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| **Company** | **RIL Number** | **Comment** |
| CATT | C234, C235, H661 | Rapporteur’s comment for the related RIL is listed as below:  Rapp: C234 and C235 are based on assumption of support N3C indirect path addition/change failure detection and reporting, while H661 propose to not have T421 for N3C case. The rapp understands if totally align with scenario 1, there should be path addition/change failure for scenario 2, but the issue is whether/how to determine change failure. In scenario 1, the remote UE may not be able to establish PC5 connection with relay UE successfully, so T421 is specified; however, in scenario 2, can we assume the N3C is stable without failure detection based on timer?  if companies think failure handling is necessary, we can have further discussion.  Indeed, C234 and C235 assume supporting N3C indirect path addition/change failure detection and reporting. But this does mean we need to have T421 for N3C case.  For the yellow marked part, CATT’s have the same point with HW that T421 for N3C case is not needed.  For the green marked part, our point is the case for N3C indirect path addition/change failure can really happen, but we don’t need to specify any method to determine the change failure (leave it to UE implementation).  When the case for N3C indirect path addition/change failure happens, our target is to capture some procedure description to guidance UE how to handle it (For this part, we can fully reuse scenario1 case).  As Rapporteur mentioned in the comment, the 1st question is for N3C whether the failure will happen for N3C indirect path addition/change case?  If the answer to 1st question is “will happen”, then we need to further check whether we leave the failure detection to UE implementation?  If the answer to 2nd questionis “leave the detection to UE implementation”, then we just add some text procedure description without introduce any new IE to finish the whole task (to guidance UE how to handle it). |
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