

TSG-RAN Working Group 1 meeting #9  
Dresden, Germany  
November 30 – December 3, 1999

***TSGR1#9(99)i63***

**Agenda item:**

**Source:** Ericsson

**Title:** CR 25.214-007: Removal of open loop power control

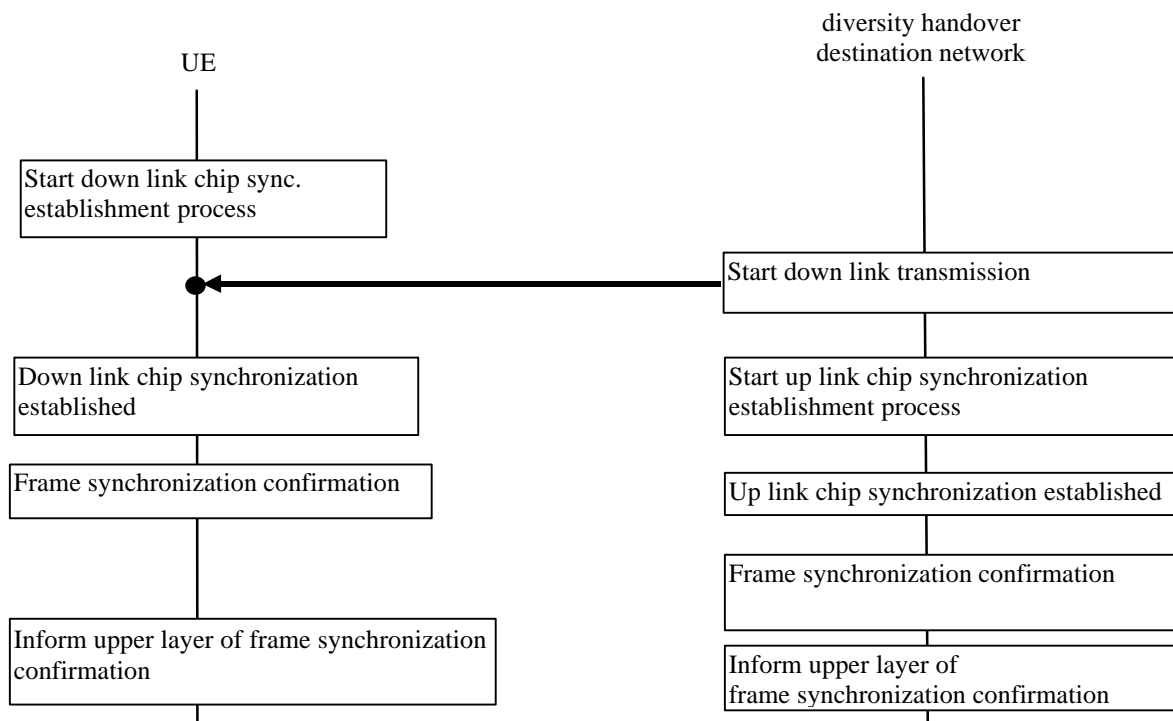
**Document for:** Decision

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At WG1#8 it was decided to move the responsibility to define open loop power control to WG2. This decision is reflected in CR 25.214-009 for the RACH procedure. However, the open loop power control is currently described in more parts of the specification. Those sections are addressed by this CR.



- a) Based on the handover destination CPICH reception timing, the UE establishes chip synchronisation of downlink channels from handover destination cell. Frame synchronization can be confirmed using the Frame Synchronization Word. Successful frame synchronization is confirmed and reported to the higher layers when  $S_R$  successive frames have been confirmed to be frame synchronized. Otherwise, frame synchronization failure is reported to the higher layers.



**Figure 1 : Synchronization establishment flow upon intra/inter-cell soft handover**

During a connection, in some cases the UE is allowed to change its transmission timing. When the UE is not in soft handover or in soft handover with cells that all are known to have the same timing reference, the UE may adjust its DPDCH/DPCCH transmission time instant. <Note: maximum rate of the adjustment should be specified in R4> Otherwise, the UE may not adjust its DPDCH/DPCCH transmission time instant.

## 5 Power control

### 5.1 Uplink power control

#### 5.1.1 PRACH

##### 5.1.1.1 General

[The power control during the physical random access procedure is described in clause 6. The setting of power of the message control and data parts is described in the next sub-clause.](#)

~~The transmitter power of UE shall be calculated by following equation:~~

$$P_{\text{RACH}} = L_{\text{Perch}} + I_{\text{BTS}} + \text{Constant value}$$

where,

$P_{\text{RACH}}$ : transmitter power level in dBm,

$L_{\text{Perch}}$ : measured path loss in dB,

$I_{\text{BTS}}$ : interference signal power level at BTS in dBm, which is broadcasted on BCH,

Constant value: This value shall be designated via Layer 3 message (operator matter).

### 5.1.1.2 Setting of PRACH control and data part power difference

The message part of the uplink PRACH channel shall employ gain factors to control the control/data part relative power similar to the uplink dedicated physical channels. Hence, section 5.1.2.4 applies also for the RACH message part, with the differences that:

- $b_c$  is the gain factor for the control part (similar to DPCCH),
- $b_d$  is the gain factor for the data part (similar to DPDCH),
- no inner loop power control is performed.

## 5.1.2 DPCCH/DPDCH

### 5.1.2.1 General

The uplink transmit power control procedure controls simultaneously the power of a DPCCH and its corresponding DPDCHs. The power control loop adjusts the power of the DPCCH and DPDCHs with the same amount. The relative transmit power offset between DPCCH and DPDCHs is determined by the network and signalled to the UE using higher layer signalling.

### 5.1.2.2 Ordinary transmit power control

#### 5.1.2.2.1 General

The initial uplink transmit power ~~to use is decided using an open loop power estimate, similar to the random access procedure.~~ *< Editor's note: This needs to be elaborated, how is the estimate derived? >* is set by higher layers.

The maximum transmission power at the maximum rate of DPDCH is designated for uplink and control must be performed within this range. *< Editor's note: The necessity of this range needs to be confirmed. >* The maximum transmit power value of the inner-loop TPC is set by the network using higher layer signalling.

The uplink inner-loop power control adjusts the UE transmit power in order to keep the received uplink signal-to-interference ratio (SIR) at a given SIR target,  $SIR_{\text{target}}$ .

The serving cells (cells in the active set) should estimate signal-to-interference ratio  $SIR_{\text{est}}$  of the received uplink DPCH. The serving cells then generates TPC commands and transmits the commands once per slot according to the following rule: if  $SIR_{\text{est}} > SIR_{\text{target}}$  then the TPC command to transmit is "0", while if  $SIR_{\text{est}} < SIR_{\text{target}}$  then the TPC command to transmit is "1".

Upon reception of one or more TPC commands in a slot, the UE derives a single TPC command,  $TPC_{\text{cmd}}$ , for each slot, combining multiple TPC commands if more than one is received in a slot. Two algorithms shall be supported by the UE for deriving a  $TPC_{\text{cmd}}$ , as described in subclauses 5.1.2.2.2 and 5.1.2.2.3. Which of these two algorithms is used is an UE-specific parameter and is under the control of the UTRAN.

The step size  $\Delta_{\text{TPC}}$  is a UE specific parameter, under the control of the UTRAN that can have the values 1 dB or 2 dB.

After deriving of the combined TPC command  $TPC\_cmd$  using one of the two supported algorithms, the UE shall adjust the transmit power of the uplink dedicated physical channels with a step of  $\Delta_{TPC}$  dB according to the TPC command. If  $TPC\_cmd$  equals 1 then the transmit power of the uplink DPCCH and uplink DPDCHs shall be increased by  $\Delta_{TPC}$  dB. If  $TPC\_cmd$  equals -1 then the transmit power of the uplink DPCCH and uplink DPDCHs shall be decreased by  $\Delta_{TPC}$  dB. If  $TPC\_cmd$  equals 0 then the transmit power of the uplink DPCCH and uplink DPDCHs shall be unchanged.