TSG RAN Meeting #19

RP-030038

Birmingham, United Kingdom, 11 - 14 March, 2003

Title CR (Rel-5) to TS 25.102

Source TSG RAN WG4

Agenda Item 8.4.5

RAN4 Tdoc	Spec	CR	R	Cat	Rel	Curr Ver	Title	Work Item
R4-020275	25.102	133	1	F	Rel-5	5.3.0	Transmit modulation quality clarification	TEI5

3GPP TSG RAN WG4 (Radio) Meeting #26

R4-030275

Madrid, Spain 17 - 22 February, 2003

CHANGE REQUEST											
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How to create CRs using this form:

Comprehensive information and tips about how to create CRs can be found at http://www.3gpp.org/specs/CR.htm. Below is a brief summary:

- 2) Obtain the latest version for the release of the specification to which the change is proposed. Use the MS Word "revision marks" feature (also known as "track changes") when making the changes. All 3GPP specifications can be downloaded from the 3GPP server under ftp://ftp.3gpp.org/specs/ For the latest version, look for the directory name with the latest date e.g. 2001-03 contains the specifications resulting from the March 2001 TSG meetings.
- 3) With "track changes" disabled, paste the entire CR form (use CTRL-A to select it) into the specification just in front of the clause containing the first piece of changed text. Delete those parts of the specification which are not relevant to the change request.

6.8 Transmit Modulation

<u>Transmit modulation defines the modulation quality for expected in-channel RF transmissions from the UE. The requirements apply to all transmissions.</u>

6.8.1 Transmit pulse shape filter

The transmit pulse-shaping filter is a root-raised cosine (RRC) with roll-off $\alpha = 0.22$ in the frequency domain. The impulse response of the chip impulse filter $RC_0(t)$ is

$$RC_0(t) = \frac{\sin\left(\pi \frac{t}{T_c} (1 - \alpha)\right) + 4\alpha \frac{t}{T_c} \cos\left(\pi \frac{t}{T_c} (1 + \alpha)\right)}{\pi \frac{t}{T_c} \left(1 - \left(4\alpha \frac{t}{T_c}\right)^2\right)}$$

Where the roll-off factor $\alpha = 0.22$ and T_c is the chip duration

6.8.2 Error Vector Magnitude

The Error Vector Magnitude is a measure of the difference between the reference waveform and the measured waveform. This difference is called the error vector. Both waveforms pass through a matched Root Raised Cosine filter with bandwidth corresponding to the considered chip rate and roll-off α =0,22. Both waveforms are then further modified by selecting the frequency, absolute phase, absolute amplitude and chip clock timing so as to minimise the error vector. The EVM result is defined as the square root of the ratio of the mean error vector power to the mean reference power expressed as a %. The period of measurement shall be one transmit timeslot excluding the guard period. The measurement interval is one timeslot. See Annex B of TS 34.122 for further details.

6.8.2.1 Minimum Requirement

The Error Vector Magnitude shall not exceed 17.5 % for the parameters specified in Table 6.9.

Table 6.9: Test parameters for Error Vector Magnitude/Peak Code Domain Error

Parameter	Unit	Level			
UE Output Power	DBm	≥-20			
Operating conditions		Normal conditions			
Power control step size	DB	1			

6.8.3 Peak Code Domain Error

This specification is applicable for multi-code transmission only.

The code domain error is computed by projecting the error vector power onto the code domain at a specific spreading factor. The error power for each code is defined as the ratio to the mean power of the reference waveform expressed in dB. And tThe Peak Code Domain Error is defined as the maximum value for Code Domain Error. The period of measurement shall be one transmit timeslot excluding the guard period, and the midamble. The measurement interval is one timeslot.

6.8.3.1 Minimum Requirement

The peak code domain error shall not exceed -21 dB at spreading factor 16 for the parameters specified in Table 6.9.

The requirements are defined using the UL reference measurement channel specified in subclause A.2.7.