**3GPP TSG-RAN WG2 Meeting #113-eR2-210xxxx**

**Electronic, 25nd Jan– 05th Feb, 2021**

Agenda Item: 8.11.3.2

Source: Huawei, HiSilicon

Title: Text proposal for IDLE and INACTIVE positioning-Ph2

**Document for: Discussion**

# Introduction

During RAN2#113e, the following email discussion is triggered after the meeting

* [AT113-e][609][POS] Continued discussion of positioning in idle/inactive (Huawei)

Scope: Continue discussion of the issues from R2-2101230, and converge to an agreeable TP, taking as a baseline the principle that positioning in inactive is supported as recommended by RAN1. R2-2101229 to be taken into account.

Intended outcome: Endorsable TP

Deadline: Tuesday 2021-02-02 1200UTC

During the online discussion of the summary for the above email discussion, the following agreements have been made:

Agreements:

Proposal 1a: RAN2 confirms on the following recommendation of TSG RAN (17/17)

 Positioning in RRC\_INACTIVE

 DL, UL and DL+UL positioning methods

 UE-based and UE-assisted positioning solutions

 Support of UE positioning measurements for UEs in RRC\_INACTIVE state

 Options that can be considered include DL-PRS or DL-PRS and SSB

 Support of gNB positioning measurements for UEs in RRC\_INACTIVE state

Proposal 1b: RAN2 confirms on the following (17/17)

 Positioning in RRC\_IDLE

 It is feasible for a UE to perform DL positioning measurement in RRC\_IDLE state

 It is up to RAN2 to decide whether to support the enhancements of NR positioning reporting of DL positioning measurements and/or positioning estimates for RRC\_IDLE UEs.

Proposal2: RAN2 recommends the following for normative work for DL positioning

 The report of PRS measurement performed in RRC\_IDLE/INACTIVE when the UE is in RRC\_INACTIVE is supported (10/12)

 PRS measurement report and/or location estimate are sent from the UE to the gNB in RRC\_INACTIVE. RAN2 generally agree to do this by enhancing small data transmission in RRC\_INACTIVE (details of the use of SDT to be studied in the WI phase) (15/16)

Proposal4: For DL positioning in IDLE/INACTIVE, the followings are already supported for the current spec and can be reused:

 Current stage3 spec has already supported assistance data delivery for DL positioning during RRC\_CONNECTED and on-demand SI request in RRC\_IDLE/ INACITVE for IDLE/INACTIVE positioning. (14/14)

 Current stage3 spec already supports the transfer of RequestLocationInformation in RRC\_CONNECTED for PRS measurement in IDLE/INACTIVE. (14/14)

Proposal5: Support RAT-Independent positioning in RRC\_IDLE/INACTIVE. FFS the procedures that can be supported. (13/14)

Then, a further continuation of the email discussion is triggered during online to further polish on the text proposal based on the agreements.

* [AT113-e][609][POS] Continued discussion of positioning in idle/inactive (Huawei)

Scope: Continue discussion of the issues from R2-2101230, and converge to an agreeable TP, taking as a baseline the principle that positioning in inactive is supported as recommended by RAN1. R2-2101229 to be taken into account.

Intended outcome: Endorsable TP, in R2-2102100

Deadline: Tuesday 2021-02-02 1200UTC – extended to 2021-02-04 0200 UTC to finalise the TP

In this discussion, we continue the discussion for the text proposal for the TR for positioning enhancement in R17

## Contacts

|  |  |  |
| --- | --- | --- |
| **Company** | **Delegate name** | **Delegate email** |
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# Discussion

During RAN2#113e, the following agreement has been made on the downlink positioning in RRC\_INACTIVE

Agreements:

Proposal2: RAN2 recommends the following for normative work for DL positioning

 The report of PRS measurement performed in RRC\_IDLE/INACTIVE when the UE is in RRC\_INACTIVE is supported (10/12)

 PRS measurement report and/or location estimate are sent from the UE to the gNB in RRC\_INACTIVE. RAN2 generally agree to do this by enhancing small data transmission in RRC\_INACTIVE (details of the use of SDT to be studied in the WI phase) (15/16)

Proposal4: For DL positioning in IDLE/INACTIVE, the followings are already supported for the current spec and can be reused:

 Current stage3 spec has already supported assistance data delivery for DL positioning during RRC\_CONNECTED and on-demand SI request in RRC\_IDLE/ INACITVE for IDLE/INACTIVE positioning. (14/14)

 Current stage3 spec already supports the transfer of RequestLocationInformation in RRC\_CONNECTED for PRS measurement in IDLE/INACTIVE. (14/14)

For positioning in RRC\_INACTVE, we propose the following text proposal:

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| --- |
| 10.1 NR positioning for UEs in RRC\_INACTIVE state NR positioning for UEs in RRC\_INACTIVE state is recommended for normative work, including   * + DL, UL and DL+UL positioning methods   + UE-based and UE-assisted positioning solutions   + Support of UE positioning measurements for UEs in RRC\_inactive state     - Options that can be considered include DL-PRS or DL-PRS and SSB   + Support of gNB positioning measurements for UEs in RRC\_inactive state   The details of how to enable the UE positioning in RRC\_ INACTIVE state can be further discussed during normative work. These details may include, but are not limited to the following aspects:   * + UL reference signals (e.g., SRS for positioning, PRACH preambles) for UL measurements   + Signalling and procedures for support the assistance data delivery, DL-PRS configuration, UL reference signals for positioning resource configuration, measurement reporting, which may be developed based on the enhancements of existing signalling and procedures (e.g., existing 2-step and/or 4-step PRACH procedures, paging procedure, small data transmission).   The following procedures are recommended for normative work for DL positioning methods in RRC\_INACTIVE:   * + Reporting of PRS measurement and/or location estimate performed in RRC\_INACTIVE when the UE is in RRC\_INACTIVE.     - The reporting of PRS measurement and/or location estimate performed in RRC\_IDLE/RRC\_INACTIVE when the UE is in RRC\_INACTIVE is enabled by enhancing small data transmission in RRC\_INACTIVE.   NOTE: The following procedures are considered to have already been supported and can be reused for DL positioning in RRC\_INACTIVE   * + - On-demand SI request in RRC\_INACTIVE for assistance data delivery by broadcast in RRC\_INACTIVE     - *ProvideAssistanceData* in RRC\_CONNECTED for PRS configuration in RRC\_INACTIVE downlink positioning   *RequestLocationInformation* can be sent in RRC\_CONNECTED for PRS measurement or location estimate in RRC\_INACTIVE |

**Question1: Do companies think the above text proposal has faithfully captured the agreement made during online for RRC\_INACTIVE positioning?**

|  |  |  |
| --- | --- | --- |
| **Company** | **Yes/No** | **Comments** |
| Ericsson | No | As discussed online, the agreement is to also capture “details of the use of SDT to be studied in the WI phase”  Hence we think the TP should be as below.  The following is recommended for further study during normative work for DL positioning methods in RRC\_INACTIVE:  - Use of Small Data Transmission (SDT) framework in RRC\_INACTIVE for positioning |
| vivo | Yes |  |
| Xiaomi | Yes with comment | * + - The reporting of PRS measurement and/or location estimate performed in RRC\_IDLE/RRC\_INACTIVE when the UE is in RRC\_INACTIVE is enabled by enhancing small data transmission in RRC\_INACTIVE.   The RRC\_IDLE should be deleted. |
| CATT | Yes, but with some modifications | We prefer to make the following modifications:  NOTE: The following procedures are considered to have already been supported and can be reused for DL positioning in RRC\_INACTIVE   * + - On-demand SI request in RRC\_INACTIVE for assistance data delivery by broadcast in RRC\_INACTIVE     - *ProvideAssistanceData* in RRC\_CONNECTED for PRS configuration used in RRC\_INACTIVE downlink positioning   *RequestLocationInformation* can be sent in RRC\_CONNECTED for PRS measurement or location estimate performed in RRC\_INACTIVE |
| Lenovo, Motorola Mobility | Yes with editorial comment | Suggest another editorial comment, all instances of “PRS” can be changed to “DL-PRS” to align with RAN1’s text. |

For positioning in RRC\_IDLE, we propose the following text proposal:

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| 10.9 DL positioning measurement in RRC\_IDLE state From a physical layer perspective, it is feasible for a UE to perform DL positioning measurement in RRC\_IDLE state.   * + Note: This does not imply that measurements have to be reported in RRC\_IDLE state.   The following procedures are considered as feasible for DL positioning methods in RRC\_IDLE:   * + Reporting of PRS measurement and/or location estimate performed in RRC\_IDLE when the UE is in RRC\_CONNETED.   NOTE: The following procedures are considered to have already been supported and can be reused for positioning in RRC\_IDLE   * + - On-demand SI request in RRC\_IDLE for assistance data delivery by broadcast in RRC\_IDLE     - *ProvideAssistanceData* can be sent in RRC\_CONNECTED for PRS configuration in RRC\_IDLE downlink positioning     - *RequestLocationInformation* can be sent in RRC\_CONNECTED for PRS measurement and/or location estimate in RRC\_IDLE |

**Question2: Do companies think the above text proposal has faithfully captured the agreement during online for RRC\_IDLE positioning?**

|  |  |  |
| --- | --- | --- |
| **Company** | **Yes/No** | **Comments** |
| Ericsson | Yes |  |
| Xiaomi | Yes |  |
| CATT | Yes, but with some modifications | We prefer to make the following modifications:  NOTE: The following procedures are considered to have already been supported and can be reused for positioning in RRC\_IDLE   * + - On-demand SI request in RRC\_IDLE for assistance data delivery by broadcast in RRC\_IDLE     - *ProvideAssistanceData* can be sent in RRC\_CONNECTED for PRS configuration used in RRC\_IDLE downlink positioning     - *RequestLocationInformation* can be sent in RRC\_CONNECTED for PRS measurement and/or location estimate performed in RRC\_IDLE |
| Lenovo, Motorola Mobility | Yes |  |

Then, for RAT-independent positioning, during the online discussion, the following agreements have been made:

Agreements:

Proposal5: Support RAT-Independent positioning in RRC\_IDLE/INACTIVE. FFS the procedures that can be supported. (13/14)

Then, we propose the following text proposal for the above agreement:

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| --- |
| 10.y RAT-Independent positioning RAT-Independent positioning in RRC\_IDLE/INACTIVE is recommended for normative work. The exact procedures that can be supported for RAT-Independent positioning in RRC\_IDLE/INACTVE can be further studied. |

**Question3: Do companies think the above text proposal has faithfully captured the agreement during online for RAT-independent positioning?**

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| --- | --- | --- |
| **Company** | **Yes/No** | **Comments** |
| vivo | Yes |  |
| Xiaomi | Yes |  |
| Lenovo, Motorola Mobility | Yes |  |

During the first phase of [609], we have discussed on the definition of IDLE/INACTIVE positioning, with the following text proposal

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| 2 References The following documents contain provisions which, through reference in this text, constitute provisions of the present document.  - References are either specific (identified by date of publication, edition number, version number, etc.) or non‑specific.  - For a specific reference, subsequent revisions do not apply.  - For a non-specific reference, the latest version applies. In the case of a reference to a 3GPP document (including a GSM document), a non-specific reference implicitly refers to the latest version of that document *in the same Release as the present document*.  [1] 3GPP TR 21.905: "Vocabulary for 3GPP Specifications".  [2] RP-193237: "new SID on NR Positioning Enhancements".  [3] 3GPP TR 38.855: "Study on NR Positioning (Release 16)".  [4] R1-2009433 Evaluation results for Rel-16 positioning and Rel-17 enhancement Huawei, HiSilicon  [5] R1-2007665 Evaluation of NR positioning performance vivo  [6] R1-2007720 Evaluation of achievable positioning accuracy BUPT  [7] R1-2007754 Evaluation of achievable accuracy and latency ZTE  [8] R1-2007859 Discussion of evaluation of NR positioning performance CATT  [9] R1-2007908 NLOS Identification and Mitigation FUTUREWEI  [10] R1-2009390 Update of Evaluation Results for NR Positioning Performance in I-IoT Scenarios Intel Corporation  [11] R1-2007997 NR Positioning Latency Evaluations Lenovo, Motorola Mobility  [12] R1-2008225 Evaluation of NR positioning in IIOT scenario OPPO  [13] R1-2009555 Results on evaluation of achievable positioning accuracy and latency Nokia, Nokia Shanghai Bell  [14] R1-2009502 Discussion on Performance evaluation of Rel-17 positioning Sony  [15] R1-2008416 Discussions on evaluation of achievable positioning accuracy and latency for NR positioning LG Electronics  [16] R1-2008489 Evaluation of achievable positioning latency InterDigital, Inc.  [17] R1-2009708 Evaluation of achievable Positioning Accuracy & Latency Qualcomm Incorporated  [18] R1-2009428 Evaluation of positioning enhancements Fraunhofer IIS, Fraunhofer HHI  [19] R1-2008720 Positioning evaluation results on potential enhancements for additional use cases CeWiT  [20] R1-2008764 Evaluation of achievable positioning accuracy and latency Ericsson  [21] R1-2008765 Potential positioning enhancements Ericsson  [22] R1-2007666 Discussion on potential positioning enhancements vivo  [23] R1-2005380 Evaluation of achievable positioning accuracy and latency vivo  [24] 3GPP TS 22.261 Service requirements for the 5G system; Stage 1 (Release 17)  [25] RP-202094 Revised SID: Study on NR Positioning Enhancements CATT, Intel Corporation  [26] 3GPP TS 38.901 Study on channel model for frequencies from 0.5 to 100 GHz (Release 16)  [xx] 3GPP TS 24.571 Control plane Location Services (LCS) procedures (Release 16)  ===================================NEXT CHANGE=================================== 10.x Scope of RRC\_IDLE/INACTIVE positioning The following UE positioning procedures are under the scope of RRC\_IDLE/RRC\_INACTIVE positioning if any of them are performed when the UE is in RRC\_IDLE/RRC\_INACTIVE.   * NAS-transported positioning signalling   + LCS messages defined in Clause 4.1.2 for location services in TS 24.571 [xx]   + LPP signaling for positioning (e.g., Capability transfer, Assistance data transfer, Location information transfer) * NRPPa   + E-CID information transfer (UE-associated)   + Positioning information transfer (UE-associated)   + Measurement information transfer (non-UE-associated) * Uu Signaling and procedure   + RRC signaling for positioning (e.g., posSRS configuration)   + MAC procedure/L1 signaling (e.g., activation/deactivation for semi-persistent/aperiodic posSRS)   + Transmission of UL-PRS and reception of DL-PRS   + Reception for assistance information broadcast   ====================================END OF CHANGE================================ |

The main difference with the first version of the text proposal [1] is that a separate section 7.x was created to capture the scope of discussion for IDLE/INACTIVE positioning.

**Question4: Do companies think the current structure of the text proposal is OK?**

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| **Company** | **Yes/No** | **Comments** |
| vivo | Yes |  |
| Xiaomi | Yes |  |

# Text proposal history

[1] Version 1: [R2-2101229](file:///C:\Users\mtk16923\Documents\3GPP%20Meetings\202101-02%20-%20RAN2_113-e,%20Online\Extracts\R2-2101229%20TP%20for%20IDLE%20and%20INACTIVE%20postiioning.docx) TP for IDLE and INACTIVE postiioning Huawei, HiSilicon discussion Rel-17 FS\_NR\_pos\_enh

[2] Version 2: [R2-2102100](file:///C:\Users\mtk16923\Documents\3GPP%20Meetings\202101-02%20-%20RAN2_113-e,%20Online\Extracts\R2-2102100%20TP%20for%20IDLE%20and%20INACTIVE%20postioning.docx) (TP from [609]) Huawei, HiSilicon discussion Rel-17 FS\_NR\_pos\_enh