBB11
124	E8E5214B4DCF5D11A245B0149D49C87C
125	51224EAA10099ACDE384834A5ADF03D8
126	64E51253554A230C186FDE4E8781BC09
127	A499E391E69ED08890AC1A82A6115BEC
128	EE54C6E1834210D3EC1B07A456B92AA8
129	949DB5CA82420B54C1E0BCC111E704D9

130	9439EE9A9E4C447D1AA350926495047F
131	AD095CC0E7438AECE38D60980B3F2D00
132	83089C254C5EE9788072BC3D9282F798
133	A27DC1A457BC5A56563D8A9B11203615
134	713053A9C0B1B08B14705FF5A7244DB4
135	D36D4B9F4007354E0EC1B0CA8C8C7124
136	82E7C990612114F1CCE1BD9509FD4386
137	C8D83FF0B48B14830D2015D53F8C0672
138	08AF223C869A36B169148FDDABB7D120
139	B6C284C600AD0A99F86C449F8F4C53A6
140	DC741B320C07682AF92AC4DBDE0C28C2
141	89B8D84FA902265850C0FA6FF0EB2C4F
142	A69445B3A52201DB984BC03D1956D7F3
143	0FE0F7224B7AD72E4D4530D0223F590C
144	1B8C06F051434048EB925133AD3BD3F9
145	E133D4C3C942726A351300C37E55D0DF
146	9E09481D1881A66F562D8B453BC83AB2
147	2397B04B60A3C5700907BDBBA4E818C8
148	8F81F7A08CC6C8DA3D692AD34F50C012
149	9AB325352981BCCFA072F8FDE3009221
150	4FA88B7F1F8A620C31B0D486C52AC2F6
151	097AF0ADD16D7D39851049F0130EE444
152	A5027732DACFF11C388D5820A4A9BA49
153	1CD981EA2EDB46218A407C7E20D4BE84
154	D0FD94279FA67EC61A3904C0AD8ACA04
155	EA73A9415EC2004D49E9D0F645961C75
156	005AF0614A7552041194DEECBF8DD016
157	B514481533DA0A731705B93CF634E40D
158	983054521841A6E4FF34B2C07B5684FE
159	C46D927D0FD2B2F509550025677C6871
160	2AD85C08127487C87ECE014D65169102
161	0F617852FA3930AA7EE74B400B2CC831
162	AE9D395004C6E27540C378625D36E0D6

163	DC4FA55750F10B0636248F12C212FFE4
164	D3602B8D6CBF1809C88B827185631ECF
165	A94825850708E7723EA8F22C44BF78B2
166	A62D231C16AEEFE0B0026B306662945A
167	9C7BE810A86465A50551F89125D93B12
168	9712D9338B9CC60485C10172F50F121F
169	A3902CE0E0B9912591FF28C695728257
170	4167057891AB29473A9E0F67F3658921
171	B3368B91EC12A284BC414C8F0D7F8D20
172	EE21888101ABF06C1175828CB58B598D
173	E43923A00ECC32CCC2D162A4A44BD7F4
174	CC9E30B8538AD51703EEB6F70801AB22
175	B908AD2F1501DA1C156811736CD798CD
176	2B46302ACCC2F808797FC648A614326D
177	8A54494F1BE27235B8764023AA0FBCFA
178	BC1041E6F636421E89277DC154439103
179	275B39A63029B974E3561AE0A8FC8032
180	9283F6FE819B80492A22B85CE5CE5DC4
181	4CCB52C0CE058A78022C22DF5788CBCC
182	B0DF9608DE549A6F6C581516919A81E6
183	2CA185163CC36060D1E85BB0A7FBB988
184	66101D2846155CAC986FC790D2124EFC
185	8016E3904644D2093579B83BD7AB5071
186	531CAB7085BEC14257439658023647CF
187	DF2910165AA5051E41F6EB198E4D491C
188	BA32052042B0FB2188DE7857DA1B6788
189	9E6D075AFF0EA4153615E140BF380666
190	9ACC5A037902534642A3BE391AA40F9B
191	4D741A3B4499843010D7E5FA8988DC80
192	FA1421C96EDC6092726154560B1C2FC8
193	882946076223CAE0B0BFE3EDA59826D5
194	CEBB288C28B7472A0D3917012276C034
195	BD35A6E00C9528DB38289CF823C34F30

196	E2C93618B6B2800D51171A5F85746A55
197	B43EF39A1A64F0E220AF740F9494291B
198	AC537817C2612744A58132A8AFBC44A3
199	98A321249A821DDBF81C38235A371A14
200	AE1D46069090D81BB6B08FED9E687285
201	7EAE2415DC2CD60AE083249A33B56E05
202	3D942AAA9BC9F27289421CE0B301FB98
203	1548BA6D08530727AC6D059C005C6C42
204	FF47C21142C65B502DA70647BAE831D1
205	C83AA7FEAC5E51A08091E10DB0C233D9
206	E86EDD2EC2DAA3104229EDC43471A16A
207	22FAFB9C184B78B56EE91B6602C03244
208	E45631DC509B1290C08D2C1A1F15DBFE
209	D203C51207092B56568FDAD9E2D44473
210	2AA87F31A7D1AB1C90024F936006C4A5
211	913136153593DEABC7305BF0C5A62180
212	D8DA5FE401F2758642A082C53A6A5CB8
213	23C2295213147F324DE8EC1C103BAE88
214	883AF097FCDE82B366A1844245E0D727
215	79E5E9F8C933159ACADC22A06F900A70
216	FE40502B44A9E44B2C336250D47538CC
217	670452E19172C843176F1278FE41D584
218	B7EAA436078E6886A3024F593AD57580
219	1044D4CDD7230E7B1953AD1232DF07E2
220	4D821ECAC3D845A2E1011695624576FF
221	96622ED2FBD44D1B859D70601999F438
222	CCC31C3D6D5B41B8D82FF4522A4C0146
223	4A84F7CD62E0C712980E6A0C89BF394F
224	10E56751F000927284DBE174E68ECC4C
225	A3DE70921356F026E084CFE302A210A9
226	B12DA0621B343A8C3FE941A32EA5D571
227	D653135DE825A74B743E275C19020C71
228	5CAD301BF846B2EE921D33A3D4BB1220

229	1292445ACBB548C668FC3853578474E6
230	B94B4B89C0654688C9E007D9061DF5FE
231	75A2C91E76061A8680884E8BFD14A64A
232	83726F3070B47ECE21504A5065D74A36
233	964A471444A270840919F7FE07382D14
234	A582701EBFCA899B8497088C3560F300
235	64FCB63E21CAC63002D1E09FD1543274
236	B1E1C83F689ADF422C865F98D288838A
237	A06A0D822165D3F3416B47419ECCB547
238	1D2068039A32B7EF728914ECE07CB416
239	64C0CF81F78E8823ECC8661A5295422A
240	902A7243F593F2180E5A306A8438E6A9
241	A4CCED356D56BF1B41C28E1504301FE8
242	82AE90E2F76B3055A2E3A966025CC01A
243	8B90D5A62364E18574145C5895CEFF60
244	43F7EA1AB0D19032551AD9DE21307353
245	DD5D8424AC60360B1C14E65815C9B15E
246	C632A67382ECB2681DFB8525140E2878
247	3A6ACF212B6F8B9C53FF224C2E00C16C
248	86A90C267B1171093F362FE5CB14E3A0
249	EA262EC36E6589C3BB005426AF2590F4
250	200F03126C5B0D7B901128E7757C5F70
251	68FC090C2221AA98BF0D24E85066EFC2
252	9E26CEC67832FC42A87E92FA1015212E
253	ACD889634F79506F2582EA03240F2A07
254	AA65407E1F4A33BF9A62860A3D6A4CC0
255	B1B950AC76A608AA32D04B03C7FF24D3

[Explanation difference:]

For low chip rate have different frame structure. It has the special time slot DwPTS and UpPTS to estimate the UL-synchronization and Cell search. So the Sync and Sync1 code is needed in low chip rate TDD.

## 10 Physical layer procedures

### 10.1 Transmitter Power Control

[Description:]

The basic purpose of power control is to limit the interference level within the system thus reducing the intercell interference level and to reduce the power consumption in the UE.

[Rationale:]

General Parameters

The main characteristics of power control are summarized in the following table.

Table: Transmit Power Control characteristics

	<b>Uplink</b>	<b>Downlink</b>
<b>Power control rate</b>	Variable Closed loop: 0-200 cycles/sec. Open loop: (about 200us – 3575us delay )	Variable closed loop: 0-200 cycles/sec.
<b>Step size</b>	1,2,3 dB (closed loop)	1,2,3 dB (closed loop)
<b>Remarks</b>	All figures are without processing and measurement times	within one timeslot the powers of all active codes may be balanced to within a range of [20] dB

Note:

All codes within one timeslot allocated to the same CCTrCH use the same transmission power in case they have the same Spreading Factor. In case of different spreading factors in the uplink for the same CCTrCH are used , the power levels of the parallel codes portion are under further study.

#### 10.1.2 Uplink Control

Open loop power control for the UpPTS

The transmit power level by a UE on the UpPTS shall be calculated based on the following equation:

$$P_{UpPTS} = L_{P-CCPCH} + PRX_{UpPTS,des}$$



where,  $P_{UpPTS}$ : transmit power level in dBm,

$L_{P-CCPCH}$ : measured path loss in dB (P-CCPCH reference transmit power level is broadcast on BCH),

$PRX_{UpPTS,des}$ : desired RX power level at cell's receiver in dBm, which is broadcast on BCH.

The interference power on the UpPTS ( $I_{UpPTS}$ ) measured by the Node B is reported to the RNC on a regular basis to allow the RNC to make a decision for new control parameters.

The network signals (on BCH) a power increment that is applied only for the access procedure. At each new transmission of a SYNC1 burst during the access procedure, the transmit power level can be increased by this power increment.

### 10.1.2.2 Common Physical Channel

In low chip rate TDD option system, the F-PACH brings the answer to the SYNC1 burst of the UE. The answer, a one burst long message, shall bring besides the acknowledgment to the received SYNC1 burst, the timing and power level indications to prepare the transmission of the RACH burst.

The transmit power level on the PRACH is calculated by the following equation:

$$P_{PRACH} = L_{P-CCPCH} + PRX_{PRACH,des}$$

Where,  $P_{PRACH}$  is the UE transmit power level on the PRACH;

$PRX_{PRACH,des}$  is the desired receive power level on the PRACH, as signalled by the network on the F-PACH

The network computes the  $PRX_{PRACH,des}$  by measuring the interference on the PRACH timeslot which has to be averaged over an configurable (by O&M) number of frames (N).

### 10.1.2.3 Dedicated Physical Channel

The closed loop power control makes uses of layer 1 symbol in the DPCH. The power control step can take the values 1,2,3 dB within the overall dynamic range 80dB. The initial transmission power of the uplink Dedicated Physical Channel is signalled by the UTRAN.

Closed-loop TPC is based on SIR, and the TPC processing procedures are described in this section. During this power control process, the node B periodically makes a comparison between the received SIR measured value and the target SIR value. When the measured value is higher than the target SIR value, TPC command = 'down'. When this is lower than the target SIR value, TPC command = 'up'. At the UE, soft decision on the TPC bits is performed, and when it is judged as 'down', the mobile transmit power shall be reduced by one power control step, whereas if it is judged as 'up', the mobile transmit power shall be raised by one power control step. A higher layer outer loop adjusts the target SIR. This scheme allows quality based power control.

When the TPC bit cannot be received due to out-of-synchronisation, the transmission power value shall be kept at a constant value. When SIR measurement cannot be performed for being out-of-synchronisation, the TPC command shall always be set to = 'up' during the period of being out-of-synchronisation.

## 10.1.3 Downlink Control

### 10.1.3.1 Common Physical Channel

The power of the P-CCPCH

The primary CCPCH transmit power is set by high layer signalling and can be changed based on network determination. The reference power of P-CCPCH is signalled on the BCCH on a periodic basis.

The power value for the F-PACH is set by the network.

The power of the S-CCPCH (for FACH)

It is set by the network and can take into account both the received power level on the PRACH from the addressed UE and the transmit power level as signalled by the UE.

The power of the S-CCPCH(for PCH)

This condition is the same as P-CCPCH.

### 10.1.3.2 Dedicated Physical Channel

The initial transmission power of the downlink Dedicated Physical Channel is set by the network until the first UL DPCH arrives. After the initial transmission, the node B transits into SIR-based closed-loop TPC.

The measurement of received SIR shall be carried out periodically at the UE. When the measured value is higher than the target SIR value, TPC command = 'down'. When this is lower than the target SIR value, TPC command = 'up'. At the Node B, soft decision on the TPC bits is performed, and when it is judged as 'down', the transmission power shall be reduced by one power control step, whereas if judged as 'up', the transmission power shall be raised by one power control step.

When the TPC bit cannot be received due to out-of-synchronisation, the transmission power value shall be kept at a constant value.

When SIR measurement cannot be performed due to out-of-synchronisation, the TPC command shall always be = 'up' during the period of being out-of-synchronisation.

[Explanation difference:]

In low chip rate TDD option, for uplink, the power control update of PRACH can be calculated according to the received power of UpPTS. The power control of the DPCH is closed loop transmitter power control. Closed loop power control in uplink is used because of beamforming. Open loop power control is under consideration if there is no beamforming. For the downlink the transmit power control adjustment of the S-CCPCH(for FACH) can be calculated according the transmit power level signaled in the RACH.

In high chip rate TDD option, for uplink, the power controls of the PRACH and DPCH are open loop transmitter power control. For downlink, the initial transmission power of DPCH is set by the network.

Operation of multiple CCH is under studying.

## 10.2 Timing Advance

### 10.2.1 With UL Synchronization

[Description:]

This section described the detail description on the UL synchronization including the establishment of UL synchronization and maintenance of the UL synchronization.

[Rationale:]

#### 10.2.1.1 The establishment of uplink synchronization

##### 10.2.1.1.1 Preparation of uplink synchronization (downlink synchronization)

When a UE is powered on, it first needs to establish the downlink synchronisation with the cell as describe in paper about cell search procedure. Only after the UE can establish and maintain the downlink synchronisation, it can start the uplink synchronisation procedure.

### 10.2.1.1.2 Establishment uplink synchronization

Although the UE can receive the downlink synchronization signal from the Node B, the distance to Node B is still uncertain which would lead unsynchronised uplink transmission. Therefore, the first transmission in uplink direction is performed in a special time-slot UpPTS to reduce interference in traffic time-slots.

The timing used for the SYNC1 burst are set e.g. according to the received power level of DwPTS and/or P-CCPCH.

At the detection of the SYNC1 sequence in the searching window, the Node B will evaluate the received power levels and timing, and reply by sending the adjustment information to UE to modify its timing and power level for next transmission and for establishment of the uplink synchronisation procedure. . Within the next 4 sub-frames, the Node B will send the adjustment information to the UE (in a single subframe message in theFPACH) The uplink synchronisation procedure, normally used for a random access to the system, can also be used for the re-establishment of the uplink synchronisation when uplink is out of synchronisation.

### 10.2.1.2. Maintenance of uplink synchronisation

For the maintenance of the uplink synchronization, the midamble field of each uplink burst can be used.

In each uplink time slot the midamble in each UE is different. The Node B can estimate the power level and timing shift by measuring the midamble field of each UE in the same time slot. Then, in the next available downlink time slot, the Node B will signal the Synchronisation Shift (SS) and the Power Control (PC) commands to enable the UE to properly adjust respectively its Tx timing and Tx power level.

These procedures guarantee the reliability of the uplink synchronisation. The uplink synchronization can be checked once per TDD sub-frame. The step size in uplink synchronization is configurable and re-configurable and can be adapted from 1/8 chip to 1 chip duration. The following updates for UL synchronization are possible: 1 step up; 1 step down; no update.

[Explanation difference:]

For high chip rate option , uplink synchronisation is mentioned in 4.3 of TS25.224. But the implementation method is a little different with the low chip rate option. For low chip rate option, the establishment of the UL synchronization is done by using the UpPTS and theFPACH.

It allocates a unique time slot UpPTS for UE to establish uplink synchronisation in the access procedure. The benefit of this method is when the UE wants to do random access, the P-RACH will have minimum interference to other traffic channel. Vice versa, it will also reduce the interference from traffic channels to P-RACH.

## 10.3 Synchronisation and Cell Search Procedures

### 10.3.1 Cell Search

[Description:]

In this section, a 4-step cell search procedure for low chip rate TDD option is described which is a slightly different with the current 3 step cell search procedure for high chip rate TDD option.

[Rational:]

During the initial cell search, the UE searches for a cell. It then determines the DwPTS synchronization, scrambling and basic midamble code identification, control multi-frame synchronisation and then reads the contents in BCH. This initial cell search is carried out in 4 steps:

Step 1: Search for DwPTS

During the first step of the initial cell search procedure, the UE uses the SYNC (in DwPTS) to acquire DwPTS synchronization to a cell. This is typically done with one or more matched filters (or any similar device) matched to the received SYNC which is chosen from PN sequences set. A single or more matched filter (or any similar device) is used for this purpose. During this procedure, the UE needs to identify which of the 32 possible SYNC sequences is used.

#### Step 2: Scrambling and basic midamble code identification

During the second step of the initial cell search procedure, the UE receives the midamble of the P-CCPCH. The P-CCPCH is followed by the DwPTS. In the current low chip rate TDD option each DwPTS code corresponds to a group of 4 different basic midamble code. Therefore there are total 128 midamble codes and these codes are not overlapping with each other. Basic midamble code number divided by 4 gives the SYNC code number. Since the SYNC and the group of basic midamble codes of the P-CCPCH are related one by one (that is, once the SYNC is detected, the 4 midamble codes can be determined), the UE knows which 4 basic midamble codes is used. Then the UE can determine the used basic midamble code using a try and error technique. The same basic midamble code will be used throughout the frame. As each basic midamble code is associated with a scrambling code, the scrambling code is also known by that time. According to the result of the search for the right midamble code, UE may go to next step or go back to step 1.

Step 3: Control multi-frame synchronisation

During the third step of the initial cell search procedure, the UE searches for the head of multi-frame indicated by QPSK phase modulation of the DwPTS with respect to the P-CCPCH midamble. The control multi-frame is positioned by a sequence of QPSK symbols modulated on the DwPTS. [n]consecutive DwPTS are sufficient for detecting the current position in the control multi-frame. To ensure correct decisions, an additional bit coded together with a BCH block, allows the UE to know the BCH interleaving block in P-CCPCH. According to the result of the control multi-frame synchronisation for the right midamble code, UE may go to next step or go back to step 2.

#### Step 4: Read the BCH

The (complete) broadcast information of the found cell in one or several BCHs is read. According to the result the UE may move back to previous steps or the initial cell search is finished.

[Explanation difference:]

The initial cell search procedure is optimized considering the frame structure that is needed to enable UL synchronization and other specific features and properties for low chip rate option .

For high chip rate option , the three steps are : slot synchronisation, frame synchronisation and code-group identification, scrambling code identification.

For low chip rate option , the four steps are : search for DwPTS , scrambling and basic midamble code identification, control multi-frame synchronisation and the read of BCH information.

## 10.4 Discontinuous transmission (DTX) of Radio Frames

'Common with the high chip rate TDD mode'

[Description:]

The different downlink transmit diversity schemes for different channel has been considered in low chip rate TDD option.

[Rationale:]

## 10.5 Downlink Transmit Diversity

### 10.5.1 Transmit Diversity for DPCH

'Common with the high chip rate TDD'

### 10.5.2 Transmit Diversity for SCH

The SCH function in high chip rate TDD has been achieved by DwPTS in low chip rate TDD and transmit diversity schemes for the DwPTS in low chip rate TDD is common with that for SCH in high chip rate TDD.

### 10.5.3 Transmit Diversity for P-CCPCH

Transmit diversity for P-CCPCH as in the high chip rate option (i.e., Block STTD) is not supported in low chip rate TDD.

[Explanation difference:]

If both the uplink and downlink physical channels are work under the synchronization mode and if "smart antenna" method is used, the interference on P-CCPCH is thought to be very little in low chip rate TDD option. As a result, "Tx diversity" has not been considered currently to be applied in low chip rate TDD. As this may not hold in all cases, the Block STTD applied for P-CCPCH is to be studied.

### 10.5.4 Transmit diversity for FPACH

The same scheme as for the DPCH can be used for the FPACH.

## 10.6 Random Access Procedure

[Description:]

The random access procedure and the collision problems for low chip rate option are described here. It include the preparation of random access, the random access procedure and the procedure for random access collision.

Note:

In this paper, the FPACH is just a physical channel used to carry one burst message responding to SYNC1 during random access procedure. There is no mapping relationship between FACH and FPACH. The FPACH here is a little like the AICH in FDD.

[Rationale:]

### 10.6.1 Preparation of random access

When the UE is in Idle mode, it will keep the downlink synchronisation and read the cell broadcast information. From the used DwPTS, the UE will get the code set of 8 SYNC1 codes (signatures) assigned to UpPTS physical channel for random access. There are total 256 different SYNC1 sequences. SYNC1 sequences number divided by 8 gives the DwPTS sequences number. From the cell broadcast information, the UE will get to know the used SYNC1 sequences within the code set to be used; the description (codes, spreading factor, midambles, time slots) of the P-RACH channels, the description (codes, spreading factor, midambles, time slots) of the FPACH channels, and other information (if needed ) related to random access.

In the BCH it is described what SYNC1 sequences are associated with what FPACH resources; what FPACHs are associated with what P-RACH resources and what P-RACH resources are associated with what (P/S-)CCPCH (carrying the FACH logical channel) resources.

Thus, when sending a SYNC1 sequence, the UE knows which FPACH resources, P-RACH resources and CCPCH resources will be used for the access.

## 10.6.2 Random access procedures

The SYNC1 sequence in UpPTS following the guard time slot is used only for uplink synchronisation. The UE randomly selects one of the 1-8 possible signatures of the cell it wants to access to and sends it on the UpPTS physical channel.

Then the UE determines the timing and the Tx power level (open loop procedure) for the UpPTS and transmits the selected signature on the UpPTS.

Once the Node B detects the UpPTS transmission from an UE, the arrival time and the received power are known. The Node B determines the Tx power update and timing adjustment and sends them to the UE within the next four frames through the FPACH (in a single burst/sub-frame message). Note that the FPACH also contains the signature reference and the relative frame number (number of frames passed after the reception of the acknowledged signature) for cross check with the UE.

Once the UE receives the above mentioned control signalling from the chosen FPACH (i.e. the FPACH which is associated to the selected signature), its UpPTS sequence has been accepted by the Node B. Then the UE will adjust its timing and power level and send the RACH (also as a single burst/sub-frame message) on the P-RACH channel corresponding to the FPACH exactly two frames later. In this step, the RACH sent to Node B by UE will have high synchronisation precision.

After that, the UE will receive a response from the network from the CCPCH associated to the P-RACH (by the FACH logical channel) indicating whether the UE random access has been accepted or not. In case it has been accepted the further signalling for establishing the link will take place on UL and DL dedicated channels assigned by the network through the FACH.

The UE can transmit a second UpPTS and wait for the response from the FPACH for a further power and SS update before transmitting on the assigned resources.

Note: Details of the random access procedure including the FPACH coding are for further study and proposals are under consideration.

## 10.6.3 Random access collision

When a collision is very likely or in bad propagation environment, the Node B does not transmit the FPACH or cannot receive the SYNC1. In this case, the UE will not get any response from the Node B. Thus the UE will have to adjust its Tx time and Tx power level based on a new measurement and send a SYNC1 again after a random delay.

Note that at each (re-)transmission, the SYNC1 burst will be randomly selected again by the UE.

Due to the two-step approach a collision most likely happens on the UpPTS. The RACH RUs are virtually collision free. This two-step approach will guarantee that the RACH RUs can be handled with conventional traffic on the same UL time slots.

[Explanation difference:]

Different from the high chip rate option, the random access procedure of low chip rate option has two-step approach. The SYNC1 word is used to carry out uplink synchronisation and to resolve the access collision. This two-step procedure enables the RACH RUs to be handled with conventional traffic on the same UL time slots.

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## 11 Physical layer measurements

*All the sections of this chapter are marked as: 'Common with the high chip rate TDD mode'. The range/mapping values should be discussed in WG2/WG4.*

### 11.1 Control of UE/UTRAN measurements

#### 11.1.1 General measurement concept

'Common with the high chip rate TDD mode'

#### 11.1.2 Measurements for cell selection/reselection

'Common with the high chip rate TDD mode'

#### 11.1.3 Measurements for Handover

#### 11.1.4 Measurements for DCA

'Common with the high chip rate TDD mode'

#### 11.1.5 Measurements for timing advance

## 11.2 Measurement abilities for UTRA TDD

### 11.2.1 UE measurement abilities

11.2.1.1 PCCPCH RSCP

11.2.1.2 CPICH RSCP

11.2.1.3 RSCP

11.2.1.4 Timeslot ISCP

'Common with the high chip rate TDD mode'

11.2.1.5 UTRA carrier RSSI

11.2.1.6 GSM carrier RSSI

11.2.1.7 SIR

'Common with the high chip rate TDD mode'

11.2.1.8 CPICH Ec/No

11.2.1.9 Physical channel BER

11.2.1.10 Transport channel BLER

'Common with the high chip rate TDD mode'

11.2.1.11 UE transmitted power

'Common with the high chip rate TDD mode'

11.2.1.12 SFN-SFN observed time difference

11.2.1.13 Observed time difference to GSM cell

### 11.2.2 UTRAN measurement abilities

11.2.2.1 RSCP

'Common with the high chip rate TDD mode'

11.2.2.2 Timeslot ISCP

'Common with the high chip rate TDD mode'



11.2.2.3 RSSI

11.2.2.4 SIR

'Common with the high chip rate TDD mode'

11.2.2.5 Physical channel BER

'Common with the high chip rate TDD mode'

11.2.2.6 Transport channel BLER

'Common with the high chip rate TDD mode'

11.2.2.7 Transmitted carrier power

'Common with the high chip rate TDD mode'

11.2.2.8 Transmitted code power

'Common with the high chip rate TDD mode'

11.2.2.9 RX Timing Deviation

## Annex A (informative): Monitoring GSM from low chip rate TDD: Calculation Results

[Description:]

This paper gives some general description about how to monitor GSM from the low chip rate TDD.

[Rationale:]

A.1 Low data rate traffic using 1 uplink and 1 downlink slot

NOTE: The section evaluates the time to acquire the FCCH if all idle slots are devoted to the tracking of a FCCH burst, meaning that no power measurements is done concurrently. The derived figures are better than those for GSM. The section does not derive though any conclusion. A conclusion may be that the use of the idle slots is a valid option. An alternative conclusion may be that this is the only mode to be used, removing hence the use of the slotted frames for low data traffic or the need for a dual receiver, if we were to considering the monitoring of GSM cells only, rather than GSM, TDD and FDD.

If a single synthesiser UE uses only one uplink and one downlink slot, e.g. for speech communication, the UE is not in transmit or receive state during 5 slots in each frame. According to the timeslot numbers allocated to the traffic, this period can be split into two continuous idle intervals A and B as shown in the figure below.

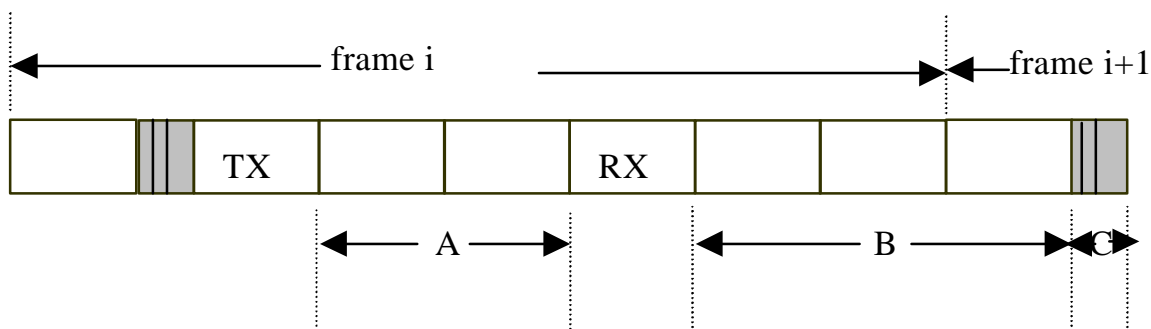


Figure A.1: Possible idle periods in a subframe with two occupied timeslots

A is defined as the number of idle slots between the Tx and Rx slots and B the number of idle slots between the Rx and Tx slots. It is clear that  $A+B=5$  time slots and C is equal to the  $DwPTS+GP+UpPTS$ .

In the scope of low cost terminals, a [0.5] ms period is supposed to be required to perform a frequency jump from low chip rate TDD to GSM and vice versa. This lets possibly two free periods of  $A*Ts-1$  ms and  $B*Ts+C-1$  ms during which the mobile station can monitor GSM,  $Ts$  being the slot period.

Following table evaluates the average synchronisation time and maximum synchronisation time, where the announced synchronisation time corresponds to the time needed to find the FCCH. The FCCH is supposed to be perfectly detected which means that it is entirely present in the monitoring window. The FCCH being found the SCH location is unambiguously known from that point. All the 5 idle slots and the  $DwPTS+GP+UpPTS$  are assumed to be devoted to FCCH tracking and the UL traffic is supposed to occupy the time slot 1.

Table A.1: example- of average and maximum synchronisation time with two busy timeslots per frame and with 0.5 ms switching time

Downlink time slot number	Number of free TS in A	Number of free TS in B	Average synchronisation time (ms)	Maximum synchronisation time (ms)
0	5	0	83	231
2	0	5	75	186
3	1	4	98	232
4	2	3	185	558
5	3	2	288	656
6	4	1	110	371

(\*) All simulations have been performed with a random initial delay between GSM frames and low chip rate TDD subframes.

Each configuration of TS allocation described above allows a monitoring period sufficient to acquire synchronisation.

A.1.1 Higher data rate traffic using more than 1 uplink and/or 1 downlink TDD timeslot

The minimum idle time to detect a complete FCCH burst for all possible alignments between the GSM and the TDD frame structure (called 'guaranteed FCCH detection'), assuming that monitoring happens every TDD frame, can be calculated as follows ( $t_{FCCH}$  = one GSM slot):

$$t_{\min, \text{ guaranteed}} = 2 \times t_{\text{synth}} + t_{FCCH} + \frac{5 \text{ ms}}{13} = 2 \times t_{\text{synth}} + \frac{25 \text{ ms}}{26}$$

- (e.g for  $t_{\text{synth}}=0\text{ms}$ : 2 low chip rate TDD **consecutive** idle timeslots needed, for  $t_{\text{synth}}=0.3\text{ms}$ : 3 slots (or 2 slots and the DwPTS+GP+UpPTS), for  $t_{\text{synth}}=0.5\text{ms}$ : 3 slots, for  $t_{\text{synth}}=0.8\text{ms}$ : 4 slots). Under this conditions the FCCH detection time can never exceed the time of 660ms.

- (For a more general consideration  $t_{\text{synth}}$  may be considered as a sum of all delays before starting monitoring is possible).

- For detecting SCH instead of FCCH (for a parallel search) the same equation applies.

- In the equation before the dual synthesiser UE is included if the synthesiser switching time is 0ms.

Considering about the frame structure of the low chip rate TDD, there are total 7 timeslot in each frame that can be used as data traffic. If more than 1 uplink and/or 1 downlink TDD timeslot are used for data traffic, that means it will occupy at least 3 time slot, equal to  $0.675 \times 3 = 2.205\text{ms}$ . And more time slots for traffic data means more switching point are needed to switch between the GSM and the low chip rate TDD. As it was mentioned above, each switching will take 0.5ms. As a result, the idle time left for monitoring the GSM will be very little. So monitoring GSM from low chip rate TDD under this situation will be considered in the future. It will need more carefully calculation and simulation.

For a synthesiser switching time of one or one half TDD timeslot the number of needed consecutive idle TDD timeslots is summarized in the table below:

Table A.2: Link between the synthesiser performance and the number of free consecutive TSs for guaranteed FCCH detection, needed for GSM monitoring

One-way switching time	Number of free consecutive TDD
------------------------	--------------------------------

<u>for the synthesiser</u>	<u>timeslots needed in the frame for a guaranteed FCCH detection</u>
1 TS (=864 chips)	<u>4</u>
0.5 TS (=432 chips)	<u>3</u>
0 (dual synthesiser)	<u>2</u>

[Explanation difference:]

Due to the different operating bandwidth and the different frame structure, some measurement method about how to monitor GSM are different between the high and low chip rate TDD.

## 12 Performance analysis of the low chip rate

### *Simulation assumptions*

Note: Some of the assumptions may need further clarifications. Other simulations may also be needed to clarify some of the special features of the low chip rate TDD.

Calculation of the  $E_b/N_0$

Intercell interference is modeled as white Gaussian noise. In the following, bit error rates (BER) are given as a function of the average  $E_b/N_0$  (or as a function of average C/I) in dB ( $E_b$  is the energy per bit and  $N_0$  is the one-sided spectral noise density) with the intracell interference, i.e. the number  $K$  of active users per time slot as a parameter. The relation between the  $E_b/N_0$  and the carrier to interference ratio C/I, with  $C$  denoting the carrier power per CDMA code and with  $I$  denoting the intercell interference power, is given by

$$\frac{C}{I} = \frac{E_b}{N_0} \cdot \frac{R_c \cdot \log_2 M}{B \cdot Q \cdot T_c} \quad (1.1)$$

with

$R_c$  the rate of the channel encoder (depends on the service),

$M$  the size of the data symbol alphabet (4),

$B$  the user bandwidth

$Q$  the number of chips per symbol (16) and

$T_c$  the chip duration (0.24414  $\mu$ s).

The expression  $\log_2 M$  is the number of bits per data symbol and  $Q \times T_c / \log_2 M$  is the bit duration at the output of the encoder. One net information bit is transmitted in a duration of  $Q \times T_c / (R_c \times \log_2 M)$ . Therefore, (1.1) is equivalent to  $C/I = (E_b/T_b)/(N_0 \times B)$ , i.e.,  $C = E_b/T_b$  and  $I = N_0 \times B$  with  $T_b$  the duration of a net information bit. The carrier to interference ratio per user is  $K_c$  times the carrier to interference ratio per CDMA code, with  $K_c$  denoting the number of CDMA codes per time slot per user.

The  $E_b/N_0$  (as the C/I) is calculated at the antenna connector of the antenna elements.

Channel model

In case smart antennas are used the channel model is like the vehicular A model used for ITU and ETSI 30.03. The channel model has been adapted to the smart antenna environment such that the directions of arrival (DOA) for the multipaths are uniformly distributed.

Antenna array

Figure 1 shows the circular array used in smart antenna simulations. The circular array is suitable for omnidirectional cell design. Let the array be composed of  $N$  antenna elements, where the first (reference) antenna element is located at the position of  $(R, 0)$ , and the  $k$ -th element is located at the location of  $(R \cos 2k\mathbf{p}/N, R \sin 2k\mathbf{p}/N)$  in circular array.

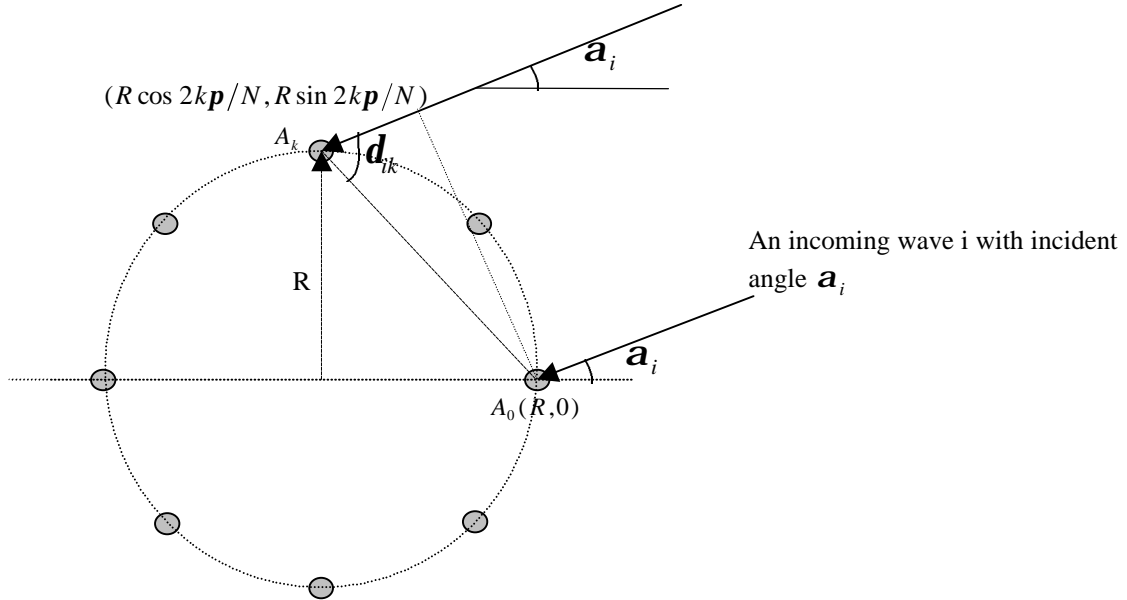


Figure . The geometric illustration for circular antenna array

Then, when an incoming wave  $i$  from the direction of  $\mathbf{a}_i$ , for circular array, the differential optical distance ( $D_{ik}$ ) between the first and the  $k$ -th antenna element will be

$$D_{ik} = R \cos \mathbf{d}_{ik} [2(1 - \cos 2k\mathbf{p}/N)]^{1/2}$$

where  $R$  is the radius of the circular array;

$$k = 1, 2, \dots, N - 1;$$

$N$  is the total number of antenna element.

The incident wave comes from the direction of  $\mathbf{a}_i$  as shown in Figure 1, and

$$\mathbf{d}_{ik} = \mathbf{a}_i + \mathbf{p}(1/2 - k/N)$$

Let's denote  $S_{kj}(n)$  as the Rx signal at the  $k$ -th antenna element from the  $i$ -th path of the  $j$ -th UE ,then

$$S_{kj}(n) = \sum_i a_{ji}(n) \exp[-j(\mathbf{w}\mathbf{t}_{ji} + \mathbf{j}_{kji})] \quad \text{for the } n\text{-th sampling}$$

where,  $a_{ji}(n)$  is the amplitude of the  $i$ -th path from the  $j$ -th UE;

$t_{ji}$  is the time delay of the  $i$ -th path from the  $j$ -th UE;

$\mathbf{j}_{kji}$  is the phase different between the  $k$ -th element and the reference element for the  $i$ -th path from the  $j$ -th UE:

$$\mathbf{j}_{jik} = 2\mathbf{p} D_{jik} / \mathbf{l}$$

and  $D_{jik}$  is the differential optical distance between the first and the  $k$ -th antenna element for the  $i$ -th path from the  $j$ -th UE;

$\mathbf{w}$  is the angle frequency and  $\mathbf{l}$  is the wavelength.

Simulation results

Simulation for BCH

Simulation parameters:

Channel model: vehicular A (Speed 120km/h)

Coding: CC ,coding rate =1/3

Link: downlink

Power control: No

SF: 16

Number of timeslots: 1

Codes per slot: 2

L1 control signals: No

TFCl: No

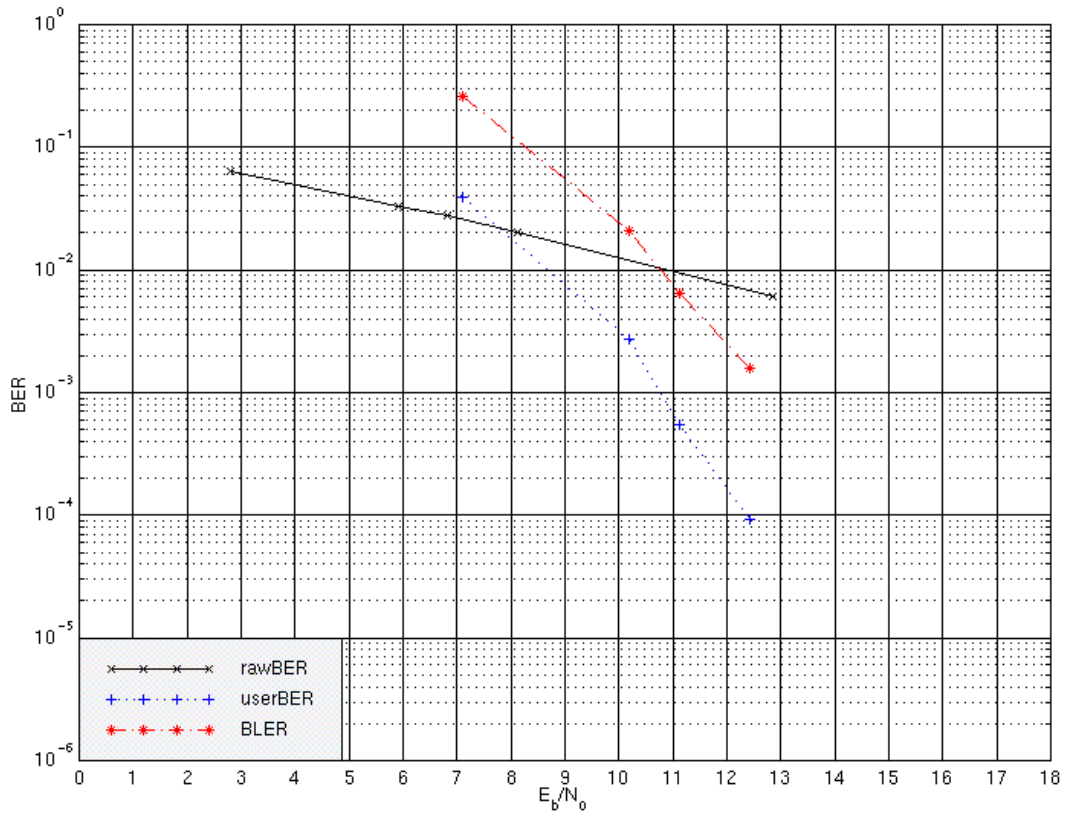


Figure : BER vs. Eb/N0 for BCH

Multiplexing of 12.2kbps data and 2.4kbps data

For 2.4kbps data path

Simulation parameters:

Channel model: vehicular A with Smart antenna (Speed 120km/h)

Coding:CC ,coding rate =1/2

Link: Uplink

Power control: No

SF:16

Number of users: 1

Number of time slot: 1

Codes per time slot: 3

L1 control signals: No

TFCI: No



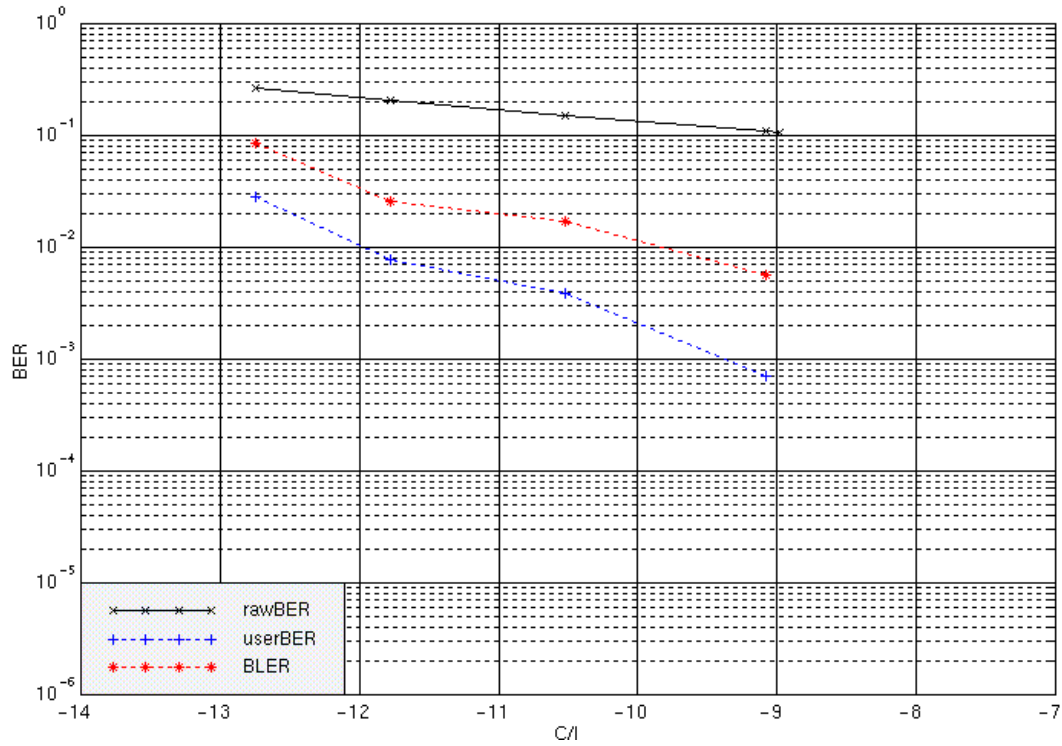


Figure : BER vs. C/I for 2.4kbps path

For 12.2kbps data path

Simulation parameters:

Channel model: vehicular A with Smart antenna (Speed 120km/h)

Coding: CC ,coding rate=1/2,class C

CC, coding rate=1/3,class A and B

Link: Uplink

Power control: No

SF:16

Number of users: 1

Number of time slot: 1

Codes per time slot: 3

L1 control singals: 4 bits.

TFCl: 16 bits( 8 bits per subframe).

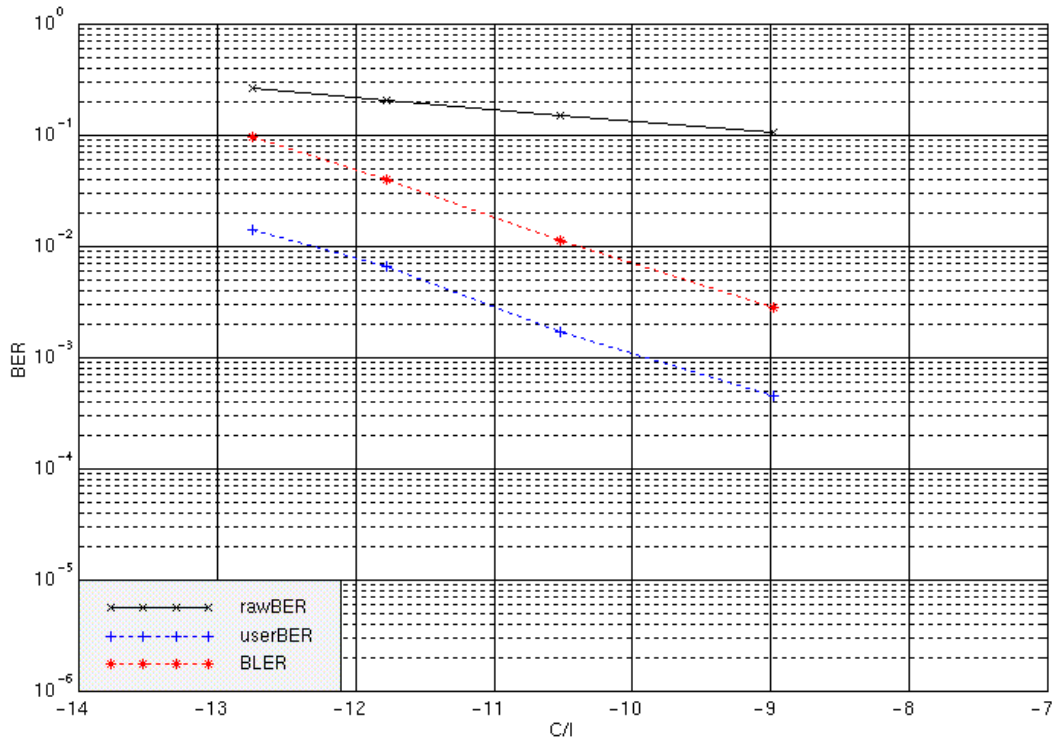


Figure : BER vs. C/I for 12.2kbps path

Simulation for 384kbps

Simulation parameters:

Channel model: vehicular A with Smart antenna (Speed 120km/h)

Coding: Turbo coding ,coding rate 1/3. Convolutional code with code rate 1/3 is optional for 384kbps packet data.

Link: Uplink

Power control: No

SF:16

Number of users: 1

Number of time slot: 4

Codes per time slot: 16

L1 control signals: 4 bits.

TFCI: 16 bits

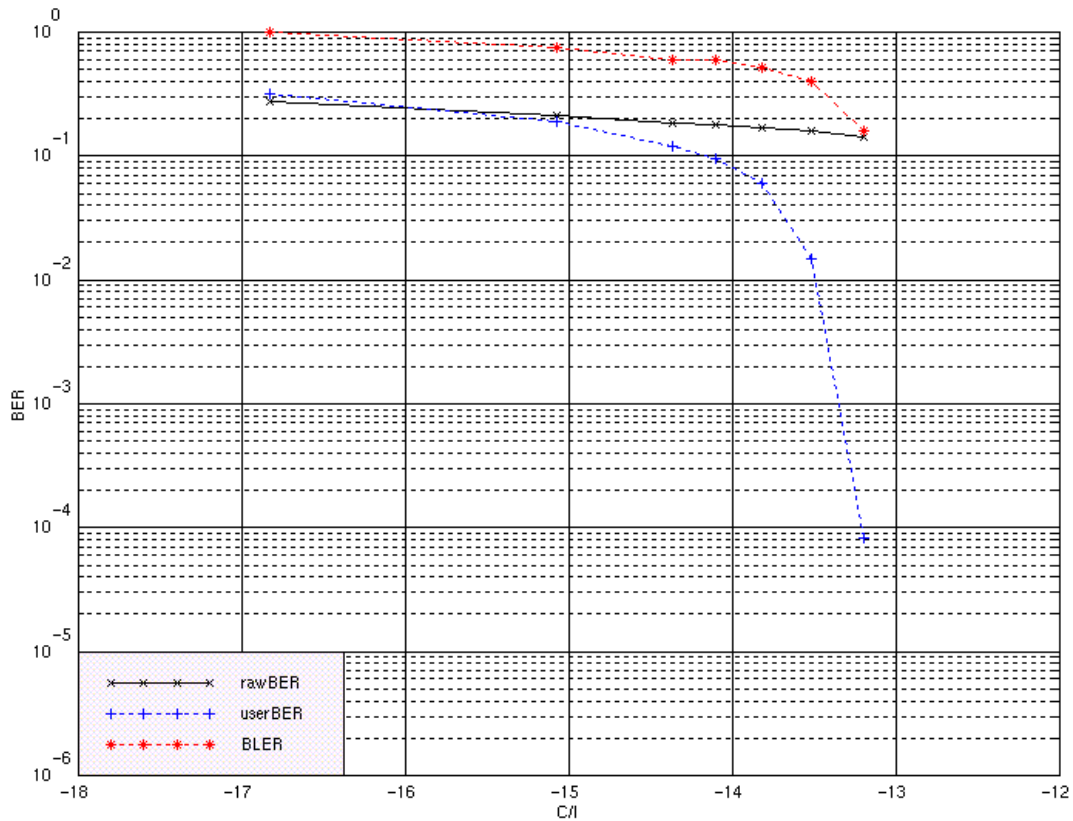


Figure BER vs. C/I for 384kbps

Simulation for 2Mbps

The simulations for the indoor environments in uplink are considered. The channel model is compatible with the one in UMTS 30.03. The main parameters are listed as following:

Parameters

Service: 2 Mbps service

Channel model: Indoor A

Channel coding: None

Modulation/Demodulation: 8PSK;

Power Control: Ideal power control

Frame structure: 5ms

Number of time slot: 5

Codes per time slot: 16

Simulation Results

The following table and figures in next pages present the simulation results for 2 Mbps service without channel coding considered.

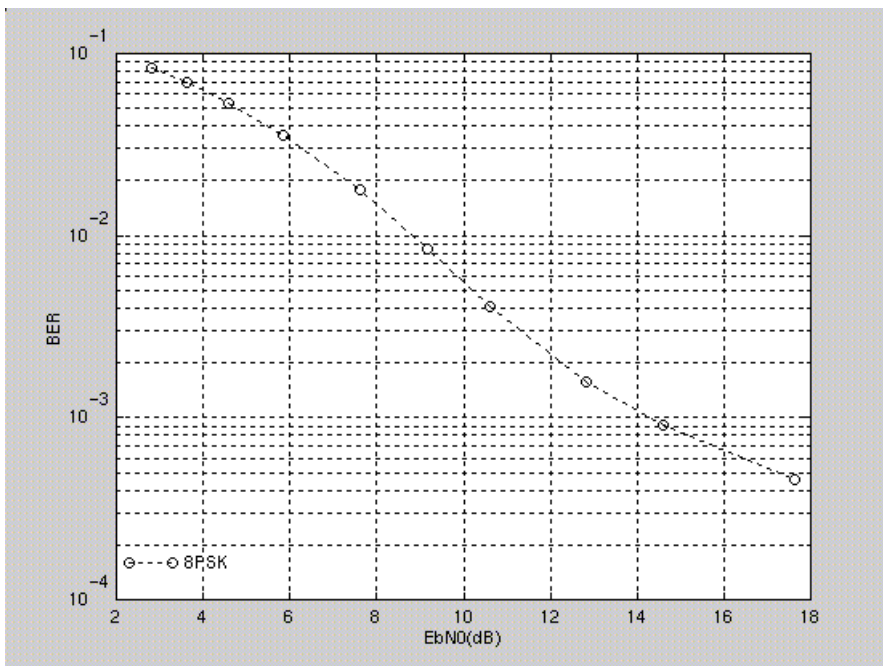


Figure : BER vs. EbNo for 2 Mbps service

(without coding using 8PSK modulation scheme)

## 13 Examples of service mapping

### B.1 BCH

Note: Other means for BCH indication are under consideration.

Table B.1 Parameters for BCH

Transport block size	246 bits+1bit (*)
CRC	16 bits
Coding	CC, coding rate = 1/3 This has to be included in table 1 in 25.222 4.2.3.
TTI	20 ms
Midamble	144 chips
Codes and time slots	SF = 16 2 codes x 1 time slot
TFCI	0 bit
L1 control signals	0 bit

Note: The example is applied to BCH without multiplexing PCH and FACH.

\*: 1 extra bit in transport block is used for BCH indication.

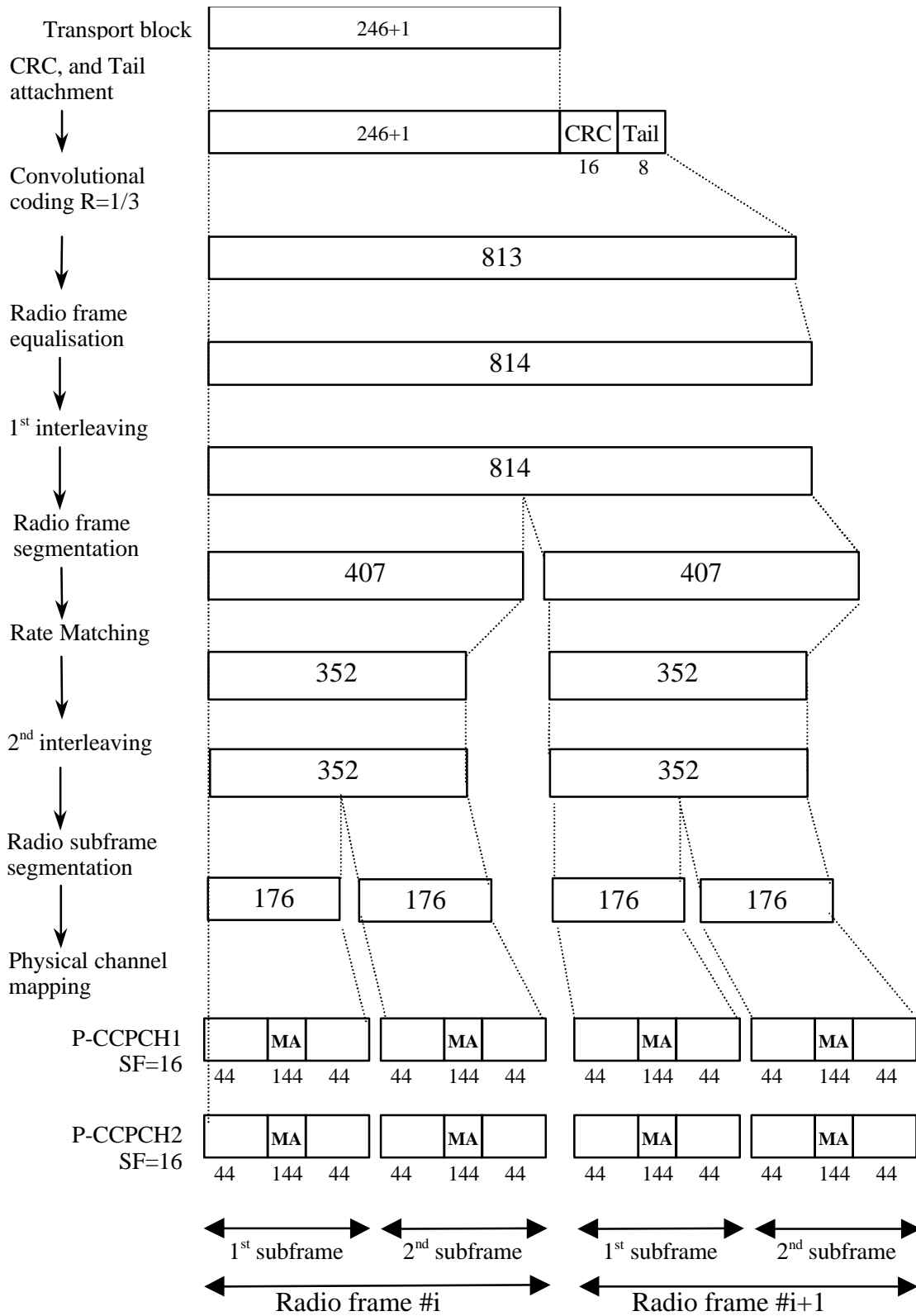


Figure B.1 Service mapping for BCH

B.2 2.4kbps data for downlink

Table B.2 Parameter examples for 2.4kbps data

Transport block set size	48 bits
CRC	16 bits
Coding	CC, coding rate = 1/2
TTI	20 ms

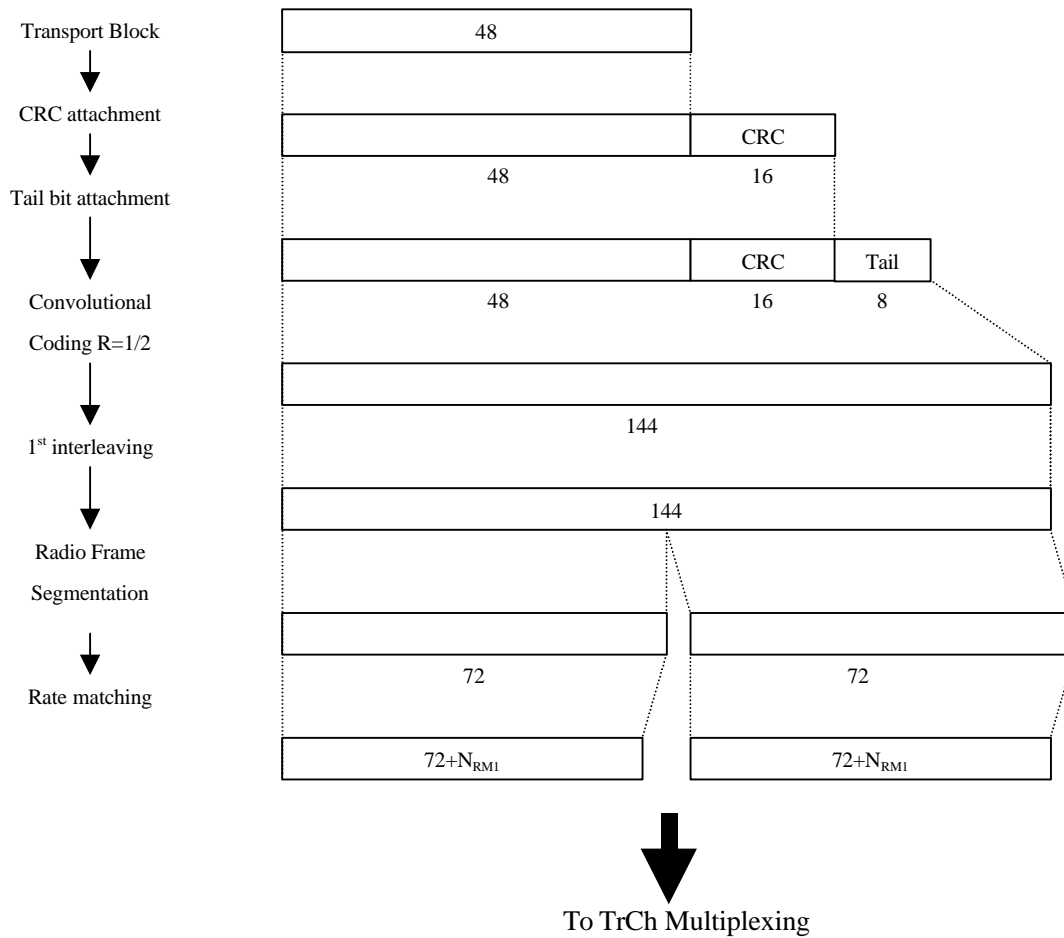


Figure B.2 Channel coding for 2.4kbps data

## B.3 12.2kbps data for downlink

Note: this example can be applied to AMR speech

Table B.3 Parameter examples for 12.2kbps data

Number of TrChs	3
Transport block size	81bits(TrCh#1) 103bits(TrCh#2) 60bits(TrCh#3)
CRC	12(Only for TrCh#1)
Coding	CC, coding rate = 1/2, class B, C CC, coding rate = 1/3, class A
TTI	20 ms
Midamble	144 chips
Codes and time slots	SF = 16 2 codes x 1 time slots
TFCI	16bits (8 bits in each subframe)
L1 control signals	4bits



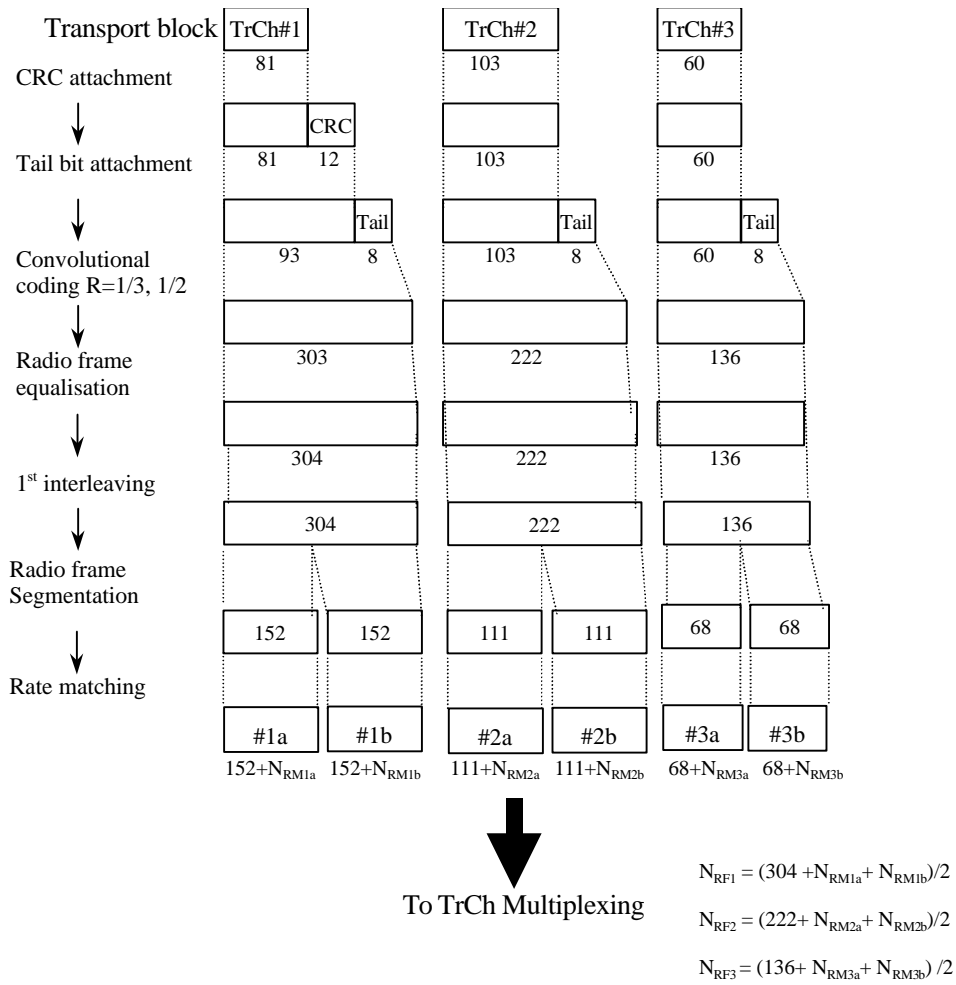
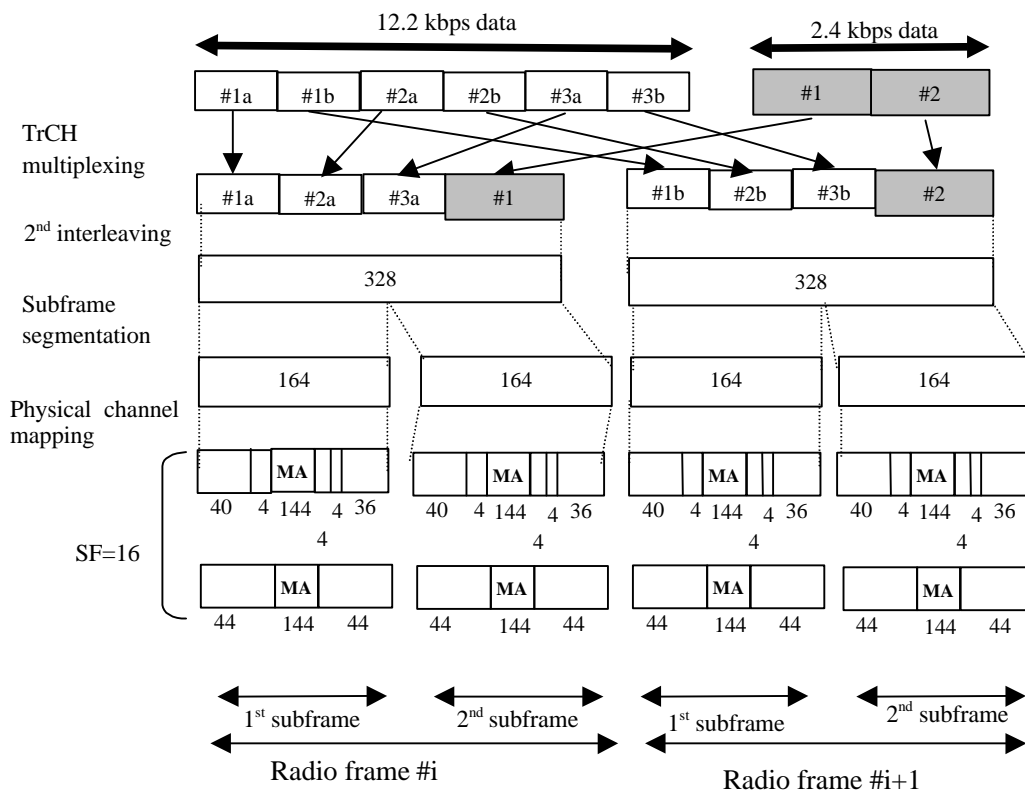


Figure B.3 Channel coding for 12.2kbps AMR

B.3-1 Example for multiplexing of 12.2 kbps data and 2.4 kbps data



B.4 384kbps packet data for downlink

Table B.4 Parameter examples for 384kbps packet data

The number of TrChs	1
Transport block set size	3840*B bits(B=0,1,2)
Segmentation C	1 (B = 0, 1) or 2 (B = 2)
CRC	16 bits
Coding	Turbo coding, coding rate = 1/3
TTI	20 ms
Midamble	144chips
Codes and time slots	SF = 16 16 codes x 4 time slots
TFCI	16bits
L1 signals	4 bits

Note1: 13codes\*4 time slots+12codes\*1 time slot is under considered.

Note2: Convolutional code with code rate 1/3 is optional for 384kbps packet data if UE capability supports it.  
B=2 for the figure B.4.

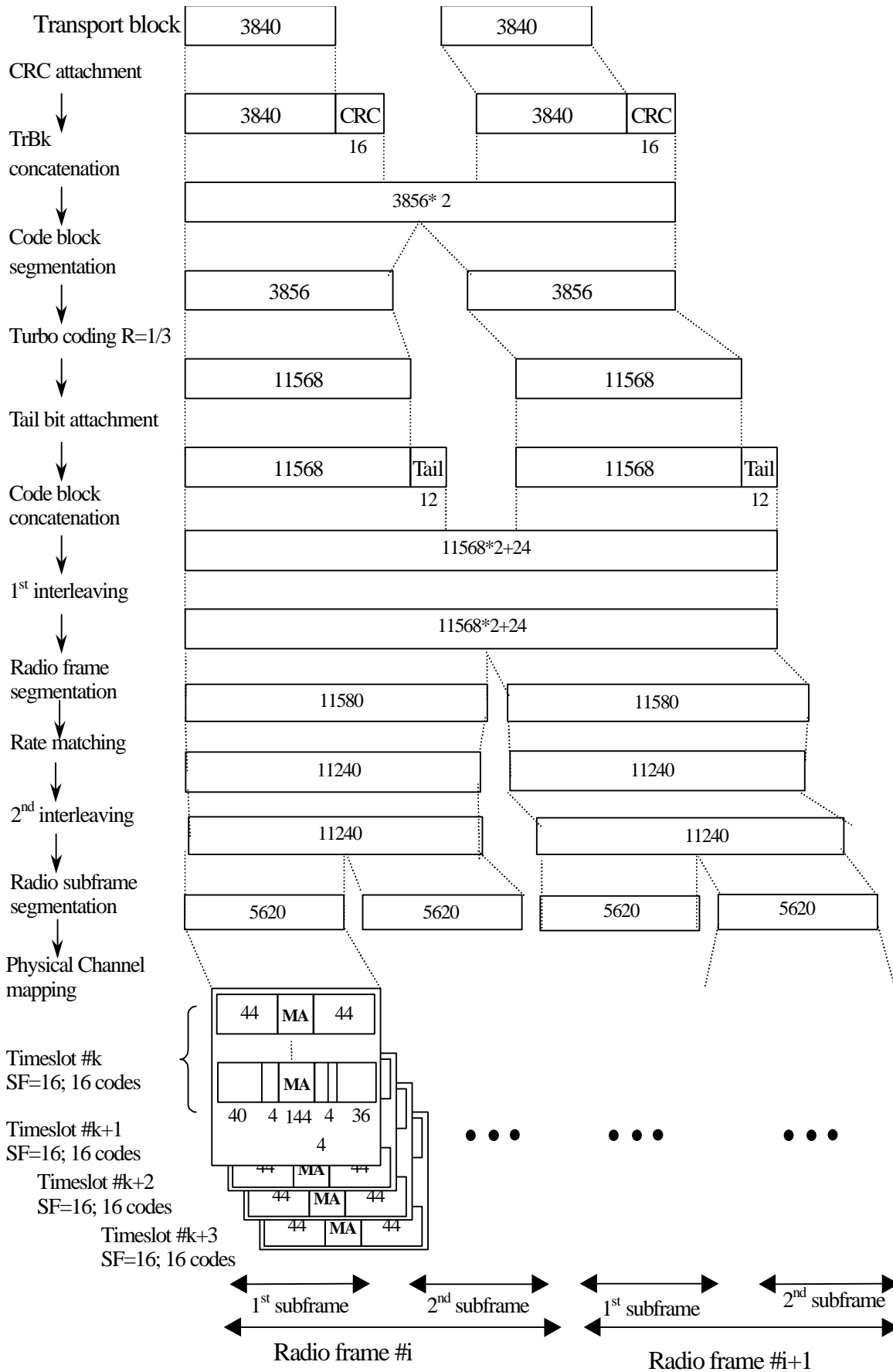


Figure B.4 Service mapping for 384kbps packet data

## B.5 2Mbps packet data for downlink

In low chip rate TDD optional, 2Mbps service is only used in some special environment. E.g. Indoor environment

Table B.5 Parameter examples for 2Mbps packet data

Transport block size	20480*B bits(B=0,1)
CRC	24 bits
Coding	no
TTI	10 ms
Midamble	144 chips
Codes and time slots	SF = 1 1 codes x 5 time slots
TFCI	24bits
L1control signals	6bits

Note1: 8PSK has to be used to provide 2Mbps packet data service. B=1 for the figure B.5.

Note2: other mapping schemes, e.g. using more resource unit and using some channel coding, or increasing the number of the code block segmentation to reduce BLER are considered.

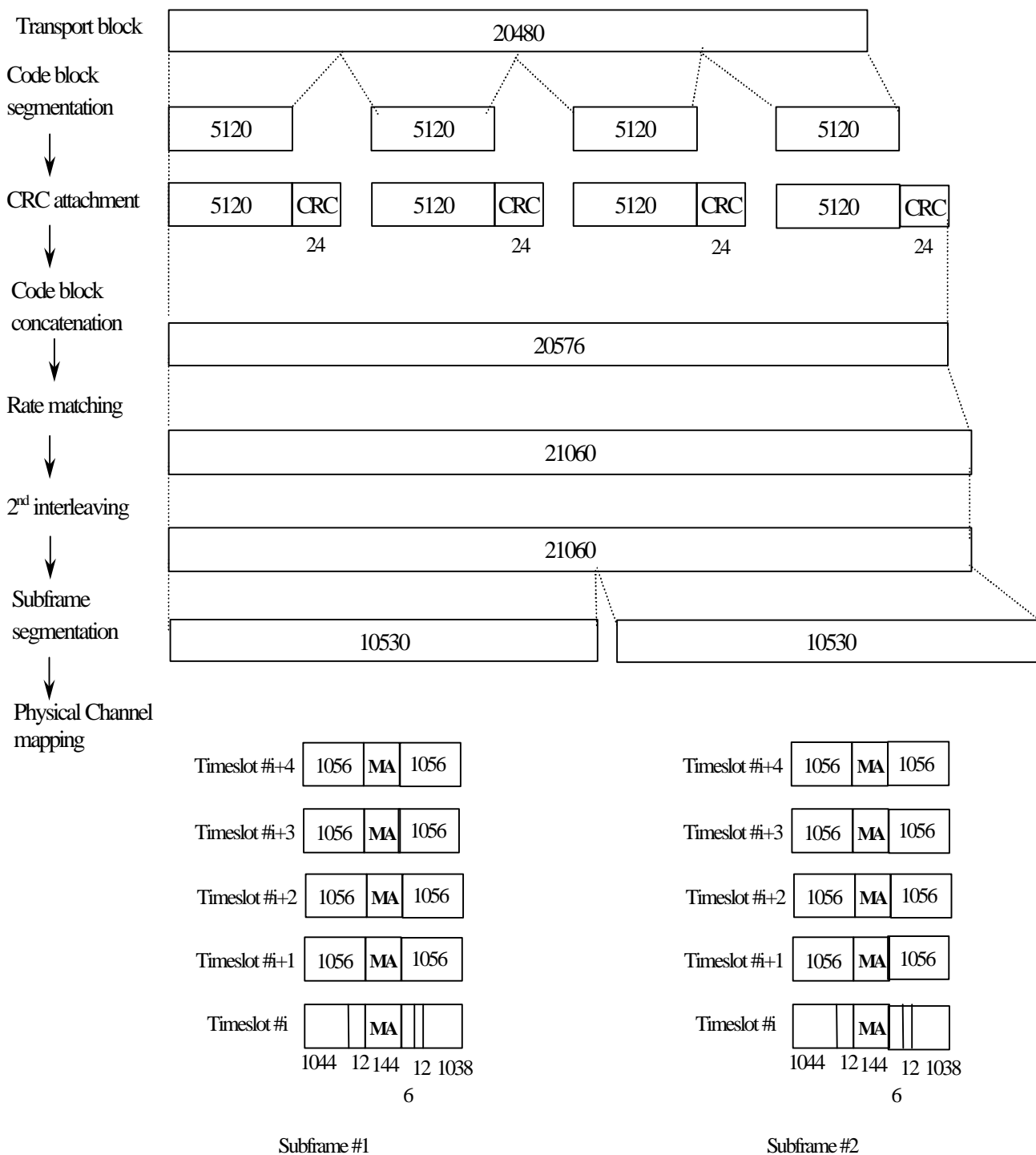


Figure B.5 Service mapping for 2Mbps packet data

## 14 History

<b>Document history</b>		
V0.0.1	January 2000	Created in WG#10 in Beijing, Table of contents approved, R1-00-149
V0.0.2	March 2000	New structure created according to the comments at the WG1#11, San Diego
V0.0.3	March 2000	Document renamed according to the conclusions in RAN#8, Madrid
V0.0.4	April 2000	Updated according to the conclusions in WG1#12, Seoul
V0.1.0	April 2000	WG1 approved version
V0.2.0	May 2000	Updated according to the conclusions in WG1#13 and approved, Tokyo
V0.2.1	June 2000	Updated according to the AH on the NB-TDD (R1-00-0840)
V1.0.0	June 2000	Approved version in the NB-TDD AH (R1-00-0841)
V1.0.1	July 2000	Draft for approval after some new proposals added
V1.1.0	July 2000	Approved version at WG1#14, Oulu

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