TSG-RAN Meeting #21 Frankfurt, Germany, 16 - 19 September 2003

RP-030522

Title: CR (R99) to TS 25.214

Source: QUALCOMM Europe, NOKIA

Agenda item: 7.2.2 & 7.2.3

TS 25.214 (RP-030513)

RP Tdoc #	WG Toc#	Spec	CR	R	Subject	Phase	Cat	Current
RP-030522	(R1-030894)	25.214	332	3	Uplink synchronization	R99	F	3.12.0
RP-030522		25.214	334	1	Uplink synchronization	R99	Α	4.6.0
RP-030522		25.214	335	1	Uplink synchronization	R99	Α	5.5.0

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5.1.2 DPCCH/DPDCH

5.1.2.1 General

The initial uplink DPCCH transmit power is set by higher layers. Subsequently the uplink transmit power control procedure simultaneously controls the power of a DPCCH and its corresponding DPDCHs (if present). The relative transmit power offset between DPCCH and DPDCHs is determined by the network and is computed according to subclause 5.1.2.5 using the gain factors signalled to the UE using higher layer signalling.

The operation of the inner power control loop, described in sub clause 5.1.2.2, adjusts the power of the DPCCH and DPDCHs by the same amount, provided there are no changes in gain factors. Additional adjustments to the power of the DPCCH associated with the use of compressed mode are described in sub clause 5.1.2.3.

Any change in the uplink DPCCH transmit power shall take place immediately before the start of the pilot field on the DPCCH. The change in DPCCH power with respect to its previous value is derived by the UE and is denoted by Δ_{DPCCH} (in dB). The previous value of DPCCH power shall be that used in the previous slot, except in the event of an interruption in transmission due to the use of compressed mode, when the previous value shall be that used in the last slot before the transmission gap.

During the operation of the uplink power control procedure the UE transmit power shall not exceed a maximum allowed value which is the lower out of the maximum output power of the terminal power class and a value which may be set by higher layer signalling.

Uplink power control shall be performed while the UE transmit power is below the maximum allowed output power.

The provisions for power control at the maximum allowed value and below the required minimum output power (as defined in [7]) are described in sub-clause 5.1.2.6.

5.1.2.2 Ordinary transmit power control

5.1.2.2.1 General

The uplink inner-loop power control adjusts the UE transmit power in order to keep the received uplink signal-to-interference ratio (SIR) at a given SIR target, SIR_{target}.

The serving cells (cells in the active set) should estimate signal-to-interference ratio SIR_{est} of the received uplink DPCH. The serving cells should then generate TPC commands and transmit the commands once per slot according to the following rule: if $SIR_{est} > SIR_{target}$ then the TPC command to transmit is "0", while if $SIR_{est} < SIR_{target}$ then the TPC command to transmit is "1".

Upon reception of one or more TPC commands in a slot, the UE shall derive a single TPC command, TPC_cmd, for each slot, combining multiple TPC commands if more than one is received in a slot. This is also valid when SSDT transmission is used in the downlink. Two algorithms shall be supported by the UE for deriving a TPC_cmd. Which of these two algorithms is used is determined by a UE-specific higher-layer parameter, "PowerControlAlgorithm", and is under the control of the UTRAN. If "PowerControlAlgorithm" indicates "algorithm1", then the layer 1 parameter PCA shall take the value 1 and if "PowerControlAlgorithm" indicates "algorithm2" then PCA shall take the value 2.

If PCA has the value 1, Algorithm 1, described in subclause 5.1.2.2.2, shall be used for processing TPC commands.

If PCA has the value 2, Algorithm 2, described in subclause 5.1.2.2.3, shall be used for processing TPC commands.

The step size Δ_{TPC} is a layer 1 parameter which is derived from the UE-specific higher-layer parameter "TPC-StepSize" which is under the control of the UTRAN. If "TPC-StepSize" has the value "dB1", then the layer 1 parameter Δ_{TPC} shall take the value 1 dB and if "TPC-StepSize" has the value "dB2", then Δ_{TPC} shall take the value 2 dB. The parameter "TPC-StepSize" only applies to Algorithm 1 as stated in [5]. For Algorithm 2 Δ_{TPC} shall always take the value 1 dB.

After deriving of the combined TPC command TPC_cmd using one of the two supported algorithms, the UE shall adjust the transmit power of the uplink DPCCH with a step of Δ_{DPCCH} (in dB) which is given by:

 $\Delta_{\text{DPCCH}} = \Delta_{\text{TPC}} \times \text{TPC_cmd}.$

5.1.2.2.1.1 Out of synchronisation handling

After 160 ms after physical channel establishment (defined in [5]), the UE shall control its transmitter according to a downlink DPCCH quality criterion as follows:

- The UE shall shut its transmitter off when the UE estimates the DPCCH quality over the last 160 ms period to be worse than a threshold Q_{out}. Q_{out} is defined implicitly by the relevant tests in [7].
- The UE can turn its transmitter on again when the UE estimates the DPCCH quality over the last 160 ms period to be better than a threshold Q_{in} . Q_{in} is defined implicitly by the relevant tests in [7]. When transmission is resumed, the power of the DPCCH shall be the same as when the UE transmitter was shut off.

5.1.2.2.1.2 TPC command generation on downlink during RL initialisation

When commanded by higher layers the TPC commands sent on a downlink radio link from Node Bs that have not yet achieved uplink synchronisation shall follow a pattern as follows:

If higher layers indicate by "First RLS indicator" that the radio link is part of the first radio link set sent to the UE and the value 'n' obtained from the parameter "DL TPC pattern 01 count" passed by higher layers is different from 0 then:

- the TPC pattern shall consist of n instances of the pair of TPC commands ("0","1"), followed by one instance of TPC command "1", where ("0","1") indicates the TPC commands to be transmitted in 2 consecutive slots,
- the TPC pattern continuously repeat but shall be forcibly re-started at the beginning of each frame where CFN mod 4 = 0.

else

- The TPC pattern shall consist only of TPC commands "1".

The TPC pattern shall terminate once uplink synchronisation is achieved.

Note: In case the Node B subsequently loses RL synchronisation, the Node B should not transmit the TPC command "0" until uplink synchronisation is achieved.

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