



## CHANGE REQUEST

# **25.453 CR 74** # rev **1** # Current version: **6.5.0** #

For **HELP** on using this form, see bottom of this page or look at the pop-up text over the # symbols.

**Proposed change affects:** UICC apps  ME  Radio Access Network  Core Network

<b>Title:</b>	#	Introduction of the requested accuracy and an indication of achieved accuracy in Position Calculation procedure over I <sub>upc</sub> interface
<b>Source:</b>	#	RAN3
<b>Work item code:</b>	#	TEI-6
		<b>Date:</b> # 21/07/2004
<b>Category:</b>	#	<b>B</b>
		<p>Use <u>one</u> of the following categories:</p> <p><b>F</b> (correction)</p> <p><b>A</b> (corresponds to a correction in an earlier release)</p> <p><b>B</b> (addition of feature),</p> <p><b>C</b> (functional modification of feature)</p> <p><b>D</b> (editorial modification)</p> <p>Detailed explanations of the above categories can be found in 3GPP <a href="#">TR 21.900</a>.</p>
		<p><b>Release:</b> # Rel-6</p> <p>Use <u>one</u> of the following releases:</p> <p>Ph2 (GSM Phase 2)</p> <p>R96 (Release 1996)</p> <p>R97 (Release 1997)</p> <p>R98 (Release 1998)</p> <p>R99 (Release 1999)</p> <p>Rel-4 (Release 4)</p> <p>Rel-5 (Release 5)</p> <p>Rel-6 (Release 6)</p> <p>Rel-7 (Release 7)</p>

<b>Reason for change:</b>	#	<p>As confirmed by SA2 LS (R3-040638/S2-040907) and the approval of CR186rev7 at SA#23 (SP-040207) against TS 23.271 v6.6.0, GMLC may not be able to evaluate what is the exact accuracy, uncertainty and potential confidence of the position estimate returned by RAN. This is because the GMLC is unaware of the radio access technology that was used to position the UE. Thus, as the RAN always try to return a best-effort position estimate, if the requested accuracy cannot be fulfilled, the GMLC do not know whether the returned position estimate fulfils or not the requested accuracy.</p>
<b>Summary of change:</b>	#	<p>Insertion of the <i>Horizontal Accuracy Code</i> IE and the <i>Vertical Accuracy Code</i> IE in the POSITION CALCULATION REQUEST message.</p> <p>If the RNC has requested an accuracy for the position estimate, the POSITION CALCULATION RESPONSE message shall include an indication whether or not the returned position estimate satisfies the requested accuracy.</p>
<b>Consequences if not approved:</b>	#	<p>Misalignment between PCAP, RANAP and TS 23.271. GMLC cannot know if the returned position estimate fulfils or not the accuracy the GMLC asked for in the location request.</p>

<b>Clauses affected:</b>	#	<p>8.2.2, 8.2.4, 9.1.3, 9.1.4, 9.3.3, 9.3.4, 9.3.6 new: 9.2.2.xx, 9.2.2.yy, 9.2.2.zz</p>								
<b>Other specs affected:</b>	#	<table border="1" style="display: inline-table; vertical-align: middle;"> <tr> <td style="width: 20px; text-align: center;">Y</td> <td style="width: 20px; text-align: center;">N</td> </tr> <tr> <td style="text-align: center;"><input type="checkbox"/></td> <td style="text-align: center;"><input checked="" type="checkbox"/></td> </tr> </table> Other core specifications # <table border="1" style="display: inline-table; vertical-align: middle; margin-left: 20px;"> <tr> <td style="width: 20px; text-align: center;">Y</td> <td style="width: 20px; text-align: center;">N</td> </tr> <tr> <td style="text-align: center;"><input type="checkbox"/></td> <td style="text-align: center;"><input checked="" type="checkbox"/></td> </tr> </table> Test specifications #	Y	N	<input type="checkbox"/>	<input checked="" type="checkbox"/>	Y	N	<input type="checkbox"/>	<input checked="" type="checkbox"/>
Y	N									
<input type="checkbox"/>	<input checked="" type="checkbox"/>									
Y	N									
<input type="checkbox"/>	<input checked="" type="checkbox"/>									

**Other comments:** ⌘

**How to create CRs using this form:**

Comprehensive information and tips about how to create CRs can be found at <http://www.3gpp.org/specs/CR.htm>. Below is a brief summary:

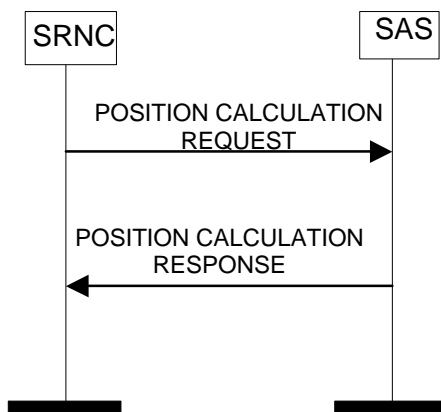
- 1) Fill out the above form. The symbols above marked ⌘ contain pop-up help information about the field that they are closest to.
- 2) Obtain the latest version for the release of the specification to which the change is proposed. Use the MS Word "revision marks" feature (also known as "track changes") when making the changes. All 3GPP specifications can be downloaded from the 3GPP server under <ftp://ftp.3gpp.org/specs/> For the latest version, look for the directory name with the latest date e.g. 2001-03 contains the specifications resulting from the March 2001 TSG meetings.
- 3) With "track changes" disabled, paste the entire CR form (use CTRL-A to select it) into the specification just in front of the clause containing the first piece of changed text. Delete those parts of the specification which are not relevant to the change request.

## 8.2 Position Calculation

### 8.2.1 General

The purpose of the Position Calculation procedure is to enable an SRNC to query an SAS for a position estimate of a UE. The procedure uses connectionless signalling.

### 8.2.2 Successful Operation



**Figure 1: Position Calculation procedure, Successful Operation**

The procedure is initiated with a POSITION CALCULATION REQUEST message sent from the SRNC to the SAS. When the SAS receives the POSITION CALCULATION REQUEST message, it shall calculate the UE position based on the provided measurement data.

If the *Initial UE Position Estimate* IE is included in the POSITION CALCULATION REQUEST message, the SAS shall use this value for the calculation of the UE Position Estimate in case of A-GPS positioning methods are used. The SAS may use this value for the calculation of the UE Position when any other methods are used.

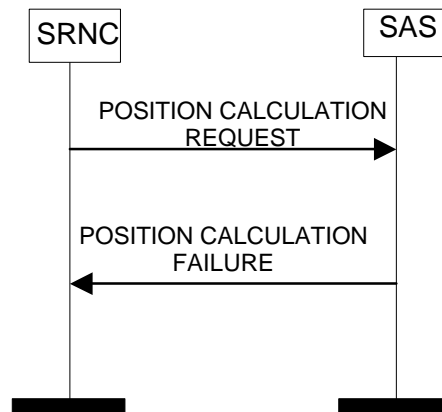
If the *Horizontal Accuracy Code* IE and possibly the *Vertical Accuracy Code* IE are included in the POSITION CALCULATION REQUEST message, the SAS shall use these values in order to assess whether the resulting position estimation fulfills the requested accuracy.

#### Response Message:

If the SAS was able to calculate the position estimate, it shall respond with a POSITION CALCULATION RESPONSE message.

If at least the *Horizontal Accuracy Code* IE was included in the POSITION CALCULATION REQUEST message and the calculated position estimate fulfils the requested accuracy, the *Accuracy Fulfilment Indicator* IE with the value "requested accuracy fulfilled" shall be included in the POSITION CALCULATION RESPONSE message. If the calculated position estimate does not fulfil the requested accuracy, the *Accuracy Fulfilment Indicator* IE with the value "requested accuracy not fulfilled" shall be included in the POSITION CALCULATION RESPONSE message.

### 8.2.3 Unsuccessful Operation



**Figure 2: Position Calculation procedure, Unsuccessful Operation**

If the SAS is unable to perform the position estimate for any reason, it shall return a POSITION CALCULATION FAILURE message to the SRNC.

Typical cause values are:

- Invalid reference information;
- Position calculation error: invalid GPS measured results;
- Initial UE Position Estimate missing;
- Processing Overload;
- Hardware Failure;
- O&M Intervention.

### 8.2.4 Abnormal Conditions

If the *Vertical Accuracy Code IE* is included and the *Horizontal Accuracy Code IE* is not included in the POSITION CALCULATION REQUEST message, the SAS shall reject the procedure.-

**/\* Partly omitted \*/**

## 9.1.3 POSITION CALCULATION REQUEST

Table 6

IE/Group Name	Presence	Range	IE type and reference	Semantics description	Criticality	Assigned Criticality
Message Type	M		9.2.2.24		YES	reject
Transaction ID	M		9.2.2.28		–	
Initial UE Position Estimate	O		Geographical Area 9.2.2.6		YES	reject
<b>GPS Measured Results</b>		<i>0..&lt;maxNoOfSets &gt;</i>			GLOBAL	reject
>GPS Measured Results	M		9.2.2.12		–	
<b>Cell-ID Measured Results Sets</b>		<i>0..&lt;maxNoOfMeasurements&gt;</i>			GLOBAL	reject
>Cell-ID Measured Results Info List	M		9.2.2.31		–	
<b>OTDOA Measurement Group</b>		<i>0..1</i>			YES	reject
>OTDOA Reference Cell Info	M		9.2.2.34		–	
<b>&gt;OTDOA Neighbour Cell Info List</b>		<i>1..&lt;maxNoOfMeasNC ell &gt;</i>			–	
>>OTDOA Neighbour Cell Info	M		9.2.2.33		–	
<b>&gt;OTDOA Measured Results Sets</b>		<i>1..&lt;maxNoOfMeasurements&gt;</i>			–	
>>OTDOA Measured Results Info List	M		9.2.2.32		–	
<a href="#">Horizontal Accuracy Code</a>	<u>O</u>		<a href="#">9.2.2.xx</a>		<a href="#">YES</a>	<a href="#">ignore</a>
<a href="#">Vertical Accuracy Code</a>	<u>O</u>		<a href="#">9.2.2.yy</a>		<a href="#">YES</a>	<a href="#">ignore</a>

Table 7

Range bound	Explanation
MaxNoOfMeasNCell	Maximum number of neighbouring cells on which information can be reported. The value of MaxNoOfMeasCell is 32.
MaxNoOfSets	Maximum number of sets of Measured Results included in the Position Calculation Request message. The value for maxNoOfSets is 3.
maxNoOfMeasurements	Maximum number of Measurements of Cell-ID Measured Results Info List and OTDOA Measured Results Info List included in the Position Calculation Request message. The value for maxNoOfMeasurements is 16.

## 9.1.4 POSITION CALCULATION RESPONSE

Table 8

IE/Group Name	Presence	Range	IE type and reference	Semantics description	Criticality	Assigned Criticality
Message Type	M		9.2.2.24		YES	reject
Transaction ID	M		9.2.2.28		–	
UE Position Estimate	M		Geographical Area 9.2.2.6		YES	ignore
Criticality Diagnostics	O		9.2.2.4		YES	ignore
<a href="#">Accuracy Fulfilment Indicator</a>	<a href="#">O</a>		<a href="#">9.2.2.zz</a>		<a href="#">YES</a>	<a href="#">ignore</a>

/\* Partly omitted \*/

9.2.2.xx Horizontal Accuracy CodeTable x1

<u>IE/Group Name</u>	<u>Presence</u>	<u>Range</u>	<u>IE Type and Reference</u>	<u>Semantics Description</u>
<u>Horizontal Accuracy Code</u>	<u>M</u>		<u>INTEGER(0..127)</u>	<u>The requested accuracy "r" is derived from the "Horizontal Accuracy Code" k by <math>r = 10x(1.1^k - 1)</math>.</u>

9.2.2.yy Vertical Accuracy CodeTable x2

<u>IE/Group Name</u>	<u>Presence</u>	<u>Range</u>	<u>IE Type and Reference</u>	<u>Semantics Description</u>
<u>Vertical Accuracy Code</u>	<u>M</u>		<u>INTEGER(0..127)</u>	<u>The requested accuracy "v" is derived from the "Vertical Accuracy Code" k by <math>v = 45x(1.025^k - 1)</math>.</u>

9.2.2.zz Accuracy Fulfilment Indicator

This IE indicates whether the returned position estimate satisfies the requested accuracy or not.

Table x3

<u>IE/Group Name</u>	<u>Presence</u>	<u>Range</u>	<u>IE Type and Reference</u>	<u>Semantics Description</u>
<u>Accuracy Fulfilment Indicator</u>	<u>M</u>		<u>ENUMERATED (requested accuracy fulfilled, requested accuracy not fulfilled, ...)</u>	

/\* Partly omitted \*/



### 9.3.3 PDU Definitions

```

-- *****
--
-- PDU definitions for PCAP.
--
-- *****

PCAP-PDU-Contents {
itu-t (0) identified-organization (4) etsi (0) mobileDomain (0)
umts-Access (20) modules (3) pcap(4) version1 (1) pcap-PDU-Contents (1) }

DEFINITIONS AUTOMATIC TAGS ::=

BEGIN

-- *****
--
-- IE parameter types from other modules.
--
-- *****

IMPORTS
    Cause,
    CriticalityDiagnostics,
    GPS-UTRAN-TRU,
    InformationExchangeID,
    InformationReportCharacteristics,
    InformationType,
    MeasuredResultsList,
    RequestedDataValue,
    RequestedDataValueInformation,
    UE-PositionEstimate,
    CellId-MeasuredResultsSets,
    OTDOA-MeasurementGroup,
    AccuracyFulfilmentIndicator,
    HorizontalAccuracyCode,
    VerticalAccuracyCode
FROM PCAP-IEs

    TransactionID
FROM PCAP-CommonDataTypes

    ProtocolExtensionContainer{},
    ProtocolIE-ContainerList{},
    ProtocolIE-Container{},
    PrivateIE-Container{},
    PCAP-PRIVATE-IES,
    PCAP-PROTOCOL-EXTENSION,
    PCAP-PROTOCOL-IES
FROM PCAP-Containers

    id-Cause,
    id-CriticalityDiagnostics,
    id-GPS-UTRAN-TRU,
    id-InformationExchangeID,
    id-InformationExchangeObjectType-InfEx-Rprt,
    id-InformationExchangeObjectType-InfEx-Rqst,
    id-InformationExchangeObjectType-InfEx-Rsp,
    id-InformationReportCharacteristics,
    id-InformationType,
    id-GPS-MeasuredResultsList,
    id-RequestedDataValue,
    id-RequestedDataValueInformation,
    id-TransactionID,
    id-UE-PositionEstimate,
    id-CellId-MeasuredResultsSets,
    id-OTDOA-MeasurementGroup,
    id-AccuracyFulfilmentIndicator,
    id-HorizontalAccuracyCode,
    id-VerticalAccuracyCode
FROM PCAP-Constants;

-- *****
--
-- POSITION CALCULATION REQUEST

```

```

--
-- *****
PositionCalculationRequest ::= SEQUENCE {
    protocolIEs          ProtocolIE-Container      { {PositionCalculationRequestIEs} },
    protocolExtensions   ProtocolExtensionContainer { {PositionCalculationRequestExtensions} }
    OPTIONAL,
    ...
}

PositionCalculationRequestIEs PCAP-PROTOCOL-IES ::= {
    { ID id-UE-PositionEstimate          CRITICALITY reject  TYPE UE-PositionEstimate
      PRESENCE optional } |
    { ID id-GPS-MeasuredResultsList      CRITICALITY reject  TYPE MeasuredResultsList
      PRESENCE optional },
    ...
}

PositionCalculationRequestExtensions PCAP-PROTOCOL-EXTENSION ::= {
    { ID id-CellId-MeasuredResultsSets   CRITICALITY reject  EXTENSION CellId-MeasuredResultsSets
      PRESENCE optional } |
    { ID id-OTDOA-MeasurementGroup       CRITICALITY reject  EXTENSION OTDOA-MeasurementGroup
      PRESENCE optional } |
    { ID id-HorizontalAccuracyCode       CRITICALITY ignore  EXTENSION HorizontalAccuracyCode
      PRESENCE optional } |
    { ID id-VerticalAccuracyCode         CRITICALITY ignore  EXTENSION VerticalAccuracyCode
      PRESENCE optional },
    ...
}

-- *****
--
-- POSITION CALCULATION RESPONSE
--
-- *****

PositionCalculationResponse ::= SEQUENCE {
    protocolIEs          ProtocolIE-Container      { {PositionCalculationResponseIEs} },
    protocolExtensions   ProtocolExtensionContainer { {PositionCalculationResponseExtensions} }
    OPTIONAL,
    ...
}

PositionCalculationResponseIEs PCAP-PROTOCOL-IES ::= {
    { ID id-UE-PositionEstimate          CRITICALITY ignore  TYPE UE-PositionEstimate          PRESENCE
    mandatory } |
    { ID id-CriticalityDiagnostics       CRITICALITY ignore  TYPE CriticalityDiagnostics          PRESENCE
    optional },
    ...
}

PositionCalculationResponseExtensions PCAP-PROTOCOL-EXTENSION ::= {
    { ID id-AccuracyFulfilmentIndicator  CRITICALITY ignore  EXTENSION AccuracyFulfilmentIndicator
      PRESENCE optional },
    ...
}

/* Partly omitted */

```

### 9.3.4 Information Element Definitions

```

-- *****
--
-- Information Element Definitions
--
-- *****

PCAP-IEs {
    itu-t (0) identified-organization (4) etsi (0) mobileDomain (0)
    umts-Access (20) modules (3) pcap(4) version1 (1) pcap-IEs (2) }

DEFINITIONS AUTOMATIC TAGS ::=

BEGIN

IMPORTS
    maxNrOfErrors,

```

```

maxSat,
maxSatAlmanac,
maxNrOfLevels,
maxNrOfMeasNCell,
maxNrOfMeasurements,
maxNrOfPoints,
maxNrOfExpInfo,
maxNrOfSets
FROM PCAP-Constants

Criticality,
ProcedureCode,
ProtocolIE-ID,
TransactionID,
TriggeringMessage
FROM PCAP-CommonDataTypes

ProtocolExtensionContainer{},
PCAP-PROTOCOL-EXTENSION
FROM PCAP-Containers;

-- *****
--
-- Accuracy Fulfilment Indicator
--
-- *****

AccuracyFulfilmentIndicator ::= ENUMERATED{
    requested-Accuracy-Fulfilled,
    requested-Accuracy-Not-Fulfilled,
    ...
}

-- *****
--
-- Almanac and Satellite Health SIB
--
-- *****

/* Partly omitted */

-- *****
--
-- Requested Data Value Information
--
-- *****

RequestedDataValueInformation ::= CHOICE {
    informationAvailable      InformationAvailable,
    informationNotAvailable   InformationNotAvailable
}

InformationAvailable ::= SEQUENCE {
    requestedDataValue      RequestedDataValue,
    iE-Extensions          ProtocolExtensionContainer { { InformationAvailable-ExtIEs} }
    OPTIONAL,
    ...
}

InformationAvailable-ExtIEs PCAP-PROTOCOL-EXTENSION ::= {
    ...
}

InformationNotAvailable ::= NULL

-- *****
--
-- Horizontal Accuracy Code
--
-- *****

HorizontalAccuracyCode ::= INTEGER (0..127)

-- *****

```

```
--
-- Vertical Accuracy Code
--
-- *****
VerticalAccuracyCode ::= INTEGER (0..127)
```

END

**/\* Partly omitted \*/**

## 9.3.6 Constant Definitions

```
-- *****
--
-- Constant definitions
--
-- *****

PCAP-Constants {
itu-t (0) identified-organization (4) etsi (0) mobileDomain (0)
umts-Access (20) modules (3) pcap(4) version1 (1) pcap-Constants (4) }

DEFINITIONS AUTOMATIC TAGS ::=

BEGIN

IMPORTS
    ProcedureCode,
    ProtocolIE-ID
FROM PCAP-CommonDataTypes;

-- *****
--
-- Elementary Procedures
--
-- *****

id-PositionCalculation          ProcedureCode ::= 1
id-InformationExchangeInitiation ProcedureCode ::= 2
id-InformationReporting         ProcedureCode ::= 3
id-InformationExchangeTermination ProcedureCode ::= 4
id-InformationExchangeFailure   ProcedureCode ::= 5
id-ErrorIndication             ProcedureCode ::= 6
id-privateMessage              ProcedureCode ::= 7

-- *****
--
-- Lists
--
-- *****

maxNrOfErrors          INTEGER ::= 256
maxSat                 INTEGER ::= 16
maxSatAlmanac         INTEGER ::= 32
maxNrOfLevels         INTEGER ::= 256
maxNrOfPoints         INTEGER ::= 15
maxNrOfExpInfo        INTEGER ::= 32
maxNrOfMeasNCell      INTEGER ::= 32
maxNrOfMeasurements   INTEGER ::= 16
maxNrOfSets           INTEGER ::= 3

-- *****
--
-- IEs
--
-- *****

id-Cause                ProtocolIE-ID ::= 1
id-CriticalityDiagnostics ProtocolIE-ID ::= 2
id-GPS-UTRAN-TRU       ProtocolIE-ID ::= 3
id-InformationExchangeID ProtocolIE-ID ::= 4
```

id-InformationExchangeObjectType-InfEx-Rprt	ProtocolIE-ID ::= 5
id-InformationExchangeObjectType-InfEx-Rqst	ProtocolIE-ID ::= 6
id-InformationExchangeObjectType-InfEx-Rsp	ProtocolIE-ID ::= 7
id-InformationReportCharacteristics	ProtocolIE-ID ::= 8
id-InformationType	ProtocolIE-ID ::= 9
id-GPS-MeasuredResultsList	ProtocolIE-ID ::= 10
id-MethodType	ProtocolIE-ID ::= 11
id-RefPosition-InfEx-Rqst	ProtocolIE-ID ::= 12
id-RefPosition-InfEx-Rsp	ProtocolIE-ID ::= 13
id-RefPosition-Inf-Rprt	ProtocolIE-ID ::= 14
id-RequestedDataValue	ProtocolIE-ID ::= 15
id-RequestedDataValueInformation	ProtocolIE-ID ::= 16
id-TransactionID	ProtocolIE-ID ::= 17
id-UE-PositionEstimate	ProtocolIE-ID ::= 18
id-CellId-MeasuredResultsSets	ProtocolIE-ID ::= 20
id-OTDOA-MeasurementGroup	ProtocolIE-ID ::= 22
<u>id-AccuracyFulfilmentIndicator</u>	<u>ProtocolIE-ID ::= 23</u>
<u>id-HorizontalAccuracyCode</u>	<u>ProtocolIE-ID ::= 24</u>
<u>id-VerticalAccuracyCode</u>	<u>ProtocolIE-ID ::= 25</u>

END