TSG-RAN Working Group1 meeting #7

TSGR1#7(99)d56

Hannover, Germany, August 30 – September 3, 1999

Agenda Item:

Source: SAMSUNG Electronics Co. and LGIC

Title: Text proposal for turbo codes and rate matching in TS 25.212, TS 25.222 (rev. of R1-99b56)

Document for: Decision

1. Introduction

Rate matching algorithm for Turbo codes proposed by Samsung and LGIC has been approved as a working assumption in Ad Hoc 5 meeting. This document proposes a revised text proposal for the rate matching and its corresponding mother code rate of turbo codes for uplink and downlink[1-3].

2. Text proposal for TS 25.212

----- Start text proposal -----

4.2.3. Channel coding

The following channel coding schemes can be applied to transport channels:

- Convolutional coding
- Turbo coding
- · No channel coding

Table 1: Error Correction Coding Parameters

Transport channel type	Coding scheme	Coding rate
ВСН	Convolutional code	1/2
PCH		
FACH		
RACH		
DCH		1/3, 1/2 or no coding
DCH	Turbo code	1/3, 1/2 of no coding

NOTE 1: The exact physical layer encoding/decoding capabilities for different code types are FFS.

NOTE 2: In the UE the channel coding capability should be linked to the terminal class.

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4.2.3.2.1. Turbo coder

NOTE: 4-state SCCC is not included in Release-99. It needs to be clarified from TSG-SA what are the service specifications with respect to different quality of services. The performance below BER of 10⁻⁶ need to be studied if there is a requirement for this quality of services of physical layer.

For data services requiring quality of service between 10⁻³ and 10⁻⁶ BER inclusive, parallel concatenated convolutional code (PCCC) with 8-state constituent encoders is used.

The 8-state PCCC and the 4-state SCCC -are described below.

The transfer function of the 8-state constituent code for PCCC is

$$G(D) = \left[1, \frac{n(D)}{d(D)}\right]$$

where.

$$d(D)=1+D^2+D^3$$

 $n(D)=1+D+D^3$.

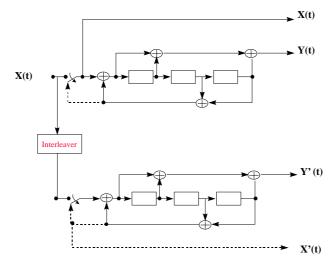


Figure 1: Structure of the 8 state PCCC encoder (dotted lines effective for trellis termination only)

The initial value of the shift registers of the PCCC encoder shall be all zeros.

The output of the PCCC encoder is punctured to produce coded bits corresponding to the desired code rate 1/3- or 1/2. For rate 1/3, none of the systematic or parity bits are punctured, and the output sequence is X(0), Y(0), Y(0), Y(0), X(1), Y(1), Y(1), etc. For rate 1/2, the parity bits produced by the constituent encoders are alternately punctured to produce the output sequence X(0), Y(0), X(1), Y'(1), X(2), Y(2), X(3), Y'(3), etc.

The SCCC is a rate 1/3 SCCC, The outer code of the SCCC is a rate 2/3 obtained by puncturing a rate ½ ode with generating matrix

4.2.6. Rate matching

Rate matching means that bits on a transport channel are repeated or punctured. Higher layers assign a rate-matching attribute for each transport channel. This attribute is semi-static and can only be changed through higher layer signalling. The rate-matching attribute is used when the number of bits to be repeated or punctured is calculated.

The number of bits on a transport channel can vary between different transmission time intervals. In the downlink the transmission is interrupted if the number of bits is lower than maximum. When the number of bits between different transmission time intervals in uplink is changed, bits are repeated or punctured to ensure that the total bit rate after second multiplexing is identical to the total channel bit rate of the allocated dedicated physical channels.

Notation used in Section 4.2.6 and subsections:

 N_{ij} : Number of bits in a radio frame before rate matching on transport channel i with transport format combination j.

 N_{ii}^{TTI} : Number of bits in a transmission time interval before rate matching on transport channel i with transport format j.

 ΔN_{ii} : If positive - number of bits that should be repeated in each radio frame on transport channel i with transport format

combination j.

If negative - number of bits that should be punctured in each radio frame on transport channel i with transport format combination j.

 ΔN_{ij}^{TTI} : If positive - number of bits to be repeated in each transmission time interval on transport channel i with transport format j.

If negative - number of bits to be punctured in each transmission time interval on transport channel i with transport format j.

RM_i: Semi-static rate matching attribute for transport channel i. Signalled from higher layers.

PL: Puncturing limit for uplink. This value limits the amount of puncturing that can be applied in order to avoid multicode or to enable the use of a higher spreading factor. Signalled from higher layers.

 $N_{data,i}$: Total number of bits that are available for the CCTrCH in a radio frame with transport format combination j.

T: Number of transport channels in the CCTrCH.

 Z_{mj} : Intermediate calculation variable.

 F_i : Number of radio frames in the transmission time interval of transport channel i.

k: Radio frame number in the transmission time interval of transport channel i (0 £ $k < F_i$).

q: Average puncturing distance.

 $I_F(k)$: The inverse interleaving function of the 1st interleaver (note that the inverse interleaving function is identical to the interleaving function itself for the 1st interleaver).

S(k): The shift of the puncturing pattern for radio frame k.

 $TF_i(j)$: Transport format of transport channel i for the transport format combination j.

<u>Nes:</u> Number of bits before rate matching for each rate matching algorithm block.

 N_{is} : Number of bits after rate matching for each rate matching algorithm block.

The following relations are used when calculating the rate matching pattern:

$$Z_{0,i} = 0$$

$$Z_{mj} = \begin{bmatrix} \sum_{i=1}^{m} RM_{i} \cdot N_{ij} \\ \sum_{i=1}^{T} RM_{i} \cdot N_{ij} \end{bmatrix} \text{ for all } m = 1 \dots T, \text{ where } \mathbf{\ddot{e}} \, \mathbf{\hat{u}} \text{ means round downwards}$$

$$\Delta N_{ij} = Z_{ij} - Z_{i-1,j} - N_{ij} \qquad \quad \text{for all } i = 1 \; .. \; T$$

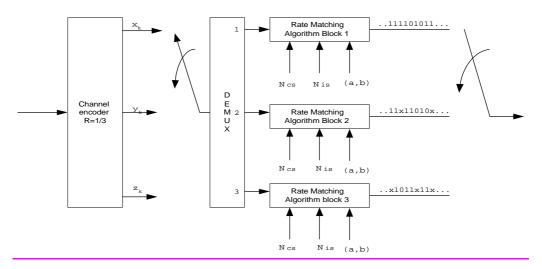


Figure 4-1. Overall rate matching block diagram before first interleaving where x denotes punctured bit.

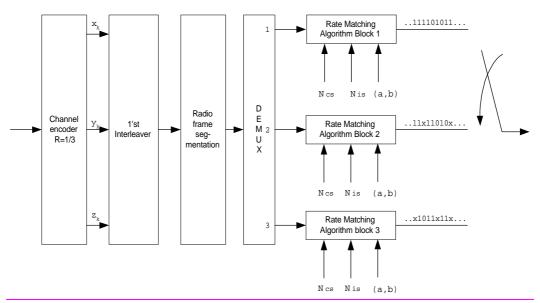


Figure 4-2. Overall rate matching block diagram after first interleaving where x denotes punctured bit.

4.2.6.1. Determination of rate matching parameters in uplink

In uplink puncturing can be used to avoid multicode or to enable the use of a higher spreading factor. The maximum amount of puncturing that can be applied is signalled at connection setup from higher layers and denoted by PL. The number of available bits in the radio frames for all possible spreading factors is given in [2]. Denote these values by N_{256} , N_{128} , N_{64} , N_{32} , N_{16} , N_{8} , and N_{4} , where the index refers to the spreading factor. The possible values of N_{data} then are $\{N_{256}, N_{128}, N_{64}, N_{32}, N_{16}, N_{8}, N_{4}, 2N_{4}, 3N_{4}, 4N_{4}, 5N_{4}, 6N_{4}\}$. Depending on the UE capabilities, the supported set of N_{data} , denoted SET0, can be a subset of $\{N_{256}, N_{128}, N_{64}, N_{32}, N_{16}, N_{8}, N_{4}, 2N_{4}, 3N_{4}, 4N_{4}, 5N_{4}, 6N_{4}\}$. $N_{data, j}$ for the transport format combination j is determined by executing the following algorithm:

SET1 = {
$$N_{data}$$
 in SET0 such that $N_{data} - \sum_{i=1}^{T} \frac{RM_i}{m_i n_i RM_i} \cdot N_{ij}$ is non negative }

If the smallest element of SET1 requires just one DPDCH then

```
N_{data,j} = \min \text{SET1} else \text{SET2} = \{ N_{data} \text{ in SET0 such that } N_{data} - PL \cdot \sum_{i=1}^{T} \frac{RM_i}{m_i n} \{ RM_i \} \cdot N_{ij} \text{ is non negative } \} \text{Sort SET2 in ascending order } N_{data} = \min \text{SET2} While N_{data} is not the max of SET2 and the follower of N_{data} requires no additional DPDCH do N_{data} = follower of N_{data} in SET2 End while N_{data,j} = N_{data} End if
```

The number of bits to be repeated or punctured, DN_{ij} , within one radio frame for each transport channel i is calculated with the relations given in Section 4.2.6 for all possible transport format combinations j and selected every radio frame. For each radio frame, the rate-matching pattern is calculated with the algorithm in Section 4.2.6.3, where $DN = DN_{ij}$ and $N = N_{ij}$. Additionally, the following parameters are needed:

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4.2.6.1.1. Parameters for convolutional codes
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'X' coded bits sequence from output 0 of convolutional coder in section 4.2.3.1.1.

'Y' coded bits sequence from output 1 of convolutional coder in section 4.2.3.1.1.

'Z' coded bits sequence from output 2 of convolutional coder in section 4.2.3.1.1.

 $\frac{N_{cs} = N_{ij}}{N_{is} = N_{ij} + \mathbf{D}N_{ij}}$ (a,b) = (2,1) for the rate matching algorithm block 1.

 $/(\hat{\boldsymbol{o}}\boldsymbol{D}N_{ii}\hat{\boldsymbol{o}})\hat{\boldsymbol{u}}$ round downwards and ôômeans absolute value. where means q=if is even $gcd(q, F_i)/F_i$ where gcd (q, F_i) means greatest common divisor of qand F_i 1/8 an integer, but multiple else q' = qendif

for l = 0 to F_{i-1} $S(I_F(\acute{e}l^*q'\grave{u} \bmod F_i)) = (\acute{e}l^*q'\grave{u} \operatorname{div} F_i)$ -- where \acute{e} \acute{u} means round upwards.

end for

4.2.6.1.2. Parameters for turbo codes

'X': systematic bits sequence of the upper constituent encoder s.t. $(x_1, x_2, ..., x_k, ...)$ in section 4.2.3.2.1.

'Y': parity bits sequence of the upper constituent encoder s.t. $(y_1, y_2, ..., y_k, ...)$ in section 4.2.3.2.1.

'Z': parity bits sequence of the lower constituent encoder s.t. $(z_1, z_2, ..., z_k, ...)$ in section 4.2.3.2.1.

If repetition is to be performed, such as $DN_{ij} > 0$, parameters for turbo codes are the same as parameter for convolutional codes. If puncturing is to be performed, parameters are as follows.

 $N_{cs} = \ddot{e}N_{ii}/3\hat{u}$ where \ddot{e} \hat{u} means round downwards.

 $N_{is} = N_{cs}$ for 'X' sequence in rate matching algorithm block 1.

 $\underline{N_{is}} = \underline{N_{cs}} - \mathbf{\ddot{e}} - \mathbf{D}N_{ii}/2\mathbf{\hat{u}}$ for 'Y' sequence in rate matching algorithm block 2 where $\mathbf{\ddot{e}}$ $\mathbf{\hat{u}}$ means round downwards.

 $N_{is} = N_{cs} - \dot{\epsilon} \cdot DN_{ij}/2\dot{u}$ for 'Z' sequence in rate matching algorithm block 3 where $\dot{\epsilon}$ \dot{u} means round upwards.

 $\underline{q} = \underline{\ddot{e}N_{cs}}/(\underline{\hat{o}N_{is}-N_{cs}}\underline{\hat{o}})\underline{\hat{u}}$: \underline{q} is the average puncturing distance of 'Y' or 'Z' sequence

```
(a,b)=(2,1) for the rate matching algorithm block 2.
(a,b)=(1,1) for the rate matching algorithm block 3.
\underline{if}(q \leq 2)
for l=0 to F_{i-1}
   if('Y' sequence)
      S[I_F[(3l+1) \bmod F_i]] = l \bmod 2;
   if('Z' sequence)
            S[I_F (3l+2) \mod F_i] = l \mod 2;
  end for
<u>else</u>
if q is even
    then q' = q - gcd(q, F_i)/F_i -- where gcd(q, F_i) means greatest common divisor of q and F_i
                             -- note that q' is not an integer, but a multiple of 1/8
 else
endif
for l = 0 to F_i - 1
   r = \acute{e} \, l * q \grave{u} \mod F_i;
   if('Y' sequence)
    S[I_F[(3r+1) \bmod F_i]] = \mathbf{\acute{e}} \, l * q' \mathbf{\grave{u}} \, div \, F_i;
   if('Z' sequence)
    S[I_F[(3r+2) \bmod F_i]] = \mathbf{\acute{e}} \, l * q' \mathbf{\acute{u}} \, div \, F_i
 endfor
endif
```

4.2.6.2. Determination of rate matching parameters in downlink

For downlink $N_{data,j}$ does not depend on the transport format combination j. $N_{data,j}$ is given by the channelization code(s) assigned by higher layers.

NOTE: The rule to convert the rate matching attributes in downlink to the parameters input to rate matching pattern algorithm are working assumption. So, it remains to be verified that they hold for all possible transport format combinations. It has been identified that the case when the transport format combination with highest rate include a transport format with zero bits need special treatment.

Radio frame segmentation is performed after 1st interleaving and N_{ii} is therefore calculated as:

$$l = TF_i(j)$$
 and $N_{ij} = \left[\frac{N_{i,l}^{TTI}}{F_i}\right]$

The number of bits repeated or punctured, DN_{iL} , within one radio frame for each transport channel is calculated for the transport format combination L with highest bitrate with the relations given in Section 4.2.6.

If fix positions of the transport channels in the radio frame are used then the same DN_{ij} is used for all transport format combinations and the last part of the rate-matching pattern omitted. That is to say for all transport format combinations j we have:

$$\Delta N_{ij} = \Delta N_{iL}$$

When flexible positions of the transport channels are used, the number of bits DN_{ij} repeated or punctured for all transport format combinations j other than L is calculated as:

$$\Delta N_{ij} = \left[\frac{\Delta N_{iL}}{N_{iL}} \cdot N_{ij} \right]$$

For each transmission time interval, the rate-matching pattern is calculated with the algorithm in Section 4.2.6.3. The following parameters are used as input:

$$l = TF_i(j)$$
 and $\Delta N = \Delta N_{il}^{TTI} = F_i \Delta N_{ij}$
 $N = N_{il}^{TTI}$

S=0.

4.2.6.2.1. Parameter for convolutional codes

'X' coded bits sequence from output 0 of convolutional coder in section 4.2.3.1.1.

'Y' coded bits sequence from output 1 of convolutional coder in section 4.2.3.1.1.

'Z' coded bits sequence from output 2 of convolutional coder in section 4.2.3.1.1.

 $N_{cs} = N$

 $\overline{N_{is}} = N + DN$

(a,b)=(2,1) for the rate matching algorithm block 1.

4.2.6.2.2. Parameter for turbo codes

'X': systematic bits sequence of the upper constituent encoder s.t. $(x_1, x_2, ..., x_k, ...)$ in section 4.2.3.2.1.

'Y': parity bits sequence of the upper constituent encoder s.t. $(y_1, y_2, ..., y_k, ...)$ in section 4.2.3.2.1.

'Z': parity bits sequence of the lower constituent encoder s.t. $(z_1, z_2, ..., z_k, ...)$ in section 4.2.3.2.1.

If repetition is to be performed, such as *DN>*0, parameters for turbo codes are the same as parameter for convolutional codes. If puncturing is to be performed, parameters are as follows.

 $N_{cs} = \ddot{\mathbf{e}} N/3 \hat{\mathbf{u}}$ where $\ddot{\mathbf{e}}$ $\hat{\mathbf{u}}$ means round downwards.

 $N_{is} = N_{cs}$ for 'X' sequence in rate matching algorithm block 1.

 $\underline{N_{is}} = \underline{N_{cs}} - \mathbf{\ddot{e}} - \mathbf{D}N/2\mathbf{\hat{u}}$ for 'Y' sequence in rate matching algorithm block 2 where $\mathbf{\ddot{e}}$ $\mathbf{\hat{u}}$ means round downwards.

 $N_{is} = N_{cs} - \epsilon DN/2\dot{\mathbf{u}}$ for 'Z' sequence in rate matching algorithm block 3 where $\dot{\mathbf{e}}$ $\dot{\mathbf{u}}$ means round upwards.

 $(\overline{a,b})=(\overline{2,1})$ for the rate matching algorithm block 2.

(a,b)=(1,1) for the rate matching algorithm block 3.

Systematic bit should not be punctured.

4.2.6.3. Rate matching algorithm

All rate matching algorithm blocks in Figure 4-1 and 4-2 in section 4.2.6 use the same rate matching algorithm below with different parameters for convolutional codes and turbo codes, respectively.

For convolutional codes, in Figure 4-1 and 4-2, DEMUX is always at the position 1 and parameters for rate matching algorithm block 1 are fixed to the value given in section 4.2.6.2.1 or 4.2.6.3.1.

For turbo codes, in Figure 4-1 and 4-2, DEMUX repeats switching for puncturing or is always at the position 1 for repetition, respectively. Parameters for rate matching algorithm blocks are fixed to the value given in section 4.2.6.2.2 or 4.2.6.3.2.

Denote the bits before rate matching by:

 $c_1, c_2, c_3, \dots c_{NCS}$

The common rate matching rule for both convolutional codes and turbo codes is as follows:

if puncturing is to be performed

$$y = -DN_{cs}-N_{is}$$

```
e = (2a*S(k)*y + b*N_{cs}) \mod 2a*N_{cs} -- initial error between current and desired puncturing ratio
         if e=0 then e=a*N_{cs}
        m = 1
                                          -- index of current bit
         do while m <= N_{cs}
                   e = e - \frac{2}{2} \underline{a} * y
if e <= 0 then
                                                                    -- update error
                                                                    -- check if bit number m should be punctured
                         puncture bit c_{\mathrm{m}}
                         e = e + \frac{2a}{a} N_{cs}
                                                       -- update error
                   end if
                                                                                 -- next bit
                   m = m + 1
        end do
else
        y = \mathbf{P} N_{\underline{-}(N_{cs}\underline{-}N_{is})}
        e = (2a*S(k)*y + b*N_{cs}) \mod 2a*N_{cs} - initial error between current and desired puncturing ratio
        m = 1
                                                       -- index of current bit
        do while m <= N_{cs}
                   e = e - \frac{1}{2}a * y
                                                                    -- update error
                   do while e \le 0
                                                       -- check if bit number m should be repeated
                         repeat bit c_m
                                                       -- update error
                         e = e + \frac{2a}{a} N_{cs}
                   enddo
                   m = m + 1
                                                                                 -- next bit
        end do
end if
```

3. Text proposal for TS 25.222

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A repeated bit is placed directly after the original one.

6.2.3. Channel coding

The following channel coding schemes can be applied to transport channels.

- Convolutional coding
- Turbo coding
- No channel coding

The maximum encoding segment length for turbo coding is 5120 bits. In Real Time (RT) services a FEC coding is used, instead Non Real Time (NRT) services could be well managed with a proper combination of FEC and ARQ.

Table 6.2.3-1 Error Correction Coding Parameters

Transport channel type	Coding scheme	Coding rate
BCH		1/2
PCH		1/2
FACH		
RACH	Convolutional code	1/2, [2/3, 7/8] < Editor's note:
		the values in square brackets
		have not yet been approved.>
DCH		1/2, 1/3 or no coding
DCH	Turbo code	1/2, 1/3 of 110 could

Note 1: The exact physical layer encoding/decoding capabilities for different code types are FFS.

Note 2: In the UE the channel coding capability should be linked to the terminal class.

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6.2.3.2.1. Turbo coder

<Note: 4-state SCCC is not included in Release –99.>

<Note: It needs to be clarified from TSG SA what are the service specifications with respect to different qualities of service. The performance below BER of 10^{-6} needs to be studied if there is a requirement for this quality of services over the physical layer.>

For data services requiring quality of service between 10^{-3} and 10^{-6} BER inclusive, parallel concatenated convolutional code (PCCC) with 8-state constituent encoders is used.

The transfer function of the 8-state constituent code for PCCC is

$$G(D) = \left[1, \frac{n(D)}{d(D)}\right]$$

where,

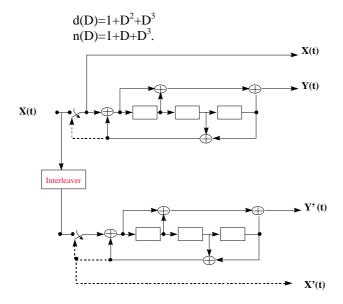


Figure 6-3. Structure of the 8 state PCCC encoder (dotted lines effective for trellis termination only)

The initial value of the shift registers of the PCCC encoder shall be all zeros.

The output of the PCCC encoder is punctured to produce coded bits corresponding to the desired code rate 1/3 or 1/2. For rate 1/3, none of the systematic or parity bits are punctured, and the output sequence is X(0), Y(0), Y(0), Y(0), X(1), Y(1), Y(1), etc. For rate 1/2, the parity bits produced by the constituent encoders are alternately punctured to produce the output sequence X(0), Y(0), X(1), Y(1), X(2), Y(2), X(3), Y'(3), etc.

The SCCC is a rate 1/3 SCCC, The outer code of the SCCC is a rate 2/3 obtained by puncturing a rate ½code with generating matrix

$$G^{(o)}(Z) = (1,(1+Z^2)/(1+Z+Z^2))$$

The rate 2/3 is obtained by puncturing every other parity-check bit. The inner code is a rate 1/2 systematic recursive convolutional code with the same previous generating matrix

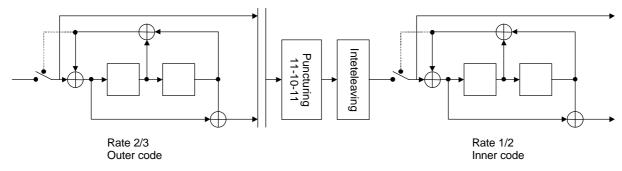
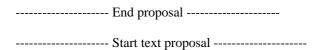


Figure 6-4. Structure of the 4 state SCCC encoder (dotted line effective for trellis termination only).



6.2.6. Rate matching

Rate matching means that bits on a transport channel are repeated or punctured. Higher layers assign a rate-matching attribute for each transport channel. This attribute is semi-static and can only be changed through higher layer signalling. The rate-matching attribute is used when the number of bits to repeat or puncture is calculated.

The number of bits on a transport channel can vary between different transmission time intervals. When the number of bits between different transmission time intervals in uplink is changed, bits are repeated to ensure that the total bit rate after second multiplexing is identical to the total channel bit rate of the allocated dedicated physical channels.

 N_{ii} : Number of bits in a radio frame before rate matching on transport channel i with transport format combination j.

 ΔN_{ij} : If positive - number of bits that should be repeated in each radio frame on transport channel i with transport format combination j.

If negative - number of bits that should be punctured in each radio frame on transport channel i with transport format combination j.

RM_i: Semi-static rate matching attribute for transport channel *i*. Signalled from higher layers.

PL: Puncturing limit for uplink. This value limit the amount of puncturing that can be applied in order to avoid multicode or enable the use of a higher spreading factor. Signalled from higher layers.

 $N_{data,j}$: Total number of bits that are available for a CCTrCH in a radio frame with transport format combination j.

T: Number of transport channels in a CCTrCH.

 Z_{mi} : Intermediate calculation variable.

 F_i : Number of radio frames in the transmission time interval of transport channel i.

k: Radio frame number in the transmission time interval of transport channel i (0 £ $k < F_i$).

q: Average puncturing distance.

- $I_F(k)$: The inverse interleaving function of the 1st interleaver (note that the inverse interleaving function is identical to the interleaving function itself for the 1st interleaver).
- S(k): The shift of the puncturing pattern for radio frame k.
- $TF_I(j)$: Transport format of transport channel ifor the transport format combination j.
- <u>Nes:</u> Number of bits before rate matching for each rate matching algorithm block
- <u>Nis:</u> Number of bits after rate matching for each rate matching algorithm block.

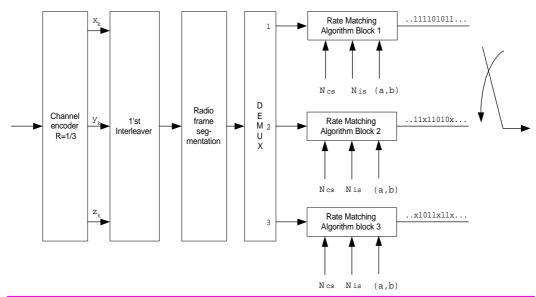


Figure 6-1. Overall rate matching block diagram after first interleaving where x denotes punctured bit.

6.2.6.1. Determination of rate matching parameters

The following relations are used when calculating the rate matching pattern:

$$Z_0 = 0$$

$$Z_{mj} = \begin{bmatrix} \sum_{i=1}^{m} RM_{i} \cdot N_{ij} \\ \sum_{i=1}^{T} RM_{i} \cdot N_{ij} \end{bmatrix} \text{ for all } m = 1 \dots T, \text{ where } \ddot{\boldsymbol{e}} \hat{\boldsymbol{u}} \text{ means round downwards}$$

$$\Delta N_{ij} = Z_{ij} - Z_{i-1,j} - N_{ij} \qquad \text{for all } i = 1 \dots T$$

Puncturing can be used to minimise the number of required transmission capacity. The maximum amount of puncturing that can be applied is signalled at connection setup from higher layers and denoted by PL. The possible values for N_{data} are always multiples of the dedicated physical channel with the smallest capacity, reduced by the amount of bits which carry the TFCI. The supported set of N_{data} , denoted SET0, depends on the UE capabilities. $N_{data,j}$ for the transport format combination j is determined by executing the following algorithm:

$$SET1 = \left\{ N_{data} in SET0 \text{ such that } N_{data} - PL \sum_{i=1}^{T} \frac{RM_{i}}{\min_{l} \left\{ RM_{l} \right\}} N_{ij} \text{ is non-negative} \right\}$$

 $N_{data,j} = min \ SET1$

The number of bits to be repeated or punctured, DN_{ij} , within one radio frame for each transport channel i is calculated with the relations given at the beginning of this section for all possible transport format combinations j and selected every radio frame.

```
For each radio frame, the rate matching pattern is calculated with the algorithm in Section 6.2.5.2., where DN = DN_{ij} and N = DN_{ij}
Additionally, the following parameters are needed:
6.2.6.1.1. Parameters for convolutional codes
'X' coded bits sequence from output 0 of convolutional coder in section 6.2.3.1.1.
'Y' coded bits sequence from output 1 of convolutional coder in section 6.2.3.1.1.
'Z' coded bits sequence from output 2 of convolutional coder in section 6.2.3.1.1.
N_{cs} = N_{ij}
N_{is} = N_{ij} + \mathbf{D}N_{ij}
(a,b)=(2,1) for the rate matching algorithm block 1.
q = [N_{ij}/(\Delta N_{ij})] where [] means round downwards, and [] means absolute value.
            Then q' = q - gcd(q, F_i)/F_I -- where gcd(q, F_I) means greatest common divisor of q and F_I -- note that q' is not an
integer, but a multiple of 1/8.
Else
            q' = q
endif
for l=0 to F_I -1
S(I_F([l*q'] \mod F_i)) = ([l*q'] div F_i) - -where [] means rounding upwards.
end for
6.2.6.1.2. Parameters for turbo codes
 X': systematic bits sequence of the upper constituent encoder s.t. (x_1, x_2, ..., x_k, ...) in section 6.2.3.2.1.
     : parity bits sequence of the upper constituent encoder s.t. (y_1, y_2, ..., y_k, ...) in section 6.2.3.2.1.
'Z': parity bits sequence of the lower constituent encoder s.t. (z_1, z_2, ..., z_k, ...) in section 6.2.3
If repetition is to be performed, such as DN_{ij} > 0, parameters for turbo codes are the same as parameter for convolutional codes.
If puncturing is to be performed, parameters are as follows.
N_{cs} = \ddot{\mathbf{e}} N_{ii} / 3 \hat{\mathbf{u}} where \ddot{\mathbf{e}} \hat{\mathbf{u}} means round downwards.
N_{is} = N_{cs} for 'X' sequence in rate matching algorithm block 1.
N_{is} = N_{cs} - \ddot{\mathbf{e}} - \mathbf{D}N_{ii}/2\hat{\mathbf{u}} for 'Y' sequence in rate matching algorithm block 2 where \ddot{\mathbf{e}} \hat{\mathbf{u}} means round downwards.
\underline{N_{is}} = N_{cs} - \underline{\epsilon}-\underline{DN_{ij}}/2\underline{\hat{u}} for 'Z' sequence in rate matching algorithm block 3 where \underline{\epsilon} \underline{\hat{u}} means round upwards.
\underline{q} = \mathbf{e} N_{cs}/(\mathbf{\hat{o}} N_{is} - N_{cs} \mathbf{\hat{o}}) \mathbf{\hat{u}}: q is the average puncturing distance of 'Y' or 'Z' sequence
\underline{(a,b)}=(2,1) for the rate matching algorithm block 2.
(a,b)=(1,1) for the rate matching algorithm block 3.
if(q \leq 2)
for l=0 to F_i-1
if('Y' sequence)
    S[I_{F}[(3\hat{l}+1) \bmod F_{i}]] = l \bmod 2;
   if('Z' sequence)
          S[I_F](3l+2) \mod F_i]] = l \mod 2;
 end for
<u>else</u>
if q is even
   then q' = q - gcd(q, F_i)/F_i -- where gcd(q, F_i) means greatest common divisor of q and F_i
                    -- note that q' is not an integer, but a multiple of 1/8
 else q' = q
```

```
endif

for l=0 to F_i-1

r = \mathbf{\acute{e}} \, l * q ' \mathbf{\grave{u}} mod \, F_i;

if ('Y' sequence)

S[I_F[(3r+1) \, mod \, F_i]] = \mathbf{\acute{e}} \, l * q ' \mathbf{\grave{u}} \, div \, F_i;

if ('Z' sequence)

S[I_F[(3r+2) \, mod \, F_i]] = \mathbf{\acute{e}} \, l * q ' \mathbf{\grave{u}} \, div \, F_i;

endfor

endif
```

6.2.6.2. Rate matching algorithm

All rate matching algorithm blocks in Figure 6-1 in section 6.2.6 use the same rate matching algorithm below with different parameters for convolutional codes and turbo codes, respectively.

For convolutional codes, in Figure 6-1, DEMUX is always at the position 1 and parameters for rate matching algorithm block 1 are fixed to the value given in section 6.2.6.2.1 or 6.2.6.3.1.

For turbo codes, in Figure 6-1, DEMUX repeats switching for puncturing or is always at the position 1 for repetition, respectively. Parameters for rate matching algorithm blocks are fixed to the value given in section 6.2.6.2.2 or 6.2.6.3.2.

Denote the bits before rate matching by:

```
c_1, c_2, c_3, \dots c_{NNcs}
```

The <u>common</u> rate matching rule <u>for both convolutional codes and turbo codes</u> is as follows:

if puncturing is to be performed

```
y = -\Delta N_{cs} - N_{is}
e = (2a*S(k)*y + b*N_{cs}) \mod 2a*N_{cs} -- initial error between current and desired puncturing ratio
   e=0 then e=a*N_{cs}

- index of current bit
do while m <= N_{CS}
e = e - \frac{2}{a} * y
                             -- update error
if e <= 0 then
                             -- check if bit number m should be punctured
puncture bit c_{\text{m}}
e = e + \frac{2a}{N_{CS}}
                        -- update error
end if
                             -- next bit
m = m + 1
end do
else
y = \frac{\Delta N}{1} - (N_{CS} - N_{is})
e = (\frac{2}{a} * S(k) * y + N_{cs}) \mod 2N_{cs}
                                        -- initial error between current and desired puncturing ratio
\underline{\text{if e=0 then e=a*N}_{\text{cs}}}
m = 1
                        -- index of current bit
do while m <= N_{cs}
e = e - \frac{2}{a} * y
                             -- update error
do while e <= 0
                             -- check if bit number m should be repeated
repeat bit c_m
e = e + \frac{2a*N_{cs}}{} -- update error
enddo
m = m + 1
                             -- next bit
end do
end if
```

A repeated bit is placed directly after the original one.

4. References

- [1] TS 25.212 (V2.0.1): "Multiplexing and channel coding (FDD)"
 [2] TS 25.222 (V2.0.2): "Multiplexing and channel coding (TDD)"
 [3] "Text proposal for rate matching algorithm for turbo codes in S25.212, S25.222", Samsung Electronics Co. and LGIC, WG1#7, R1-99b56.